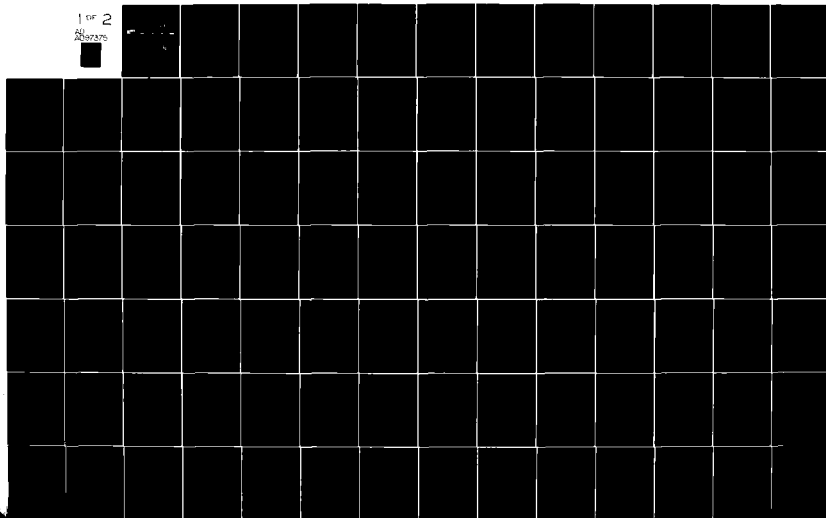


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A STUDY OF AVIONICS TIME DIVISION MULTIPLEX BUS SIMULATION.(U)
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**A STUDY OF
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MULTIPLEX BUS SIMULATION**

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By

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1. REPORT NUMBER AFOSR-TR- 81-0311	2. GOVT ACCESSION NO. <i>AD-AC 17 525</i>	3. RECIPIENT'S CATALOG NUMBER
4. TITLE (and Subtitle) A STUDY OF AVIONICS TIME DIVISION MULTIPLEX BUS SIMULATION		5. TYPE OF REPORT & PERIOD COVERED FINAL 1 Jan 1980 to 31 Dec 1980
		6. PERFORMING ORG. REPORT NUMBER
7. AUTHOR(s) MALCOLM D. CALHOUN and BEHROOZ KHATIRZAD		8. CONTRACT OR GRANT NUMBER(s) AFOSR-80-0126
9. PERFORMING ORGANIZATION NAME AND ADDRESS Mississippi State University Drawer EE Mississippi State, MS 39762		10. PROGRAM ELEMENT PROJECT, TASK AREA & WORK UNIT NUMBERS 2304/D9 <i>61102 F</i>
11. CONTROLLING OFFICE NAME AND ADDRESS Directorate of Mathematical and Information Sciences, Lt. Col. George W. McKemie, AFOSR/IM Bolling AFB, DC 20332		12. REPORT DATE <i>DEC. 1980</i>
14. MONITORING AGENCY NAME & ADDRESS (if different from Controlling Office)		13. NUMBER OF PAGES 156
		15. SECURITY CLASS. (of this report) Unclassified
		15a. DECLASSIFICATION/DOWNGRADING SCHEDULE
16. DISTRIBUTION STATEMENT (of this Report) Approved for public release; distribution unlimited.		
17. DISTRIBUTION STATEMENT (of the abstract entered in Block 20, if different from Report)		
19. KEY WORDS (Continue on reverse side if necessary and identify by block number) SIMULATION TIME DIVISION MULTIPLEXING MUXSIM AVIONICS DATA BUS		
20. ABSTRACT (Continue on reverse side if necessary and identify by block number) Utilization of AFAL's MUXSIM Simulation Program is made, linking MU'DA and MUXDB to GASP IV. Computer Simulations are made to compare FORTRAN, GASP IV, GPSS II, SIMSCRIPT II. ADA and ECSS II are considered as possible simulation tools.		

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Mississippi State University
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A STUDY OF AVIONICS TIME DIVISION
MULTIPLEX BUS SIMULATION.

For Period Covering
1 January 1980 to 31 December 1980

Final Report
AFOSR-80-0126

Principal Investigator
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TABLE OF CONTENTS

Chapter	Page
LIST OF FIGURES	vii
LIST OF TABLES	x
I. INTRODUCTION	1
II. SIMULATION LANGUAGE	4
General Views of SIMSCRIPT II	6
General Structure of Simulation	
Programming in SIMSCRIPT II	7
General Views of GASP IV	9
GASP Input Data Cards	12
Data Card Type I	12
Data Card Type II	16
Data Card Type III	16
Data Card Type IV	16
Data Card Type V	16
Data Card Type VI	17
Data Card Type VII	17
Data Card Type VIII	17
Data Card Type IX	17
Data Card Type X	18
Data Card Type XI	18
Data Card Type XII	18

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TABLE OF CONTENTS (Continued)

Chapter	Page
II. SIMULATION LANGUAGE (Continued)	
Data Card Type 0	19
General Views of GPSS II	20
Description of GPSS II Blocks	21
General Views of the ADA Language	28
Exceptional Situation in the ADA Language	30
General Views of ECSS II	31
III. GENERAL IDEAS OF MUXSIM	35
The Purpose of the MUXSIM System	38
Description of the MUXDA Program	39
Statement of the Problem	39
Simulation Objective	41
GASP IV Simulation Structure and Program Variables for MUXDA	41
Main Program	41
Subroutine INTLC	44
Subroutine FUIFRE (NF)	45
Subroutine ENDDM (NM)	45
Subroutine DMARIV (ND)	46
Subroutine NXTFUI (I, WHEN)	46
Subroutine NXTDM (I)	46
Simulation Report	47

TABLE OF CONTENTS (Continued)

Chapter	Page
III. GENERAL IDEAS OF MUXSIM (Continued)	
A Description of the MUXDB Program ...	77
Statement of the Problem	77
Simulation Objective	83
GASP IV Simulation Structure and Program Variable	84
Main Program	84
Subroutine INTLC	84
Subroutine EVNTS	84
Subroutine WATCH (IDUM)	85
Subroutine CTERM (ITRM)	85
Subroutine TERM (ITRM)	86
Subroutine NOISES (IN)	86
Subroutine NOISET (IN)	86
Subroutine TRMUP (ITN)	87
Subroutine TRMDN (ITN)	87
Subroutine FUI (IFUI)	87
Subroutine DMARIV (IDM)	88
Subroutine OPUT	88
Subroutine NXTMSG (IAM)	88
Subroutine STAT (ILBUS, IRBUS)	89
Simulation Report	90

TABLE OF CONTENTS (Continued)

Chapter	Page
IV. A SIMULATION EXAMPLE IN VARIOUS LANGUAGES	100
A Description of the FORTRAN Simulation	
Program	100
Subroutine ARRIVAL	104
Subroutine SERVICE	105
Subroutine DEPARTURE	106
GASP IV Simulation Program	109
A Description of the GASP IV Simulation	
Program	110
Main Program	110
Subroutine EVNTS	110
Subroutine ARR	112
Subroutine BEGS	112
Subroutine FINS	112
Simulation Report	112
GPSS II Simulation Program	116
A Description of the GPSS II Simulation	
Program	116
Simulation Report	118
SIMSCRIPT II Simulation Program	120
A Description of SIMSCRIPT II Simulation	
Program	120

TABLE OF CONTENTS (Continued)

Chapter	Page
IV. A SIMULATION EXAMPLE IN VARIOUS LANGUAGES (Continued)	
Simulation Report	122
V. SUMMARY AND CONCLUSION	124
APPENDIX - List of Programs and Subroutines	127
REFERENCES	155

LIST OF FIGURES

Figure	Page
1-1 Sample Multiplex Bus Architecture	3
2-1 General Layout for the Simulation of an Arrival and Departure	8
2-2 General Layout of the Main Program for GASP IV	10
2-3 Layout of Subroutine EVNTS	11
2-4 Functional Flow of GASP IV Program	13
2-5 Relation of GASP IV and User Subprograms	15
2-6 Schematic of ECSS Program Processing	33
3-1 MUXSIM System Data Flow Diagram	36
3-2 MUXSIM Modular Software Structure	37
3-3 Demand Message Multiplex System Schematic Representation	40
3-4 GASP IV Input Echo Check and User Input Data Incorporated in MUXDA	48
3-5 File Printout at Time 0 for MUXDA in First Run	49
3-6 Plot Output for MUXDA	60
3-7 Variation of Queue Length with Time in MUXDA (First Run)	61
3-8 Variation of the Percentage of Interval Time for Demand Message Transmission with Time in MUXDA (First Run)	62
3-9 Variation of Bus Idle Time with Time in MUXDA (First Run)	63

LIST OF FIGURES (Continued)

Figure	Page
3-10 File Printout at Time 0 for MUXDA in Second Run	64
3-11 Plot Output for MUXDA in Second Run	73
3-12 Variation of Queue Length with Time in MUXDA (Second Run)	74
3-13 Variation of the Percentage of Interval Time Available for Demand Message Transmission with Time in MUXDA (Second Run)	75
3-14 Variation of Bus Idle Time with Time in MUXDA (Second Run)	76
3-15 GASP IV Input Data Echo Check for MUXDB Simulation	92
3-16 User Input Data for GASP IV in MUXDB Simulation	93
3-17 User Detailed Input	94
3-18 Printout of Files at Time 0 for MUXDB	95
3-19 Output from Subroutine MONTR, showing Event Tracing for MUXDB	96
3-20 GASP Summary Report	97
3-21 Statistics Regarding the Use of Files for MUXDB	98
3-22 Histogram Output for MUXDB	99
4-1 Flow Chart of Single Queue, Single Server in the FORTRAN Program	102
4-2 Flow Chart of Subroutine ARRIVAL	104
4-3 Flow Chart of Subroutine SERVICE	105
4-4 Flow Chart of Subroutine DEPARTURE	106

LIST OF FIGURES (Continued)

Figure	Page
4-5 Printout of the FORTRAN Simulation Program	107
4-6 Flow Chart for GASP Single Queue, Single Server	111
4-7 Input Data Echo Check and Printout of Files at Time 0 for Single Bus Example	114
4-8 GASP IV Summary Report for Single Bus Example	115
4-9 Block Diagram for GPSS II Simulation Program	117
4-10 GPSS II Printout for Single Bus Example	119
4-11 Flow Chart for Event Arrival for Single Bus Example	128

LIST OF TABLES

Table	Page
2-1 GPSS II Standard Block Limits	27
3-1 Definition of GASP Files for MUXDA	42
3-2 Definition of Non-GASP Variables	43
3-3 Definition of GASP Files for MUXDB	78
3-4 Definition of Non-GASP Variables for MUXDB	79
5-1 Comparative Study of Various Simulations of Single Queue, Single Bus Problems	125

CHAPTER I

INTRODUCTION

Progress in digital technology has led to the development of shared information among electronic subsystems. For example, a number of digital processors may be interconnected via one common communication channel. Recent advances in microprocessors have made distributed processing a reality in many practical applications: manufacturing, computing, integrated avionics systems, etc. One technique for transferring information between several devices on one common channel is known as time division multiplexing; the channel over which the information is transferred is called a multiplex data bus. [1]

The multiplex system is a collection of electronic devices which send or receive signals for encoding and/or decoding; also, the system is capable of storing for future dispersal messages which arrive simultaneously. The components of the multiplex system are, (1) the bus controller, (2) remote terminals, (3) subsystems which may have embedded remote terminals, and (4) the data bus. See Figure 1-1. The data bus conveys information between the bus controller and the remote terminals (RT). The number of RT's on the data bus depends on the complexity of the desired system. The bus controller initiates information transfers on the data bus and is an integral part of the multiplex system. A subsystem is a functional unit which receives data transfer service from the data bus. Frequently it is necessary to have more than one data bus; a data bus which has more than one path between the subsystems is called a redundant data bus. Figure 1-1 illustrates a

redundant data bus architecture.

Discrete event simulation is a viable means of modeling digital multiplex systems. Questions concerning data bus utilization and/or bus traffic loading should be answered prior to the hardware development of the system. A simulation model may be used in the preliminary design and accuracy testing of a digital multiplex system. One such simulation model which has been developed for this purpose is the Multiplex System Simulator (MUXSIM) [2]. In building the model for MUXSIM, FORTRAN IV and the GASP IV simulation languages were used; however, other simulation languages such as GPSS II or SIMSCRIPT II may be used. In selecting the simulation language to use in modeling a multiplex system, care should be taken that the simulation language matches the host computer system.

An overview of several current simulation languages is presented in Chapter II. In Chapter III, the general views of MUXSIM and the analysis of the dynamic part of the MUXSIM system are described in detail. The purpose of the dynamic MUXSIM (MUXDA and MUXDB) is to model the time-variant or stochastic aspects of the system and to obtain the simulation results on such system parameters as queue size, time delay, system failure, etc. In Chapter IV, a programming example of a single queue, single bus is presented in FORTRAN IV, and three different simulation languages, (GASP IV, SIMSCRIPT II, and GPSS II). Chapter V is a comparative study of the simulation languages based on the results of Chapter IV. Recommendations regarding the choice of a language for multiplex simulation are included.

All programs and modified programs which are used in this report are included in the Appendix. Numbers enclosed in brackets [] refer to the reference list at the end of the report.

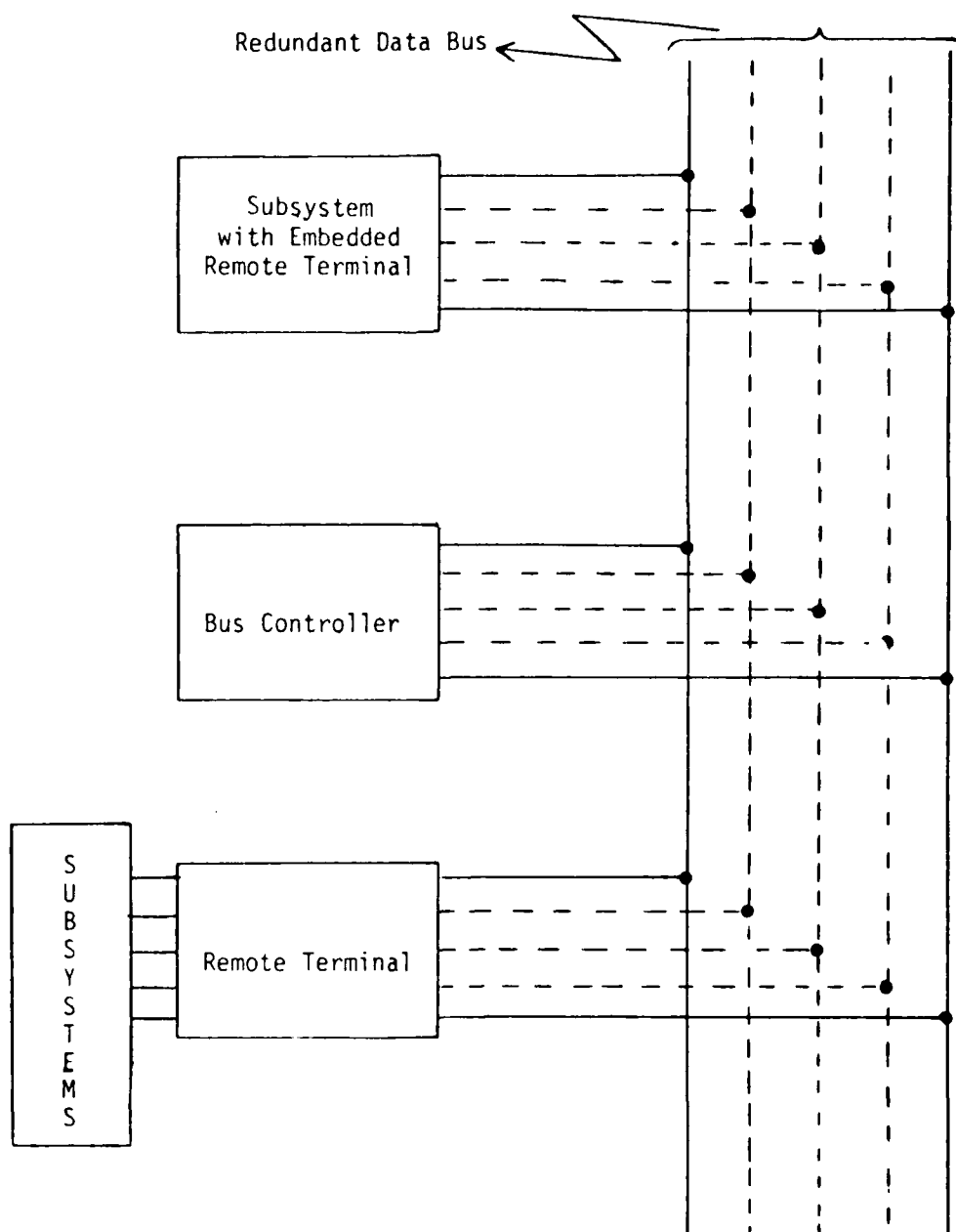


Figure 1-1 Sample Multiplex Bus Architecture.

CHAPTER II

SIMULATION LANGUAGE

Simulation is a good approach to analysis in the design and operation of a complex system. It is necessary for the modern engineer to be familiar with the techniques of simulation.

Large scale system modeling, using simulation is very dependent on the digital computer; therefore, one who is interested in simulation modeling should have a basic knowledge of computer science. In this project, it is necessary to know FORTRAN IV as a requirement for learning and working with the GASP IV simulation language.

The definition of simulation: Simulation is the process of designing a model of a real system and conducting experiments with this model for the purpose of either understanding the behavior of the system or evaluating various strategies (within the limits imposed by criterion or set of criteria) for the operation of the system [3].

In simulation modeling, the engineer seeks to describe a system and its behavior. For this purpose, theories or hypothesis must be constructed. These theories are used to predict future events.

The greatest advantage of simulation is its powerful education and training application, because the development and use of simulation allows a means to find the problems which may happen in the real world; this, in turn, helps in understanding and learning how to handle the difficulties or problems. It should be pointed out that the development of a good simulation model may require a lot of time and expense.

In addition, simulation modeling is a type of art work, and therefore requires a talented engineer. Furthermore, the complexity of the system may be such that it is not amenable to simulation. Thus, it is possible that the results of a simulation do not always fit in the real world. Another reason for the difference between simulation results and real world is that we cannot create all the conditions in our simulation model; therefore, when possible, the results of a simulation should be compared with the direct experiment in the real life systems. If there is too much difference in the results, the model should be modified to overcome many difficulties in obtaining a good match between the model and actual conditions.

Is it always possible to perform a direct experiment? The answer is not always yes, because the direct experiment may be too costly and time consuming, or it may be too difficult to maintain the same condition for each run of the experiment. Also, it may not be possible to create many types of alternatives in the real life. Furthermore, the simulation result is numerical. These numbers may be truncated several times during the simulation process itself; therefore, there is always danger of obtaining an incorrect result or a slightly different result from the real world.

GENERAL VIEWS OF SIMSCRIPT II

SIMSCRIPT II is a very impressive and flexible computer programming language. It can be used for general programming problems [4] [5]. SIMSCRIPT II is divided into five language levels, which are as follows:

1. Level One or Elementary User's Language

This is designed to introduce programming concepts if one is not familiar with computer programming. This level is a simple teaching language.

2. Level Two or Level of FORTRAN

This is almost like the FORTRAN language, but is different in specific features. For example, all variables are not real unless otherwise defined; SQRT (square root) and other FORTRAN functions are not allowed to be used as variable names.

3. Level Three or Level of PL/I or ALGOL

This level is almost comparable to PL/I or ALGOL, but as in level two, they have many differences.

4. Level Four or Entity-Attribute-Set-Level

This level contains the entity-attribute-set of this language. The simulation program in this level should have a preamble, and every statement which appears in the preamble should define the existence of a class of entities. An entity can belong to other entities, have sets of other entities, and may have attributes.

5. Level Five or Simulation-Oriented Feature

Levels one through four present a general programming language, but level five is different, in that it provides concepts and programming

features for discrete-event simulation. Discrete-event simulation handles models whose entities interact with one another at discrete times, instead of continuously. This level deals with concepts and statements made to help in modeling systems.

General Structure of Simulation Programming in SIMSCRIPT II

Every EVENT must be defined in the preamble, scheduled by the modeler, and must be supported by an event routine. For example, for simulation of an arrival and departure, one should define arrival and departure in the preamble. In the main program, the arrival should be scheduled and after it, an event arrival must be written. A schedule of departures should be in the event arrival and departures should be supported by an event departure. Figure 2-1 illustrates the general layout of the above example.

PREAMBLE

EVENT NOTICES INCLUDE ARRIVAL AND DEPARTURE

END

MAIN

SCHEDULE AN ARRIVAL

.
. .
. .
. .

EVENT ARRIVAL

.
. .
. .
. .

SCHEDULE A DEPARTURE

.
. .
. .
. .

RETURN

END

EVENT DEPARTURE

.
. .
. .
. .

RETURN

END

Figure 2-1 General Layout for the Simulation of an Arrival and Departure.

GENERAL VIEWS OF GASP IV

GASP IV was developed by Dr. A. Alan B. Pritsker at Purdue University and is based on GASP II, which was developed at Arizona State University, which in turn was based on the original GASP developed at U. S. Steel by Mr. Phillip J. Kiviat. [6]

GASP is an acronym for General Activity Simulation program. GASP IV is a specialized language for constructing simulation models of computer systems. It is a powerful and a well-documented simulation language. GASP IV is a FORTRAN based simulation language and does not require a separate compiling system. It is easy to maintain on any machine which has a FORTRAN IV compiler. This simulation language is used for discrete, continuous, and combined discrete/continuous modeling and is the only simulation language with this capability. It is easy to modify and extend to meet the needs of particular applications. GASP IV has the capabilities for event control, to update system variables, to initialize the state of system, and to collect the statistical value.

A simulation program written in GASP IV is divided into two parts, a user part and a GASP IV part. The user part consists of the main program and subroutine. In the main program, all non-GASP variables that remain constant for all simulation runs should be initialized. Some of the most used GASP subroutines are described below: Subroutine GASP is called via the main program. The general layout of the main program is shown in Figure 2-2. Subroutine INTCL is used to initialize non-GASP variables at the start of each run.

```
C MAIN PROGRAM
  DIMENSION NSET (NNSET)
C NNSET to be specified
  COMMON (GASP VARIABLES)
  COMMON (NON-GASP VARIABLES)
  EQUIVALENCE (NSET (1), QSET (1))
C Initialization of non-GASP variables
C Initialization of Card Reader Value, NCRDR and Printer Value,
C NPRNT.
  CALL GASP
C If more runs are desired, insert GO TO statement to either
C reinitialize non-GASP variables or to CALL GASP again.
  STOP
  END
```

Figure 2-2 The General Layout of the Main Program for GASP IV.

The user written subroutine EVNTS (IX) is called to pick up the event code IX and to call the appropriate event code. The general form event code is given in Figure 2-3.

```
SUBROUTINE EVNTS (IX)
  DIMENSION NSET (1)
  COMMON QSET (1)
  COMMON (GASP VARIABLES)
  COMMON (NON-GASP VARIABLES)
  EQUIVALENCE (NSET (1), QSET (1))
  C  For Single Queue and Single Server
  C  Simulation program which is written in this thesis
  C  IX has been specified as follows:
  C  If IX is 20, Event Arrival will occur.
  C  If IX is 30, Event Begin Service will occur.
  C  If IX is 40, Event Finish Service will occur.
  GO TO (20, 30, 40), IX
20  CALL ARR
    RETURN
30  CALL BEGS
    RETURN
40  CALL FINS
    RETURN
END
```

Figure 2-3 Layout of Subroutine EVNTS.

Subroutine OTPUT produces some information in addition to the standard GASP summary report. It can be used as an end of simulation event.

The GASP part of the simulation program consists of the subprogram that prepares for the following functions: data collection, statistics computation and reporting, monitoring and error reporting, random deviate generation, data storage and retrieval data, and event initialization and mode controller. Figure 2-4 shows the flow chart of the GASP program.

Figure 2-5 presents a diagram showing the relationship of the GASP IV subprograms and the user written subprograms. The lines in Figure 2-5 represent one subprogram calling another. Each of the user written subprograms can call any of the GASP IV subprograms. Lines indicating such calls are problem specific and are not shown in the figure. Subprogram names, having both a solid box and a dashed box around them, are usually written by the user. GASP IV gives a "dummy" version if no user version is written.

GASP Input Data Cards

The GASP program has standard input data cards besides the user input cards. The user input data card is placed before or after, or both before and after the GASP input data card, depending on the type of program.

There are twelve types of input data cards as described below:

Data Card Type I

Data card type I is used for recording the name of the programmer, the number of the project, the date and number of the simulation run.

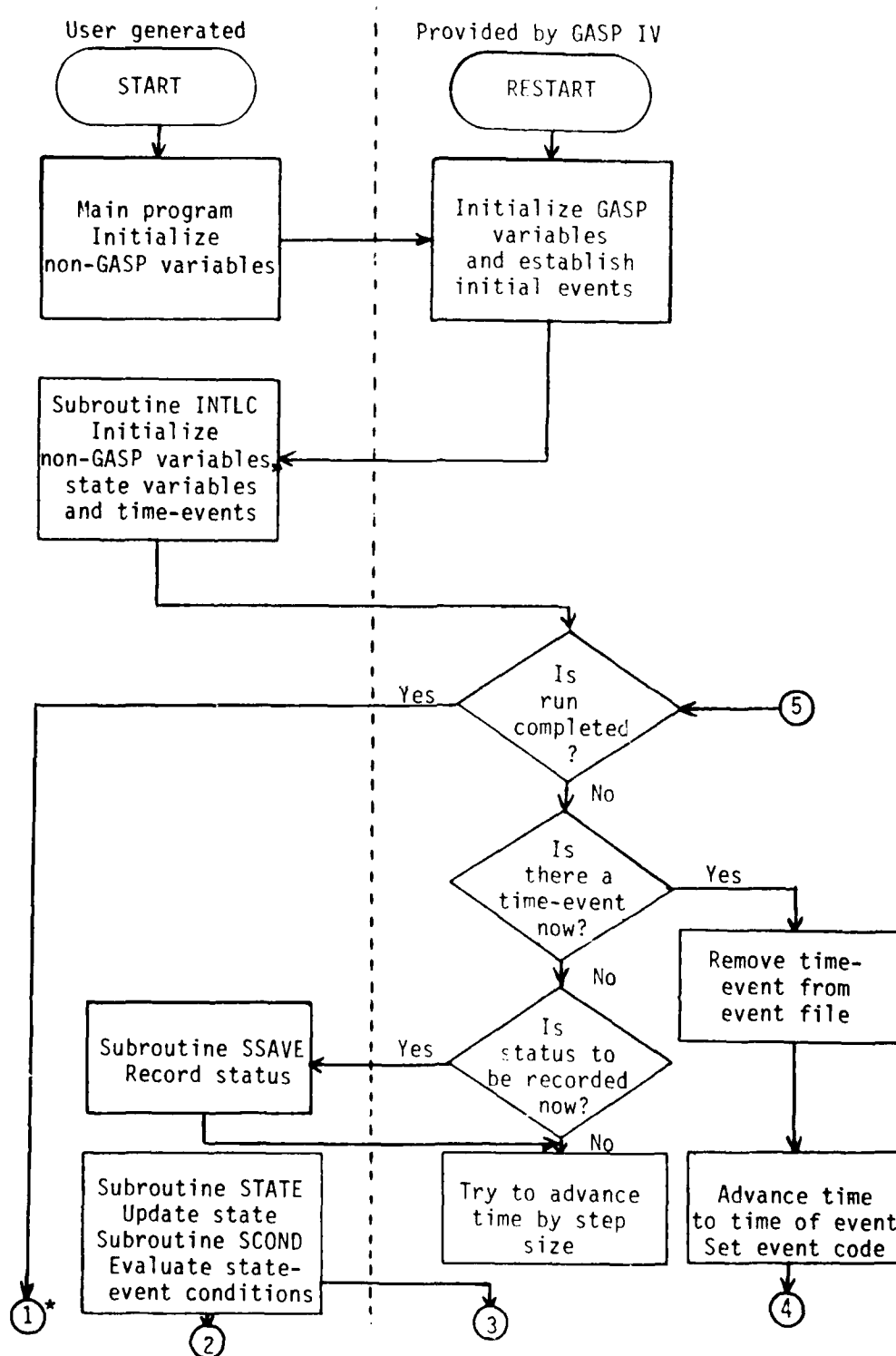


Figure 2-4 Functional Flow Chart of a GASP IV Program,

* Numbered circles refer to destination points in the program.

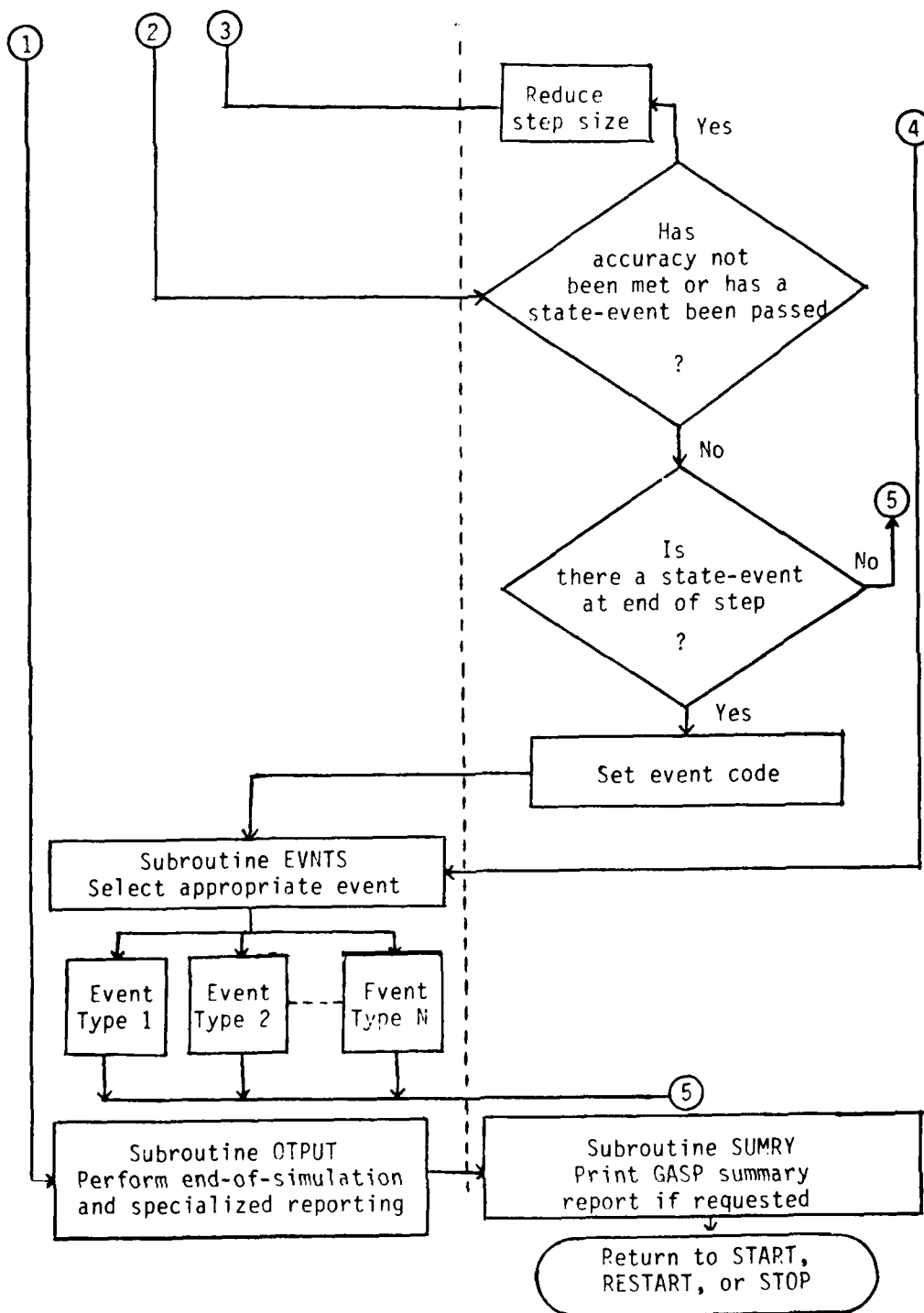


Figure 2-4 Functional Flow Chart of a GASP IV Program (Continued)

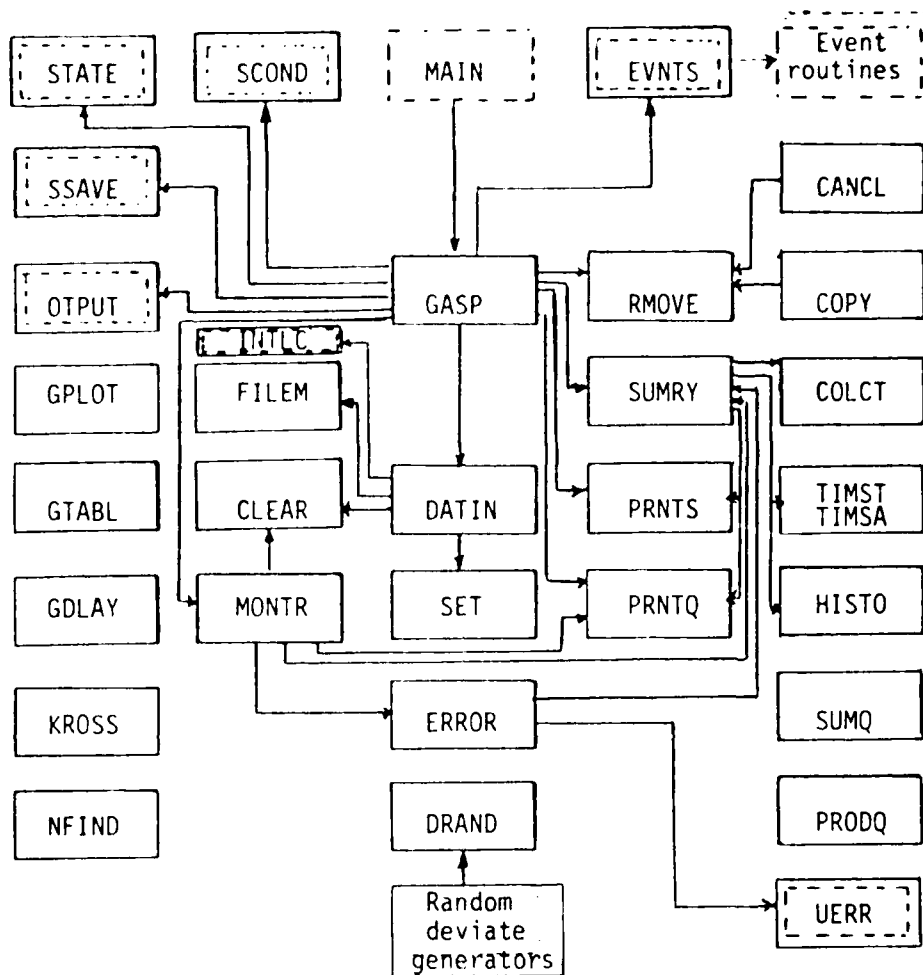


Figure 2-5 Relation of GASP IV and user subprograms. [6]

The format is (3A4, 3X, 5I5, 15I1) for type I data cards.

Data Card Type II

Data card type II is used if the control variable (LLSUP (2)) is less than one. It consists of information about subroutine COLCT, TIMST, and TIMSA, number of histograms, number of parameter sets, number of plots or tables, number of random streams, maximum allowable number of entries in the file storage area (NSET/QSET), maximum number of attributes per entry in NSET/QSET, number of files in NSET/QSET, dimension of NSET/QSET, number of derivative equations, number of equations defining in state level and number of state condition flags (LFLAG) employed. The format is (15I5).

Data Card Type III

Input card type III is used only if the number of sets of statistics collected by subprogram COLCT (NMCLT) is greater than zero and the control variable (LLSUP (3)) is less than one. The format of this card is (5X, I5, 2A4) and it contains labels associated with variables used in COLCT.

Data Card Type IV

Input data card type IV is used only if the number of sets of statistics collected by subprograms TIMST and TIMSA is greater than zero and the control variable (LLSUP (4)) is less than one. The format of this card is (5X, I5, 2A4, E10.0) and it consists of a label for TIMST, TIMSA and the initial value for the time persistent variable.

Data Card Type V

This input data card is used only if the number of histograms (NNHIS) is greater than zero and the control variable (LLSUP (5))

is less than one. The format of this type of card is (5X, I5, 2A4, 7X, I5, 2E10.0). It consists of a label of histogram, number of cells of each histogram, upper limit of the first cell of the histogram, and the width of a cell for histogram.

Data Card Type VI

Data input card type VI is divided into two types, Type A and Type B.

Type A is used only if the number of plots and/or tables (NNPLT) is greater than zero and the control variable (LLSUP (6)) is less than one. The format used is (5X, I5, 2A4, 7X, 3I5, E10.0). This card gives information about the label of plot, index of tape, number of variables for the table or plot, keys for specifying the type of table or plot, and intervals between successive plot points.

Type B is used only if IJ (Index) is less than the number of variables to be plotted or tabled. The format used is (5X, I5, A1, 2A4, 1X, 2I5, 2E10.0). This card gives plot symbols, labels for plots, keys for specifying lower and upper limits and values associated with lower and upper limits of plot ordinates.

Data Card Type VII

This type of card is used only if the number of files in the file storage area (NSET) is greater than zero and the control variable (LLSUP (7)) is less than one. The format is (14I5). This card gives information about ranking attributes for files.

Data Card Type VIII

This type of card is used only if the number of files (MNFIL) in the file storage area (NSET) is greater than zero and the control variable (LLSUP (8)) is less than one. The format of this card is

(1415). This card consists of keys for priority systems to be used in the files.

Data Card Type IX

This type of card is used only if the number of state and derivative equations (NNEQT) is greater than zero and the control variable (LLSUP (9)) is less than one. The format of this card is (2I5, 5E10.0). This card has information about accuracy, minimum and maximum step size permitted, and keys between communication points.

Data Card Type X

This type of card is used only if the number of parameter sets (NNPRM) is greater than zero and the control variable (LLSUP (10)) is less than one. The format of this card is (5X, I5, 4E10.0). This data card has information about parameter set numbers and parameter numbers.

Data Card Type XI

Data card type XI is used only if the control variable (LLSUP (11)) is less than one. The format of this card is (4I5, 2E10.0, I5, (6I5)). This data card yields information about stopping the simulation, whether statistical array should be cleared during initialization, and the initialization of the random number seed.

Data Card Type XII

This type of card is used only if the number of files in NSET (NNFIL) is greater than zero and the control variable (LLSUP (12))

is less than one. The format is (5X, I5, (6E10.0)). This data card gives information about the file number for attributes. If this number is equal to zero, it shows the end of data card type XII.

Data Card Type 0

Data card type 0 is used only if the remaining number of runs (NNRNS) is greater than one and the indicator used in DATIN for initialization (IICRD) is equal to zero. The format of this card is (15I1, I5). This card is used for multiple runs and it has a different value for different programs.

GENERAL VIEWS OF GPSS II [7]

GPSS II is an acronym of General Purpose Systems Simulator II. This program language is one of the easiest simulation languages. It is not as flexible as GASP IV or other advanced simulation languages, because of a limitation on the number of blocks, storage areas, and transaction in systems.

In order for a system to be simulated, it must be reducible to a series of operations performed on units of traffic. The units of traffic upon which the system operates relies on the nature of the system. Traffic may be work items in a production line, electrical pulses in a digital circuit, or messages in a communications system. Transactions are the units of traffic that are made and used by the simulator. These transactions have certain properties which conform to characteristics of traffic in a system. Each transaction is associated with a priority, which is one integer between zero and seven. When competing for service, the transaction with the numerically higher priority will be the first to be processed. If transactions have the same priority, the one that has been delayed longer will be selected first.

The program supplies block types, which present operations in a model of the system equivalent to the actions happening in the real system. Each block specifies a number of clock units that the transactions are to spend in that block. The number may be made to depend upon a number of factors within the system itself, or it may be constant or computed from statistical distribution. Every block specifies the next step to which a transaction will be sent when its computed

time interval is completed.

The user gives each block an identifying number to designate the path of flow. The fundamental properties of some of these block types are described and all the operations which may be performed are discussed. Before the properties of these blocks can be discussed, it is necessary to specify the format of the block types.

The card fields of the GPSS II blocks are as follows:

<u>Field</u>	<u>Columns</u>
LOCATION	2-6
NAME	7-18
X	19-24
Y	25-30
Z	31-36
SELECTION MODE	37-42
NEXT BLOCK A	43-48
NEXT BLOCK B	49-54
MEAN TIME	55-60
MODIFIER	61-66
COMMENTS	67-80

In these fields, all numbers should be left justified.

Description of GPSS II Blocks

ADVANCE

Purpose: In this block, transaction waits while the clock advances.

Operand: This block has no operand.

Condition for entry acceptance: It does not refuse entry under any

condition.

ASSIGN

Purpose: This block modifies the value of the parameter.

Operand: X field gives the parameter numbers. Y field specifies system variables.

Condition for entry acceptance: It never refuses entry.

ASSEMBLY

Purpose: This block is used to terminate the number of assembly sets (assembly sets are original and duplicated blocks).

Operand: X field specifies the assembly count, which must be at least two.

Condition for entry acceptance: It always accepts entry.

COMPARE

Purpose: This block tests the relationship between two system variables.

Operand: X field gives the system variable that is going to be tested. Y field is specified by Mnemonics (kind of relationship).

Z field gives the system variable that is going to be tested.

Condition for entry acceptance: It refuses entry whenever the relationship is false.

ENTER

Purpose: This block places one or more units into storage.

Operand: X field specifies the storage number. Y field specifies the number of units to be stored.

Condition for entry acceptance: It never refuses entry.

GENERATE

Purpose: The GENERATE block creates transaction.

Operand: X field gives the time of the first transaction. Y field specifies the limit count. Z field gives the priority of a central transaction. Mean time should be given for the interval between the creation of two transactions. The modifier can be specified two ways, first, by a constant value which gives a uniform random variable. Second, by a function which gives the form of distribution.

Condition for entry acceptance: It never accepts entry.

GATE

Purpose: This block tests the status of some entities.

Operand: X field is given by Mnemonic, followed by a number (facility number).

Condition for entry acceptance: It refuses entry whenever indicated status is false.

INDEX

Purpose: The INDEX block is used to compute a transaction parameter value for temporary use. A constant is added to the specified parameter and stores the result in Parameter 1.

Operand: X field gives a parameter number. Y field gives the constant value.

Condition for entry acceptance: It never refuses entry.

LOGIC *

Purpose: This block changes the status of the LOGIC switch.

Operand: X field is specified by S(set) or R(reset), plus number.

Condition for entry acceptance: It never refuses entry.

* Initially LOGIC switches are reset (0).

LEAVE

Purpose: The LEAVE block takes a unit out of storage.

Operand: X field specifies the storage number. Y field gives the number of units to be taken out.

Condition for entry acceptance: It never refuses entry.

LOOP

Purpose: This block causes a transaction to cycle through a set of blocks several times.

Operand: X field gives a parameter number.

Condition for entry acceptance: It never refuses entry.

MARK

Purpose: This block marks the transaction with the current clock time.

Operand: X field is either blank or contains a parameter number. When using a parameter number, the parameter number should be marked.

Condition for entry acceptance: It never refuses entry.

MATCH

Purpose: The MATCH block is used to synchronize the movement of the assembly set.

Operand: X field specifies the block number of a MATCH block.

Condition for entry acceptance: It always accepts entry.

PREEMPT

Purpose: This block attempts the higher level usage of facility.

Operand: X field gives the facility number.

Condition for entry acceptance: It refuses entry if the facility has already been preempted.

PRIORITY

Purpose: This block is used to set PRIORITY of entry transactions.

Operand: X field is used to specify the value of PRIORITY. Y field is either blank or buffer.

Condition for entry acceptance: It never refuses entry.

PRINT

Purpose: This block is used to print out some expected value.

Operand: X field specifies the first location of SAVEX to be printed. Y field specifies the last location of SAVEX to be printed.

Condition for entry acceptance: It never refuses entry.

QUEUE

Purpose: It records one or more entries into a Queue.

Operand: X field gives the QUEUE number. Y field specifies the number to be added into QUEUE.

Condition for entry acceptance: It never refuses entry.

RELEASE

Purpose: The RELEASE block is used to end service on facility.

Operand: X field specifies the number of facility.

Condition for entry acceptance: It always refuses entry.

RETURN

Purpose: This block is used to end the preemption.

Operand: X field gives the facility number.

Condition for entry acceptance: It never refuses entry.

SAVEX

Purpose: This block allows the user to gather and print information from the block diagram, and transmit information from one transaction to another.

Operand: X field of this block specifies a SAVEX storage location.

Y field gives the system variable to be used in the modification.

Condition for entry acceptance: It always accepts entry.

SEIZE

Purpose: The SEIZE block begins service on a facility.

Operand : X field specifies the number of facility.

Condition for entry acceptance: It refuses entry if it has already seized.

SPLIT

Purpose: This block creates a duplication of each transaction that enters the block.

Operand: There is no operand.

Condition for entry acceptance: It always accepts entry.

TABULATE

Purpose: This block gives statistics on the simulation program.

Operand: X field specifies the number of TABULATE blocks.

Condition for entry acceptance: It always accepts entry.

TERMINATE

Purpose: The TERMINATE block removes transactions from the block diagram.

Operand: X field should be left blank or specified by the letter R.

If R is used in the X field, the termination counter would be reduced by one.

Condition for entry acceptance: It does not refuse entry under any condition.

The standard upper limits of blocks, storage, etc. are given for GPSS II in Table 2-1:

<u>Item</u>	<u>Std. Max.</u>	<u>Words/Item</u>
Blocks	800	5
Facilities	200	6
Storage	200	7
Queues	200	6
Logic Switches	500	1
Savex Locations	500	1
Functions	100	4
Tables and QTABLES	100	10
Variable Statements	50	1
Transactions in System	1000	9

Table 2-1 GPSS II Standard Block Limits.

GENERAL VIEWS OF THE ADA LANGUAGE

The ADA language was designed by a team led by Jean D. Ichbiah. It has been chosen as the name for the common language, honoring Ada Augusta, the daughter of the poet, Lord Byron, and Babbage's programmer [8].

The ADA language was designed with three concerns in mind: a recognition of the importance of program dependability and maintenance, a concern for programming as a human activity, and efficiency.

The ADA language is a modern algorithmic language which contains the usual control structures, and is able to define types* and subprograms. ADA is also capable of serving the need for modularity, whereby data, types, and subprograms can be packaged. Any program in the ADA language is a series of higher level program units, with the capability of compiling separately.

The program units can be a subprogram which is an executable algorithm. Package modules are collections of entities or task modules which are concurrent calculations. The subprogram, package modules, and task modules are described in more detail as follows:

Subprogram

A subprogram is an executable unit which is the basic unit for expressing an algorithm. A subprogram can have parameters, which

* A type characterizes a set of values and a set of operations that apply to those values.

show its connections to other program units. There are two kinds of subprograms in the ADA language: (1) procedures and (2) functions. These are described below:

(1) Procedure Subprogram

A procedure subprogram is the logical equivalent to a series of actions. For example, it may read in data, update variables, or produce some output.

(2) Function Subprogram

A function subprogram is the logical equivalent to a mathematical function for computing a value.

Package Modules

A package module is composed of fundamental units to define a collection of logically related entities.

Task Modules

A task module is almost like a package module, but with more capability for parallel processing. A task can be carried out on multiple processors or with interleaved execution on a single processor, the same as procedure entries can have a parameter showing the transmission of data between tasks.

Each program unit usually consists of two parts:

- (1) a declarative part and (2) a sequence of statements.

These are described as follows:

(1) A declarative part defines the logical entities to be used in the program unit and associates names with declared entities. A name can be a variable, a constant, or a type.

(2) A sequence of statements defines the execution of the

program unit. A statement describes the type of action to be taken. An assignment statement indicates that the current value of a variable should be replaced by a new value.

Exceptional Situation in the ADA Language

In the ADA language, sometimes the computer reaches the point where normal program execution can not continue. For example, it may be needed to access the value of an uninitialized variable. To overcome this situation, the statements of a program unit can be textually followed by an exception handler describing the action to be taken if an exceptional situation arises.

GENERAL VIEWS OF ECSS II [9]

ECSS II, or Extendable Computer System Simulator II, is called "ex-two". This program language has been constructed for simulation models of a computer-based system; it is an extension of the general purpose simulation language SIMSCRIPT II, and that language is implied as a subset. It gives a wide selection of statements and data structures for describing common computer hardware structures, software operations, and work load characteristics in a natural and straight forward notation. In general, the ECSS II program includes a preamble, a system description section, a work load description, automatic event routines, and SIMSCRIPT routines. These characteristics are described below:

(1) Preamble

The preamble statement is used only if defining new global variables, functions, and entities.

(2) System Description Section

The section which describes the system of an ECSS II program defines the simulated resources in an ECSS II model. Declarative statements in this part give the name and number of every device, specify device characteristics and capabilities, show how devices are interconnected, and describe paths through which simulated data may pass.

(3) Work Load Description Section

This part of the ECSS II program defines routines which are called processes and may be used to characterize the load on a computer system's resources. The load is determined by the

environment and behavior of the program that comes to be executed as a result of environmental demands.

(4) Automatic Event Routines

This section of the program is generally used for simulation monitoring and control and for representing actions that happen outside the model itself.

(5) SIMSCRIPT II Routines

SIMSCRIPT II routines, formed by a translator, consists of the initialization routine, the translation of automatic event routines, the translation of process routines, and process routines.

Processing

Producing an executable ECSS program is a three-step procedure: translation, compilation, and editing. This is illustrated in Figure 2-6.

Simulation Reports

ECSS produces three types of outputs: system display output, statistical output, and tracing output. These are described as follows:

System Display

This report is created by the SHOW SYSTEM statement. It produces the name of each device group and specifies whether it is a device or a class, and shows characteristics of the device groups and the state of model at any point during simulation.

Statistics

ECSS II can provide statistics on model performance at any particular interval. ECSS II automatically collects data on the

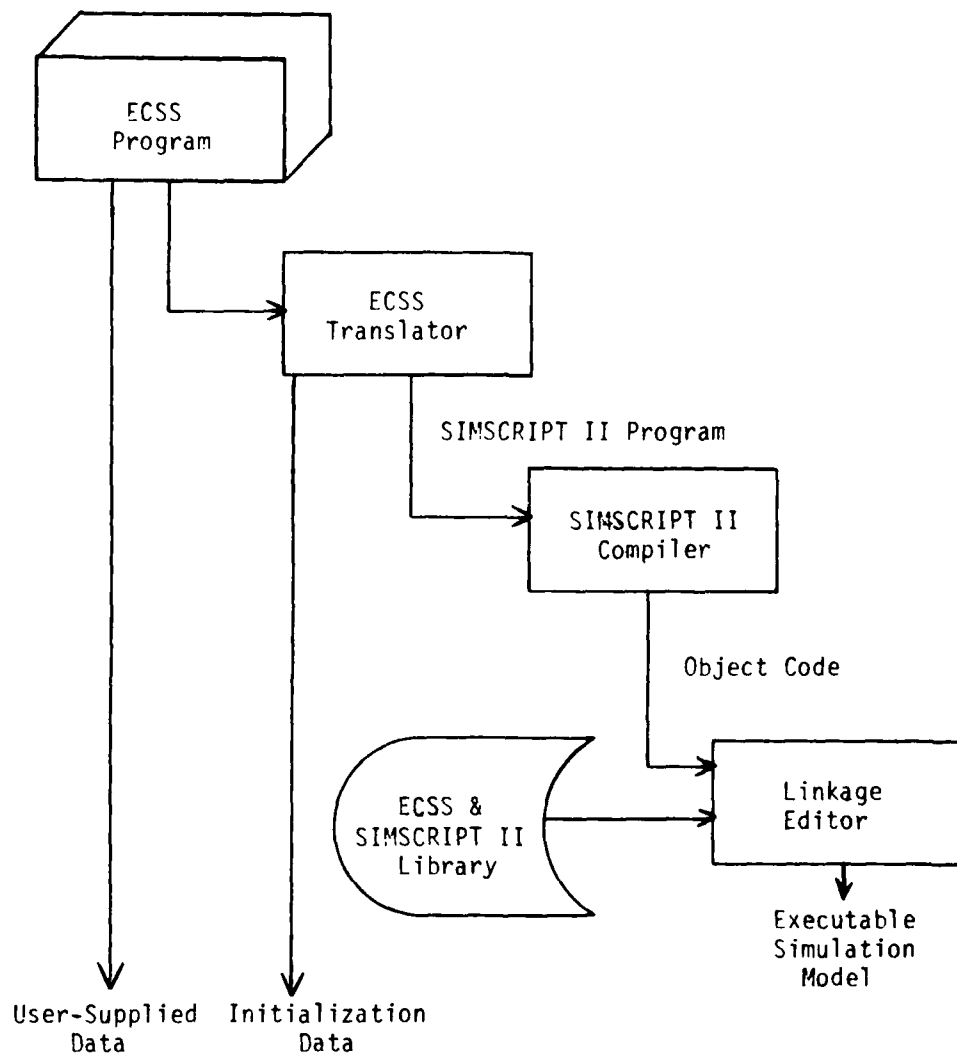


Figure 2-6 Schematic of ECSS Program Processing. [9]

activity of each device and contents of queues and is produced by the SHOW STATISTICS statement.

Tracing

This part of output gives details about interactions within a computer system and traces each step of the simulation model.

CHAPTER III

GENERAL IDEAS OF MUXSIM

MUXSIM is the abbreviation for Multiplex Simulation [2] [10] [11]. It consists of four major subsystems: the utility, the static, the dynamic, and the executive. These subsystems are then divided into programs, subprograms, and subroutines or modules. Most of these are written in FORTRAN and some are in GASP. The executive uses the TOPS-10 control statement. Figure 3-1 illustrates the MUXSIM System Data Flow Chart.

The four major parts of MUXSIM are described as follows:

(1) Utility Subsystem

The utility subsystem is a module of MUXSIM which manages the signal flow list, withdrawing the simulator inputs from it. This subsystem is also the management system for MUXSIM. In checking the Equipment Complement for completeness, signal deficiencies, and flagging any equipment, the utility subsystem uses the information from the signal flow list.

(2) Static Subsystem

The static subsystem deals with all the signal information, grouping, and handling, such as remote terminal assignments, word maps, message maps, as well as fixed format bus loading and utilization computation.

(3) Dynamic Subsystem

The dynamic subsystem, consisting of two discrete-event modules, handles the random messages, scheduling tasks, and computes the dynamic bus loading and time statistics. It is called "dynamic" because

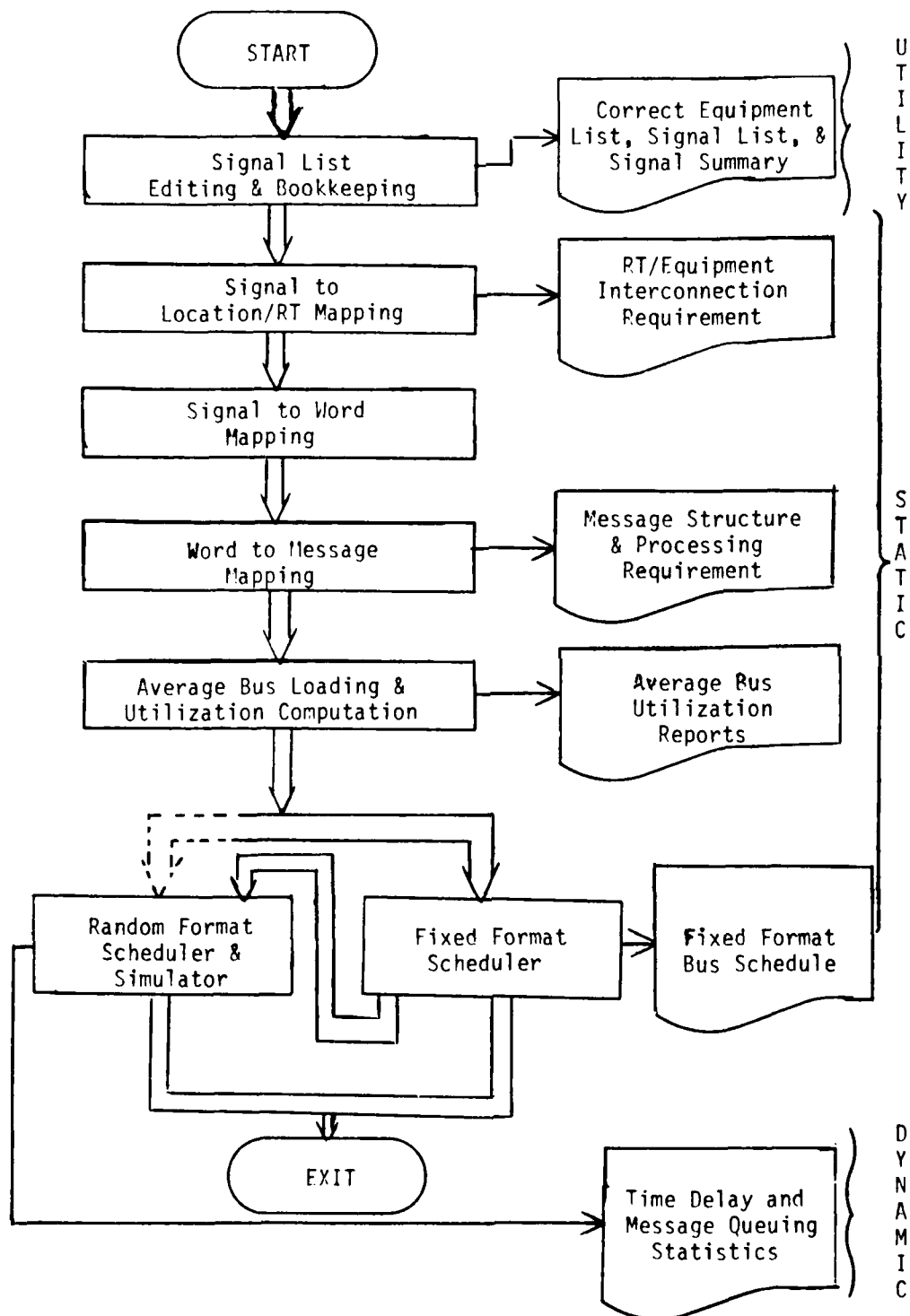


Figure 3-1 MUXSIM System Data Flow Diagram.

stochastic events characterizing such phenomena as multiplex system failure, bus noise, and time variable data transfer requirements are considered. This system uses the simulation language GASP IV as a component.

(4) Executive Subsystem

The executive subsystem supplies the interface between the user and the other three subsystems: the utility, the static, and the dynamic. It has an interactive section with optional coaching to assist the user and to make learning the simulator operation easier. Figure 3-2 shows the MUXSIM Modular Software Structure and their relation to one another.

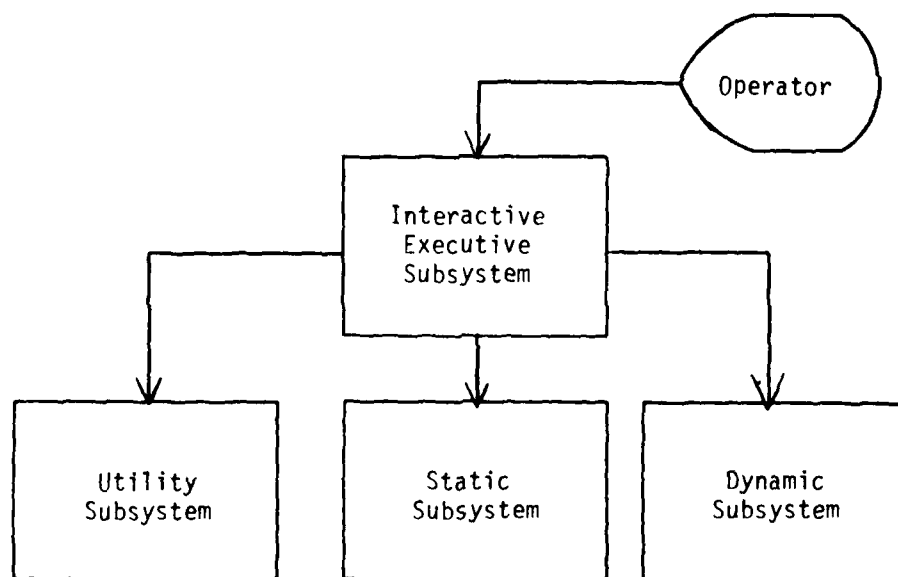


Figure 3-2 MUXSIM Modular Software Structure.

The Purpose of the MUXSIM System

The purpose of the MUXSIM system is to prepare the design and design accuracy of a digital system, used by those interested in carrying out the system design of a digital information transfer/multiplex system. MUXSIM directs questions of data bus utilization and/or bus traffic loading.

The MUXSIM programs serve to combine specific analysis and prototype hardware. MUXSIM provides a means of interacting parts of the detailed analysis (such as updating rate requirements, sampling requirements, data buffering requirements, bus data requirements, processing delay requirements) for numerous point-to-point signaling into logical requirements which can be confirmed for compatible operation by a computer, before attempting a hardware development program.

MUXSIM is devised to be applicable to a set of multiplex system designer's questions that cannot be promptly answered by other available means.

DESCRIPTION OF THE MUXDA PROGRAM

Demand Access Transfer

This model basically deals with a demand access information transfer over the bus. The demand access messages are transmitted after the fixed message requirements are finished and until either the demand messages are used up or time has come for the start of the next fixed message transmission sequence. The central controller should know the length of every transmission and prevent the transmission of a demand message if it will interfere with the start of a fixed message.

Shown in Figure 3-3 is the demand message multiplex system schematic representation.

Statement of the Problem

MUXDA represents an information transfer system which has a fixed format data transfer foreground and an interrupt enabled demand access first-in, first-out background. This system is expected to reduce bus loading and the delay in access of the sporadic data.

Some of the assumptions made to allow the simulation to cycle faster are: error and failure-free environment, interrupt system which allows the Central Control to initiate command/response requests for the demand access data, foreground with fetch messages on a fixed telemetry format command/response basis, and foreground-background mode similar to hybrid analog-digital real-time operating system. Other assumptions are that the foreground transmission has no sporadic motion, and the computed bus load for each transfer is

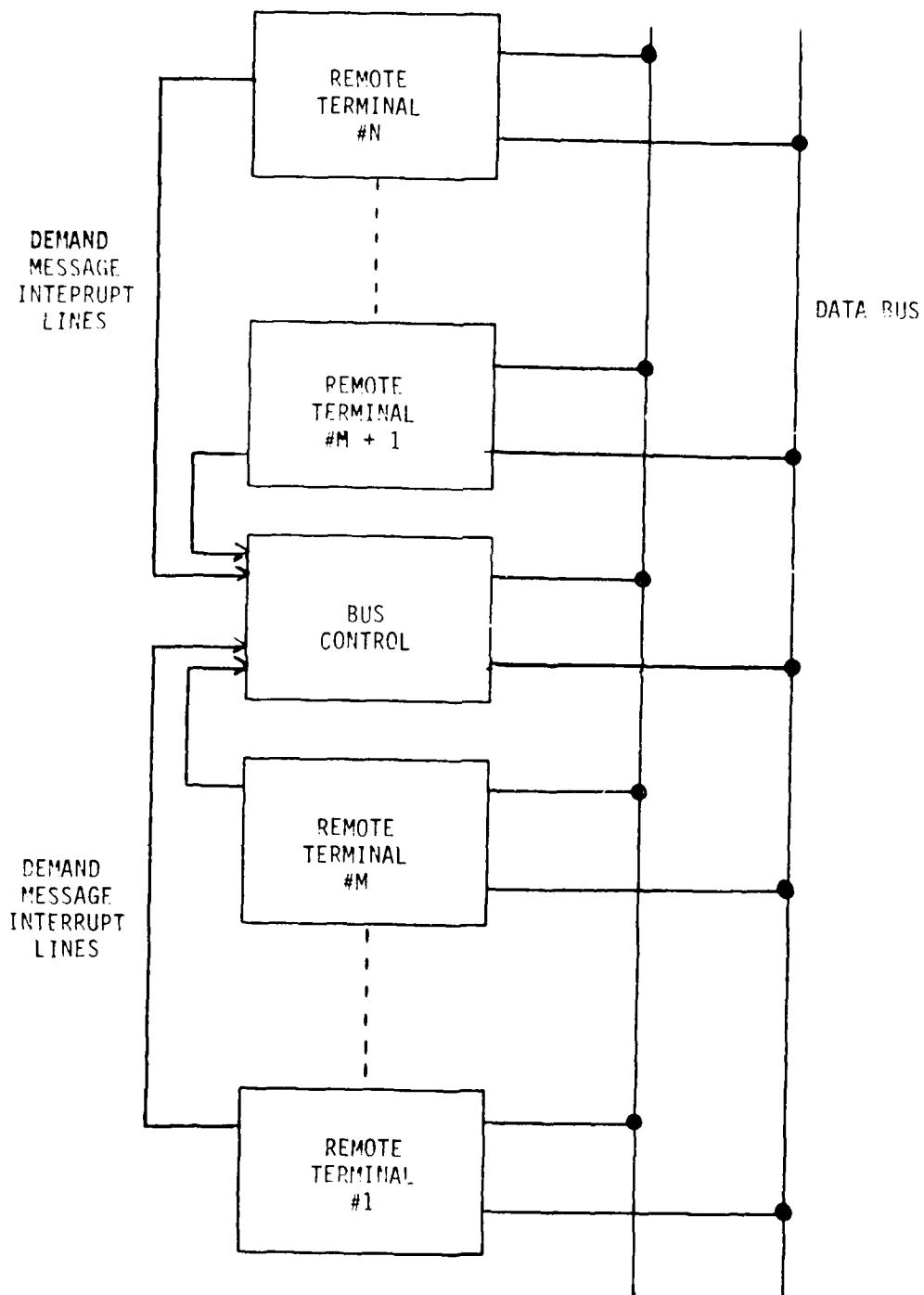


Figure 3-3 Demand Message Multiplex System Schematic Representation.

available from the static subsystem in a lumped sequence for each fundamental update interval. A further assumption is that the command response for this demand access data is initiated by central. Central knows the length of data transmission for each demand access message and does not initiate a demand message transfer which could interfere with the next foreground transmission.

Simulation Objective

The objective of this simulation is to determine bus resource utilization impact on the technique of using demand access background transfer for signals of sporadic nature.

GASP IV Simulation Structure and Program Variables for MUXDA

In this problem, there were two files used. Table 3-1 gives the definition of the files and their associated characteristics for this simulation. File 1 is the event file as per GASP IV and File 2 stores the demand message arrival. Table 3-2 defines the non-GASP variables.

Main Program, Subroutine INTLC and Subroutine EVNTS Description

Main Program

The Main Program establishes the card reader (MCPDR) and line printer (NPRNT) values and subroutine GASP is called.

In this program, a temporary disk file is not used and plot data is stored in the QSET. The MUXSIM executive system is not used, therefore it is not necessary to use subroutines CHAIN, RESTOR, and GETCOM.

ATTRIBUTES	FILE 1	FILE 2
File Definition	Events	Arrived <u>demand message</u> queue
ATTRIB (1)	Event Time	Message Length
(2)	Event type = $100 \cdot I + J$ where I = event type J = sub type	Demand message Number
(3)	Message length (if event type is 200 otherwise it is a don't care situation)	Time of arrival in wait queue

I = Event Type

100 - FUI time start
 200 - Start of FUI free time
 300 - End of Demand Message
 400 - Demand Message arrival

J = Sub Type

I	
100	FUI Number (1,NFUIS)
200	FUI Number (1,NFUIS)
300	Demand Message Number (1,NDM)
400	Demand Message Number (1,NDM)

Table 3-1 Definition of GASP Files.

Variable	Definition
DM (I,J)	Demand message parameter definition $J = \text{Demand message number } (1, NDM)$ $I = \text{Demand message parameter, where:}$ <ul style="list-style-type: none"> 1 = mean time between demand message occurrence 2 = Maximum Δ of uniform distribution about mean 3 = Demand message length
DMSENT (I)	Sum of demand message lengths sent for a particular FUI, where I is the FUI number $I = (1, NFUIS)$
FUI	Fundamental Update Interval for data transmission on bus
FUIT	The time of occurrence of the last FUI numbered 1
FUIFX (I)	Sum of the Fixed Message lengths sent for a particular FUI, where I is the FUI number $I = (1, NFUIS)$
FUINXT	The next FUI start time
FUIWAT (I)	Data bus idle time per FUI, computed by subtracting time of end of last Demand Message sent from start of next FUI. I is the FUI number (1,NFUIS).
MODE	MODE = 1 is FIFO; MODE = 2 is largest to FIT in interval first.
NDM	Maximum quantity of demand messages which the system must process.
NFUI	NFUI is the integer comment FUI number.
NFUIS	Maximum number of FUI intervals. This is the number of minor frame cycles per major frame.

Table 3-2 Definition of non-GASP Variables.

Subroutine INTLC

Subroutine INTLC is called via subroutine DATIN, in order to read in the simulation data cards and to set up the initial conditions from the input data cards or algebraic statements.

In this program, subroutine INTLC reads in Card Type I, Card Type II, and Card Type III. Card Type I defines the FUI duration and run mode, Card Type II specifies the FUI fixed message sequence duration, and Card Type III gives the demand message. All non-GASP user input data are printed out to make checking easier.

Subroutine EVNTS

Subroutine EVNTS sends control to one of the four user written subroutines: FUIT, FUIFRE, ENDDM, and DMARIV. The events of the simulation, in the order of their event code are:

- 100-Start of fundamental update interval time (FUIT)
- 200-End of fixed message transmission on bus (FUIFRE)
- 300-End of demand message transmission on bus (ENDDM)
- 400-Arrival of demand message to the queue (DMARIV)

Subroutine FUIT

Subroutine FUIT performs the following functions:

- (1) In order to prevent round-off errors from accumulating and destroying the results, FUIT establishes the beginning of a major frame.
- (2) In order to demonstrate the validity of operation, FUIT prints out the following for the first 100 intervals: the number of messages

in the queue, the length of demand messages transmitted in a fundamental update interval as a percent of the time available for demand message transmission, and the bus idle time as a percent of the time available for demand message transmission.

(3) For each FUI, a histogram of the length of the demand message transmission sequence is formed.

(4) By calling subroutine NXTFUI, the next FUI is scheduled.

(5) This FUI is scheduled for the start of the FUI free time.

Subroutine FUIFRE (NF)

The end of message transfer for FUI is established in subroutine FUIFRE, which performs the following functions:

(1) This subroutine processes the end of a message transmission and schedules the next.

(2) It establishes if there are any messages to be transmitted and/or the time remaining to do so.

(3) The routine tests to see if a message can be transmitted within the remaining time in FUI.

(4) This subroutine is designed to branch a specified mode and select the message for proper transmission according to that mode.

(5) FUIFRE brings the total length of demand messages up-to-date that are being sent during that FUI; also, it updates the FUI free time to the present remaining time.

Subroutine ENDDM (NM)

The start of a demand message transfer for FUI is established in subroutine ENDDM, which performs the following functions:

- (1) ENDDM performs the end of the demand message arrival processing and establishes a histogram.
- (2) It programs the arrival of FUIFRE while pointing out the end of the message transmission in that FUI.

Subroutine DMARIV (ND)

The arrival of a demand message on the queue is established in subroutine DMARIV, which performs the following functions:

- (1) DMARIV calls for the scheduling of the next demand message arrival and processes the arrival of the demand message.
- (2) It files the current demand message on the queue where it waits for transmission on the data bus.

Subroutine NXTFUI (I,WHEN)

Subroutine NXTFUI performs only one function; that is, the scheduling of the next FUI arrival.

I is the index of the FUI interval number. WHEN is the index of the next start time for this FUI interval.

Subroutine NXTDM (I)

Subroutine NXTDM performs only one function; it schedules the arrival of the next demand message.

I is the index of the Demand Message number.

Simulation Report

The MUXDA outputs are given in the following section. Figure 3-4 shows the input data echo check, provided by subroutine DATIN. Figure 3-5 presents the printout of the files that are obtained at the end of subroutine DATIN. After the GASP IV summary report, there are twenty histograms for the first run, which give the observed, the relative, and the cumulative frequencies for each cell. For example, histogram number two shows that thirty-one percent (31%) of the message has delay time less than or equal to .03 of the time unit. The length of the delay time is from the message arrival to the end of the transfer. Histogram number eleven shows that ninety five percent (95%) of the length of the demand message is less than or equal to .15 of the time unit.

In Figure 3-6, three variables versus time are plotted. These are as follows:

- (1) The number of messages in the queue, versus time
- (2) The length of demand messages transmitted in a fundamental update interval as a percent of the interval time available for demand message transmission, versus time
- (3) The bus idle time as a percent of the time available for demand message transmission, versus time

This plot is expanded and is shown in Figures 3-7, 3-8, and 3-9.

Figure 3-10 shows the output for MUXDA in the second run. Figures 3-12, 3-13, and 3-14 are expanded plots of Figure 3-11.

**GASP FILE STORAGE AREA DUMP AT TIME .0000 **
 MAXIMUM NUMBER OF ENTRIES IN FILE STORAGE AREA = 15

PRINTOUT OF FILE NUMBER 1
 INOW = .0000
 QQTIM = .0000

ENTRY	1	0.0000
ENTRY	2	.3193-01
ENTRY	3	.8715-01
ENTRY	4	.1000+00
ENTRY	5	.1140+00
ENTRY	6	.2000+00
ENTRY	7	.2036+00
ENTRY	8	.3000+00
ENTRY	9	.3373+00
ENTRY	10	.4000+00
ENTRY	11	.5000+00
ENTRY	12	.6000+00
ENTRY	13	.7000+00
ENTRY	14	.8000+00
ENTRY	15	.9000+00

FILE CONTENTS
 .1010+03
 .4020+03
 .4040+03
 .1020+03
 .4050+03
 .1030+03
 .4030+03
 .1040+03
 .4010+03
 .1050+03
 .1060+03
 .1070+03
 .1080+03
 .1090+03
 .1100+03

PRINTOUT OF FILE NUMBER 2
 INOW = .0000
 QQTIM = .0000

THE FILE IS EMPTY

Figure 3-5 File Printout at Time 0 for MUXDA in First Run.

••GASP FILE STORAGE AREA DUMP AT TIME .1000+03••

MAXIMUM NUMBER OF ENTRIES IN FILE STORAGE AREA = 28

PRINTOUT OF FILE NUMBER 1
INOW = .1000+03
QQTIM = .1000+03
TIME PERIOD FOR STATISTICS .1000+03
AVERAGE NUMBER IN FILE 15.6913
STANDARD DEVIATION .4637
MAXIMUM NUMBER IN FILE 16

FILE CONTENTS

ENTRY 1 1000+03
ENTRY 2 1000+03
ENTRY 3 1000+03
ENTRY 4 1000+03
ENTRY 5 1001+03
ENTRY 6 1001+03
ENTRY 7 1001+03
ENTRY 8 1002+03
ENTRY 9 1003+03
ENTRY 10 1004+03
ENTRY 11 1005+03
ENTRY 12 1006+03
ENTRY 13 1007+03
ENTRY 14 1008+03
ENTRY 15 1009+03
ENTRY 16 1010+03

.4020+03
.4010+03
.4040+03
.2010+03
.1020+03
.4050+03
.4030+03
.1030+03
.1040+03
.1050+03
.1060+03
.1070+03
.1080+03
.1090+03
.1100+03
.1010+03

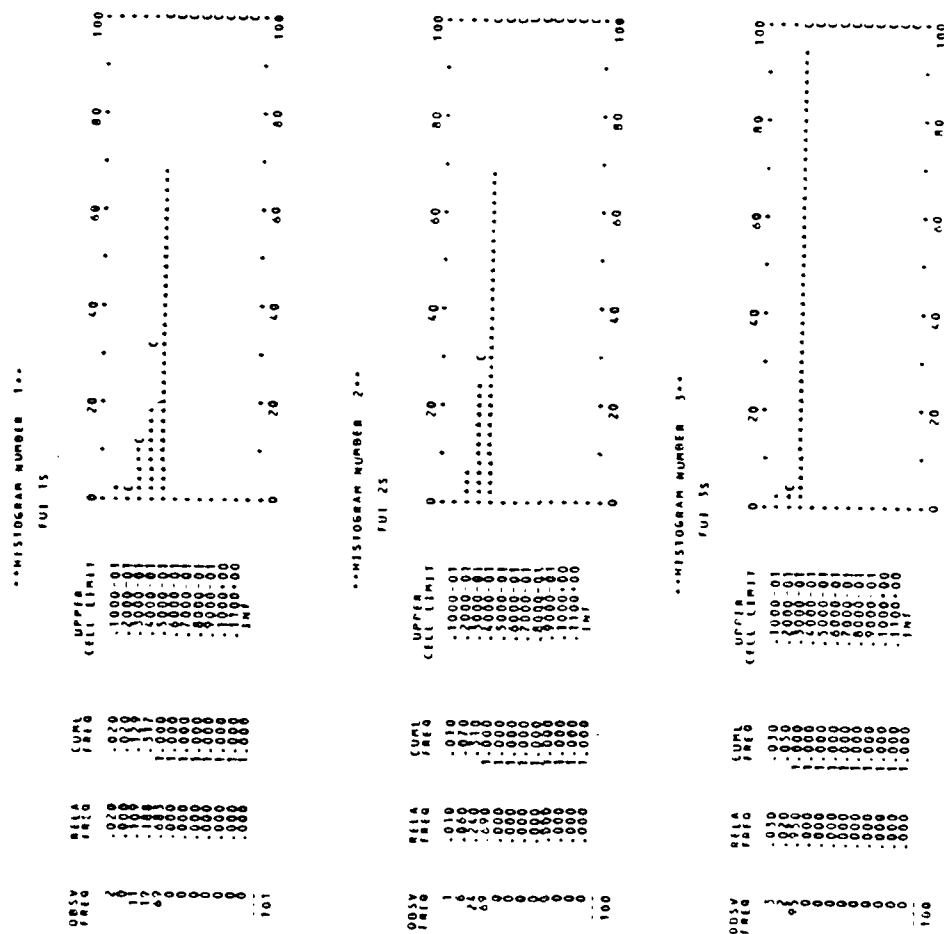
PRINTOUT OF FILE NUMBER 2
INOW = .1000+03
QQTIM = .9999+02
TIME PERIOD FOR STATISTICS .1000+03
AVERAGE NUMBER IN FILE 2.9019
STANDARD DEVIATION 2.1125
MAXIMUM NUMBER IN FILE 12

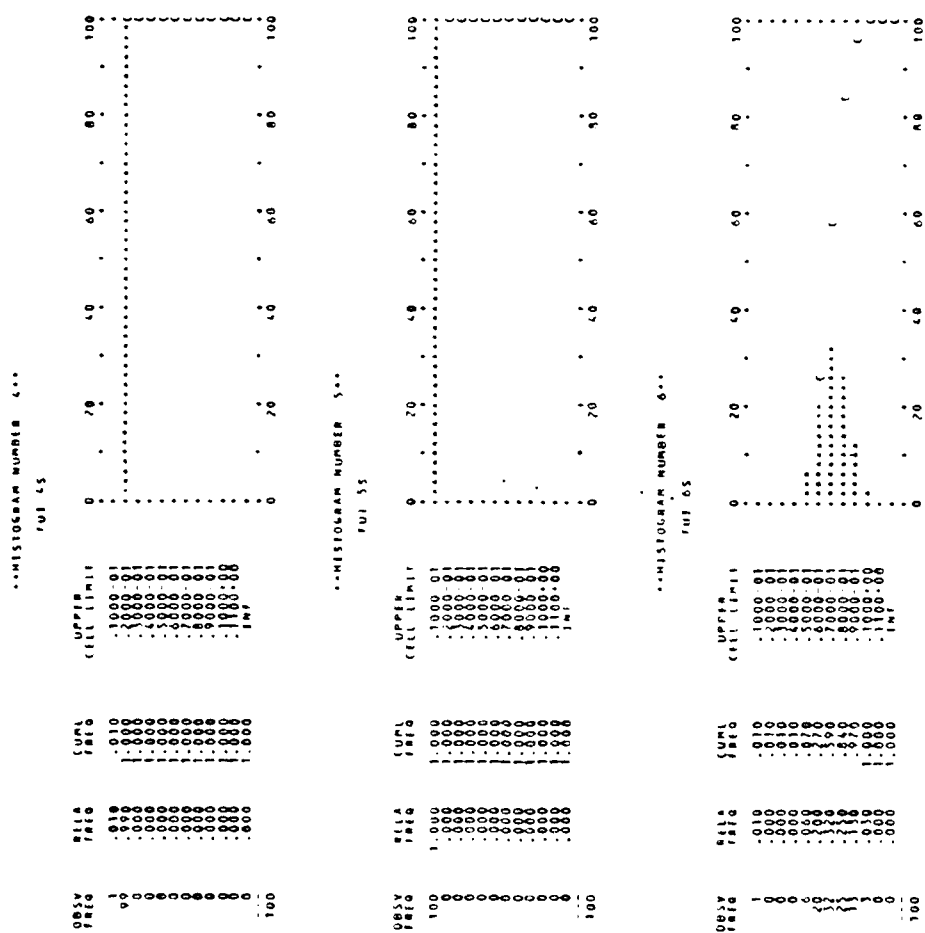
FILE CONTENTS

ENTRY 1 9000-02
ENTRY 2 6000-02

.4000+01
.5000+01

Figure 3-5 (Continued).





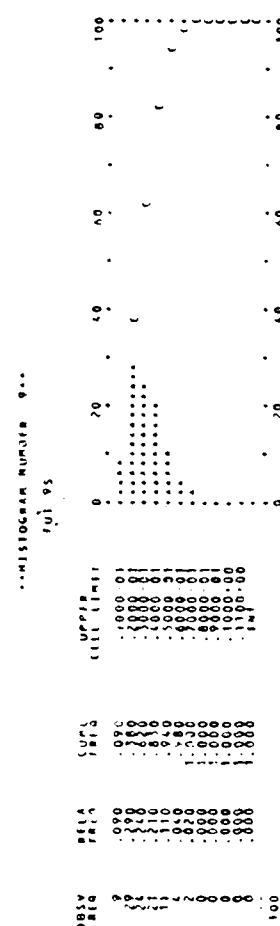
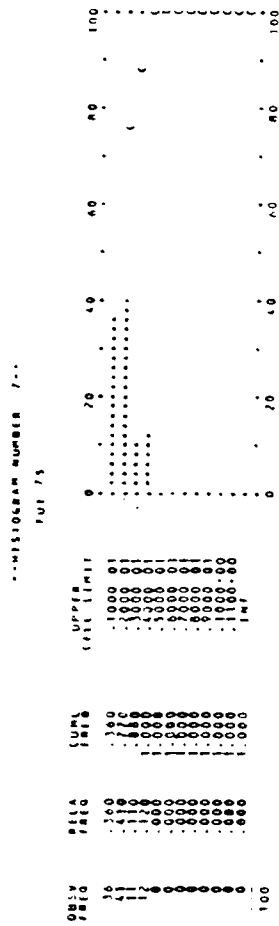
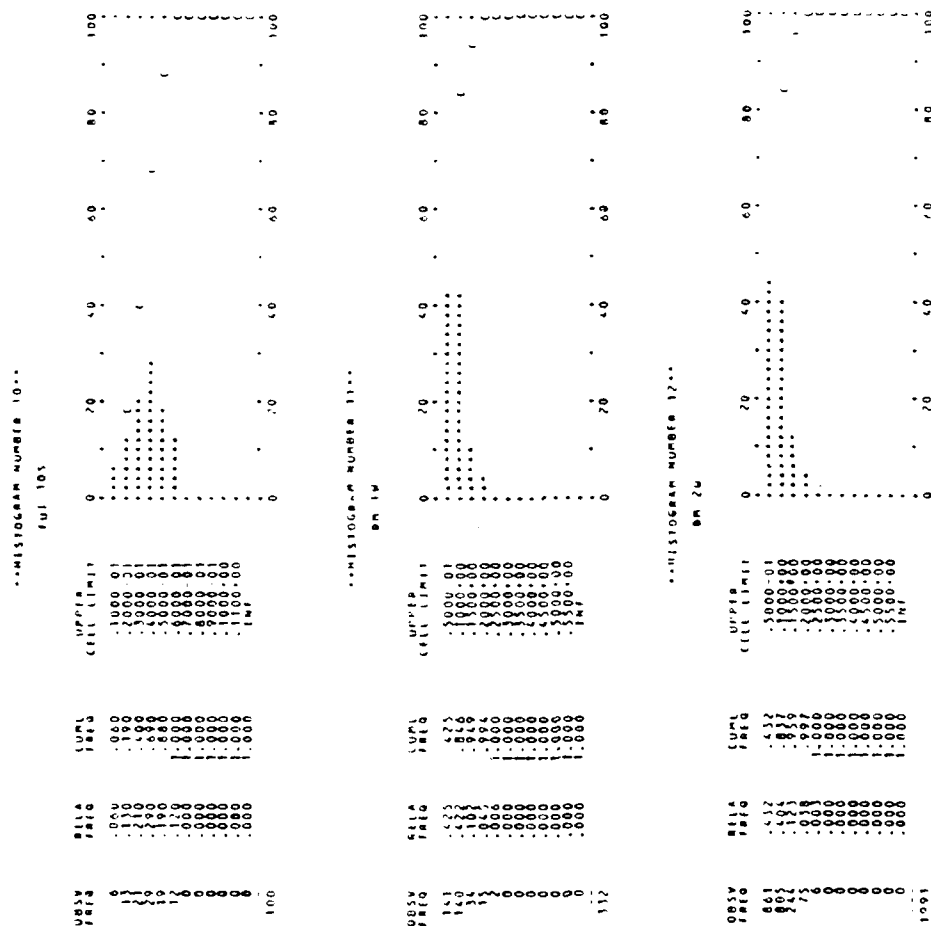
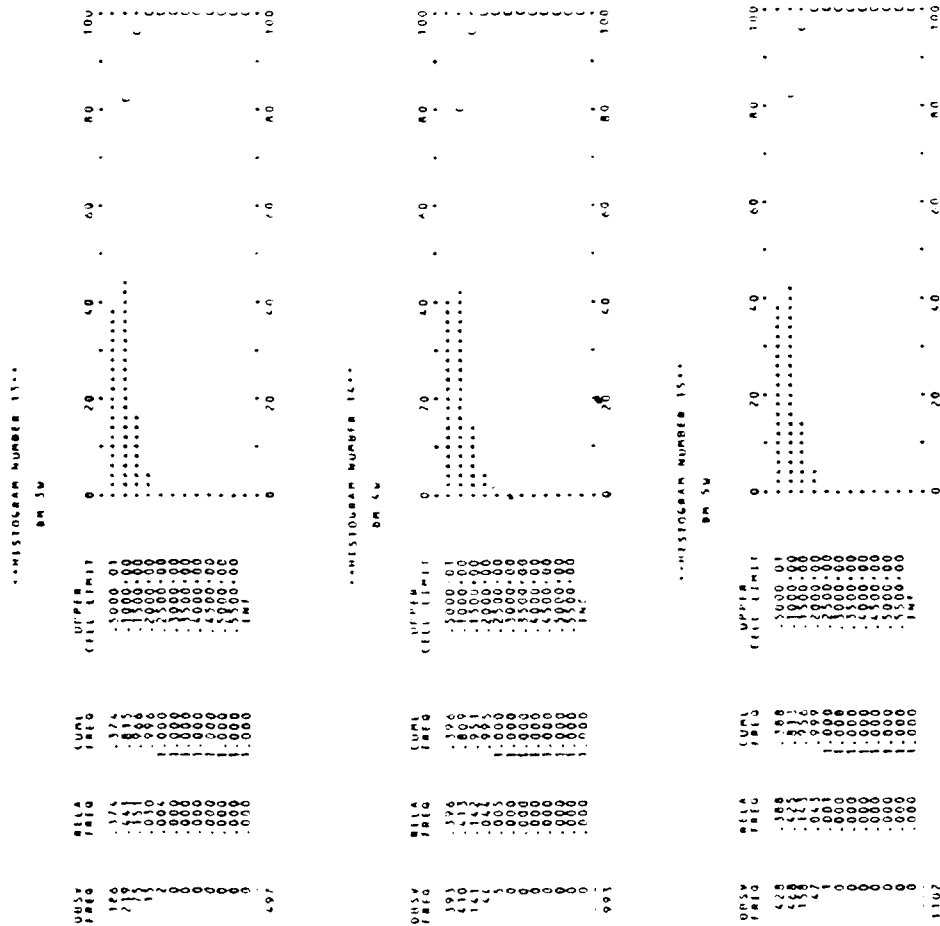


Figure 3-5 (Continued).





```

--HISTOGRAM NUMBER 1A--
PM AV
DATA  DATA  DATA  DATA  DATA  DATA  DATA  DATA  DATA  DATA
INFO  INFO  INFO  INFO  INFO  INFO  INFO  INFO  INFO  INFO
0  .  20  .  40  .  60  .  80  .  100
NO VALUES RECORDED.

--HISTOGRAM NUMBER 17--
PM JV
DATA  DATA  DATA  DATA  DATA  DATA  DATA  DATA  DATA  DATA
INFO  INFO  INFO  INFO  INFO  INFO  INFO  INFO  INFO  INFO
0  .  20  .  40  .  60  .  80  .  100
NO VALUES RECORDED.

--HISTOGRAM NUMBER 18--
PM BV
DATA  DATA  DATA  DATA  DATA  DATA  DATA  DATA  DATA  DATA
INFO  INFO  INFO  INFO  INFO  INFO  INFO  INFO  INFO  INFO
0  .  20  .  40  .  60  .  80  .  100
NO VALUES RECORDED.

--HISTOGRAM NUMBER 19--
PM DV
DATA  DATA  DATA  DATA  DATA  DATA  DATA  DATA  DATA  DATA
INFO  INFO  INFO  INFO  INFO  INFO  INFO  INFO  INFO  INFO
0  .  20  .  40  .  60  .  80  .  100
NO VALUES RECORDED.

--HISTOGRAM NUMBER 20--
PM EV
DATA  DATA  DATA  DATA  DATA  DATA  DATA  DATA  DATA  DATA
INFO  INFO  INFO  INFO  INFO  INFO  INFO  INFO  INFO  INFO
0  .  20  .  40  .  60  .  80  .  100
NO VALUES RECORDED.

```

Figure 3-5 (Continued).

GASP FILE STORAGE AREA DUMP AT TIME .1000+03

MAXIMUM NUMBER OF ENTRIES IN FILE STORAGE AREA = 28

PRINTOUT OF FILE NUMBER 1
INOW = .1000+03
QQTIM = .1000+03

TIME PERIOD FOR STATISTICS .1000+03
AVERAGE NUMBER IN FILE 15.6931
STANDARD DEVIATION .4629
MAXIMUM NUMBER IN FILE 16

	FILE CONTENTS
ENTRY 1	.4050+03
ENTRY 2	.5000-01
ENTRY 3	.4020+03
ENTRY 4	.5000-01
ENTRY 5	.2010+03
ENTRY 6	.5000-01
ENTRY 7	.4040+03
ENTRY 8	.5000-01
ENTRY 9	.1020+03
ENTRY 10	.5000-01
ENTRY 11	.4010+03
ENTRY 12	.5000-01
ENTRY 13	.4030+03
ENTRY 14	.5000-01
ENTRY 15	.1030+03
ENTRY 16	.5000-01
ENTRY 17	.1040+03
ENTRY 18	.5000-01
ENTRY 19	.1050+03
ENTRY 20	.5000-01
ENTRY 21	.1060+03
ENTRY 22	.5000-01
ENTRY 23	.1070+03
ENTRY 24	.5000-01
ENTRY 25	.1080+03
ENTRY 26	.5000-01
ENTRY 27	.1090+03
ENTRY 28	.5000-01
ENTRY 29	.1100+03
ENTRY 30	.5000-01
ENTRY 31	.1010+03
ENTRY 32	.5000-01

PRINTOUT OF FILE NUMBER 2
INOW = .1000+03
QQTIM = .9998+02

TIME PERIOD FOR STATISTICS .1000+03
AVERAGE NUMBER IN FILE 2.9605
STANDARD DEVIATION 2.1782
MAXIMUM NUMBER IN FILE 12

	FILE CONTENTS
ENTRY 1	.2000+01
ENTRY 2	.9994+02
ENTRY 3	.3000+01
ENTRY 4	.9994+02
ENTRY 5	.4000+01
ENTRY 6	.9998+02
ENTRY 7	.9998+02
ENTRY 8	.2000+01
ENTRY 9	.5000-02
ENTRY 10	.7000-02
ENTRY 11	.9000-02
ENTRY 12	.5000-02

Figure 3-5 (Continued).

••TABLE NUMBER 1••
RUN NUMBER 1

[illegible]

Figure 3-5 (Continued).

.8600+01	.1000+01	.2660+00	.7340+00
.8700+01	.5000+01	.3978+00	.6022+00
.8800+01	.0000	.2174+00	.7826+00
.8900+01	.6000+01	.4615+00	.5385+00
.9000+01	.3000+01	.9000+00	.1000+00
.9100+01	.2000+01	.9250+00	.7500+01
.9200+01	.0000	.6667+00	.3333+00
.9300+01	.1000+01	.9000+00	.1000+00
.9400+01	.2000+01	.5000+00	.5000+00
.9500+01	.6000+01	.7474+00	.2526+00
.9600+01	.2000+01	.5319+01	.9468+00
.9700+01	.3000+01	.6129+00	.3871+00
.9800+01	.2000+01	.0000	.1000+01
.9900+01	.4000+01	.4725+00	.5275+00
.1000+02	.2000+01	.8000+00	.2000+00
.1010+02	.0000	.8000+00	.2000+00
.1020+02	.2000+01	.9667+00	.3333+01
.1030+02	.5000+01	.9500+00	.5000+01
.1040+02	.5000+01	.6000+00	.4000+00
.1050+02	.1100+02	.5368+00	.4632+00
.1060+02	.1000+01	.3191+00	.6809+00
.1070+02	.3000+01	.3441+00	.6559+00
.1080+02	.2000+01	.1739+00	.8261+00
.1090+02	.4000+01	.5714+00	.4286+00
MINIMUM	.0000	.0000	.1987+05
MAXIMUM	.1100+02	.1000+01	.1000+01

Figure 3-5 (Continued).

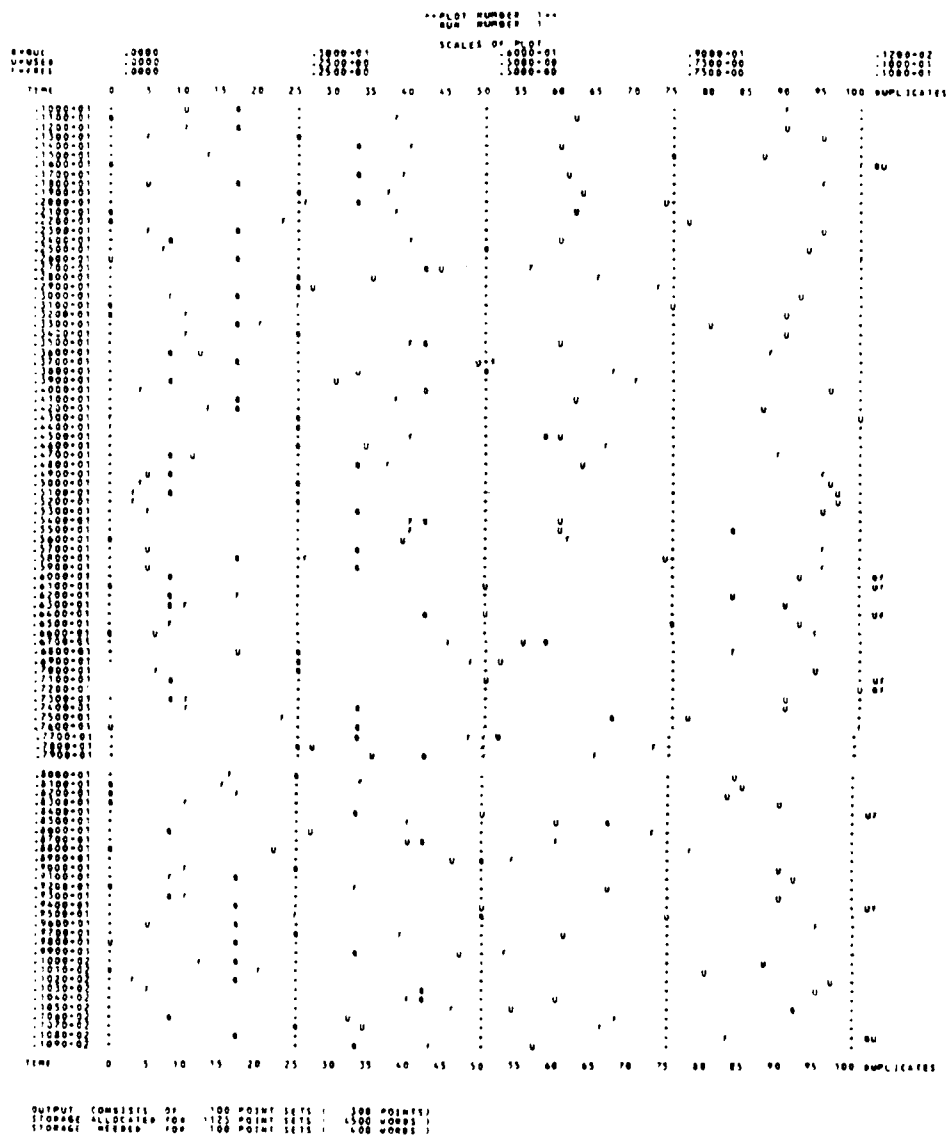


Figure 3-6 Plot Output for MUXDA.

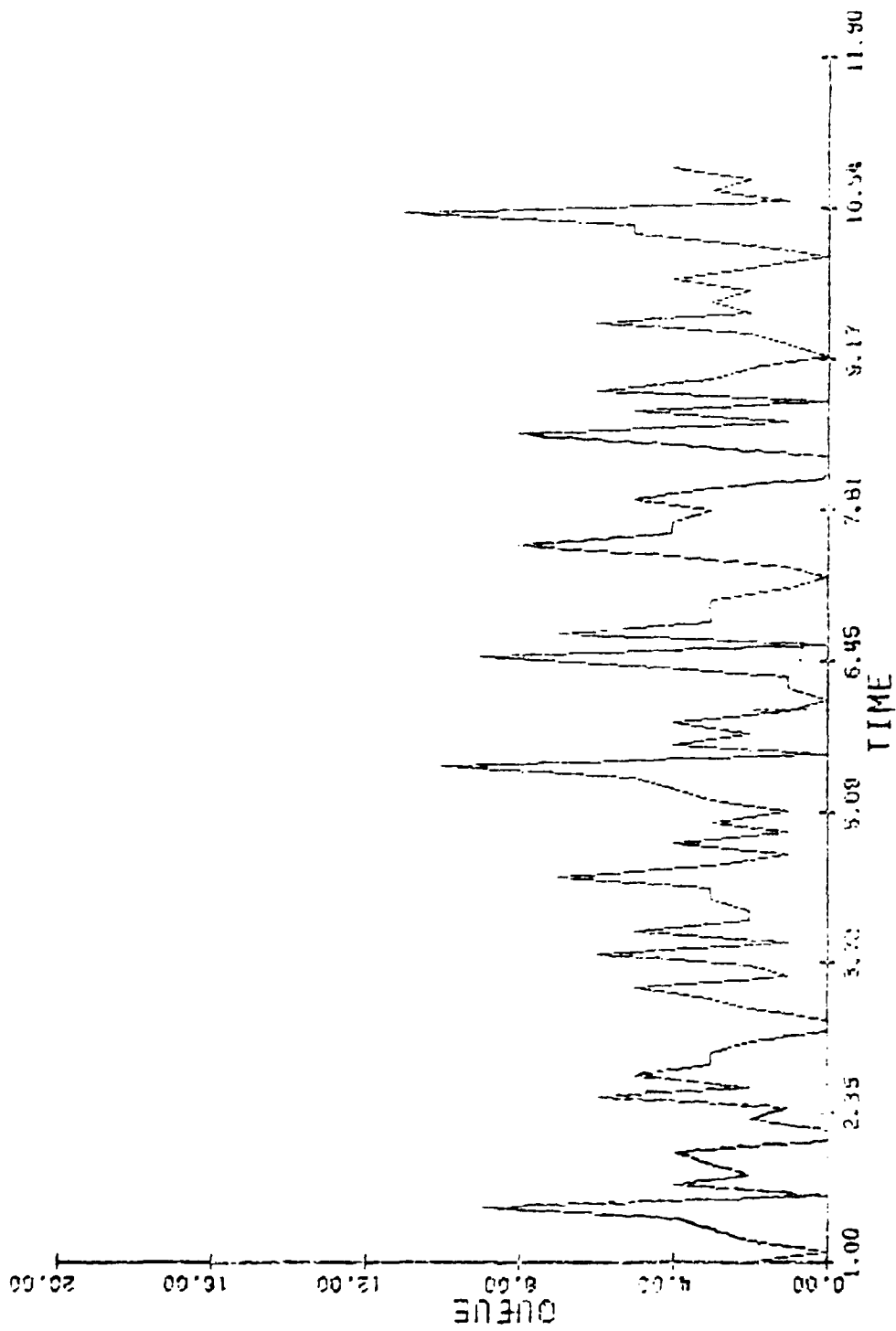


Figure 3-7 Variation of Queue Length with Time in MUXDA (First Run).

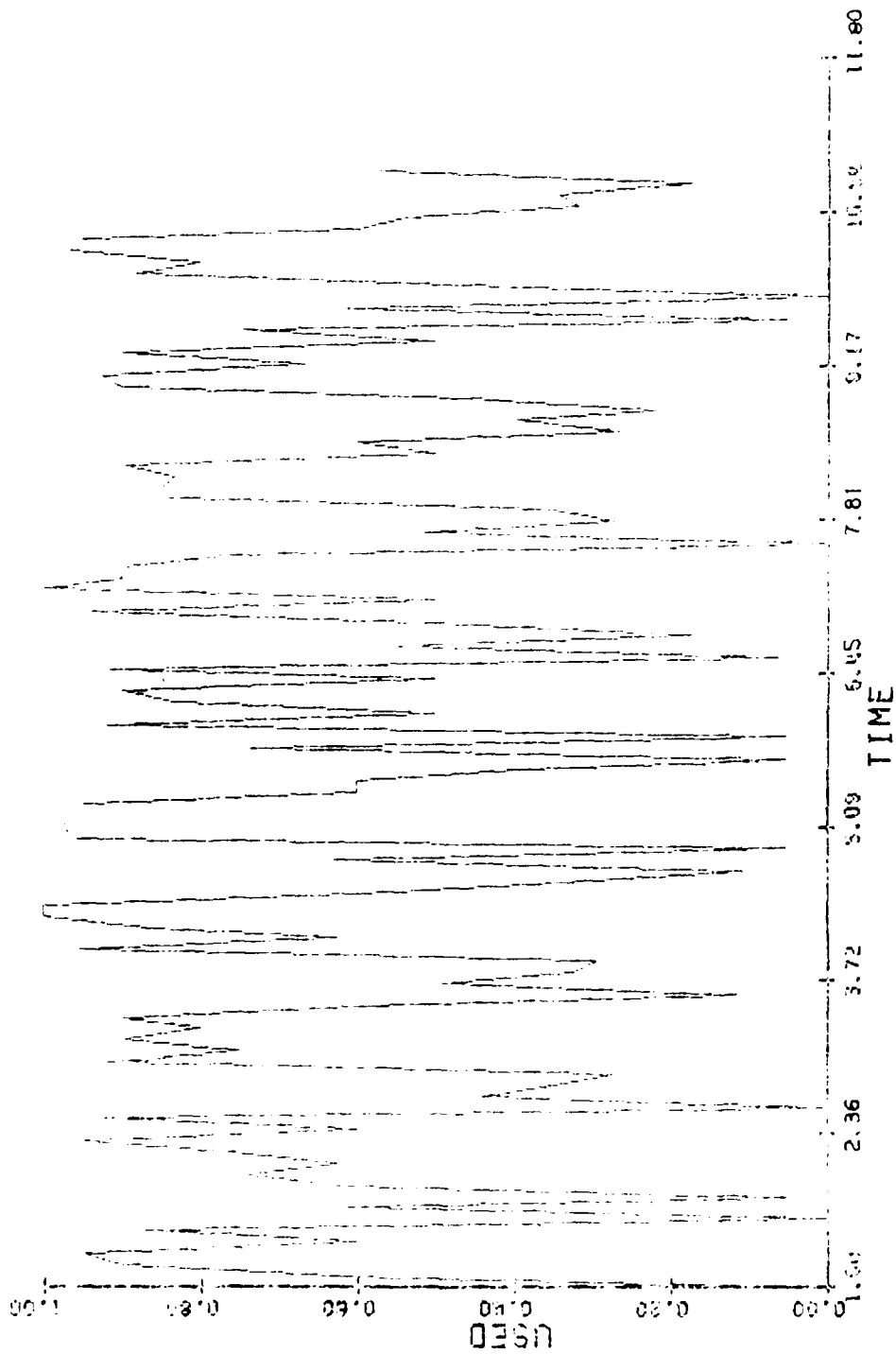


Figure 3-8 Variation of the Percentage of Interval Time Available for Demand Message Transmission with Time in MUXDA (First Run).

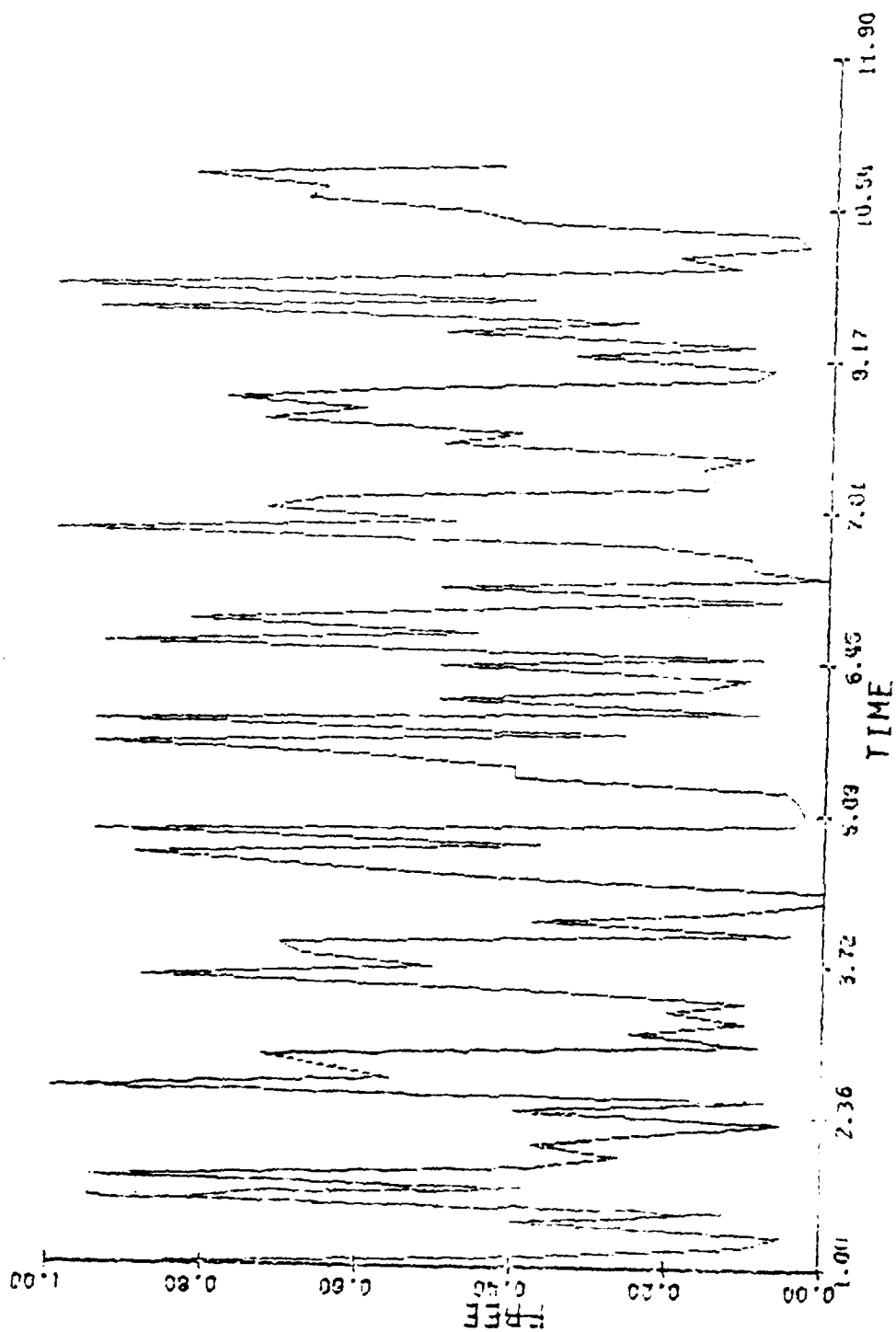


Figure 3-9 Variation of Bus Idle Time with Time in MUXD (First Run).

**GASP FILE STORAGE AREA DUMP AT TIME .0000 **
 MAXIMUM NUMBER OF ENTRIES IN FILE STORAGE AREA = 15

PRINTOUT OF FILE NUMBER 1
 TNOW = .0000
 QQTIM= .0000

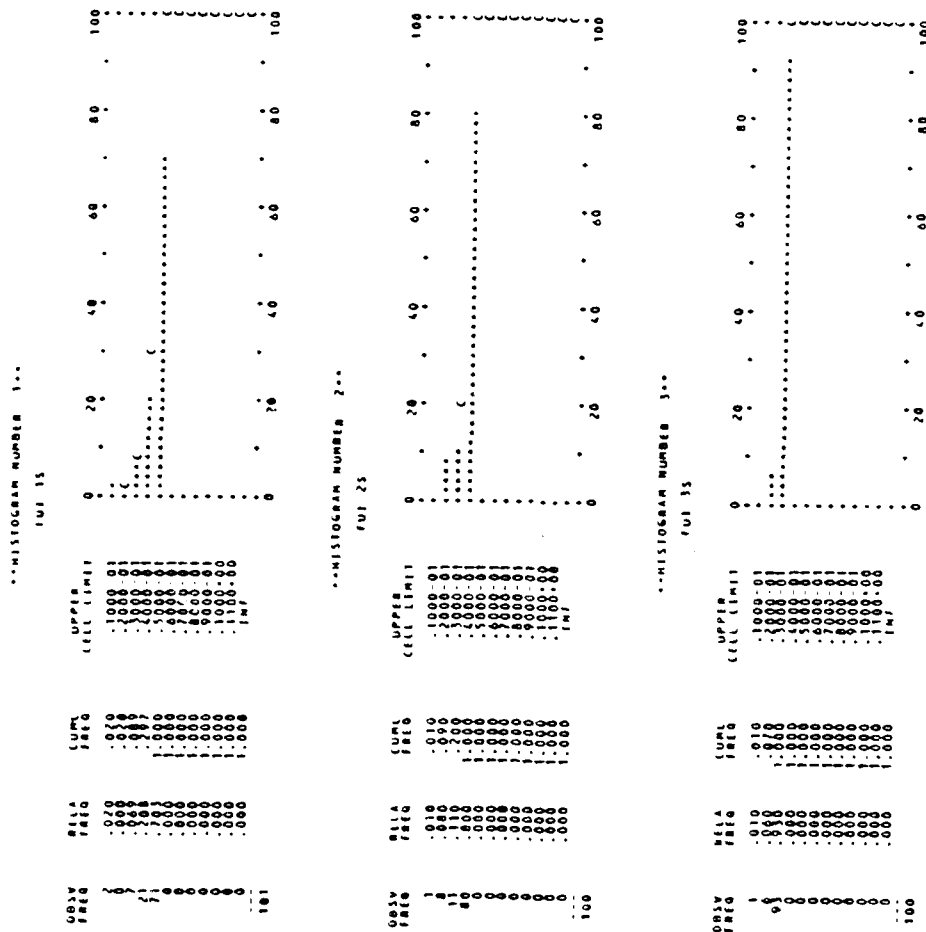
ENTRY	1	0000	1010+03	FILE CONTENTS
ENTRY	2	4624-01	4020+03	.5000-01
ENTRY	3	8444-01	4050+03	.5000-01
ENTRY	4	8779-01	4040+03	.5000-01
ENTRY	5	1000+00	1020+03	.5000-01
ENTRY	6	2000+00	1030+03	.5000-01
ENTRY	7	2136+00	4030+03	.5000-01
ENTRY	8	3000+00	1040+03	.5000-01
ENTRY	9	3297+00	4010+03	.5000-01
ENTRY	10	4000+00	1050+03	.5000-01
ENTRY	11	5000+00	1060+03	.5000-01
ENTRY	12	6000+00	1070+03	.5000-01
ENTRY	13	7000+00	1080+03	.5000-01
ENTRY	14	8000+00	1090+03	.5000-01
ENTRY	15	9000+00	1100+03	.5000-01

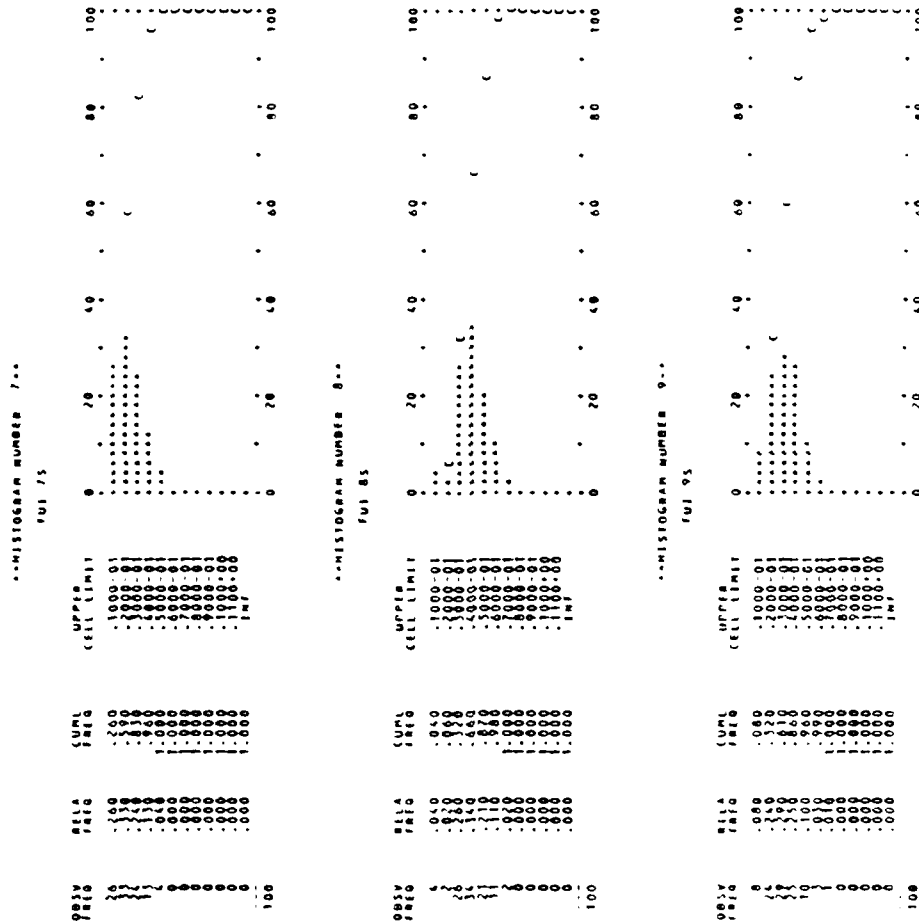
=====

PRINTOUT OF FILE NUMBER 2
 TNOW = .0000
 QQTIM= .0000

THE FILE IS EMPTY

Figure 3-10 File Printout at Time 0 for MUXDA in Second Run.





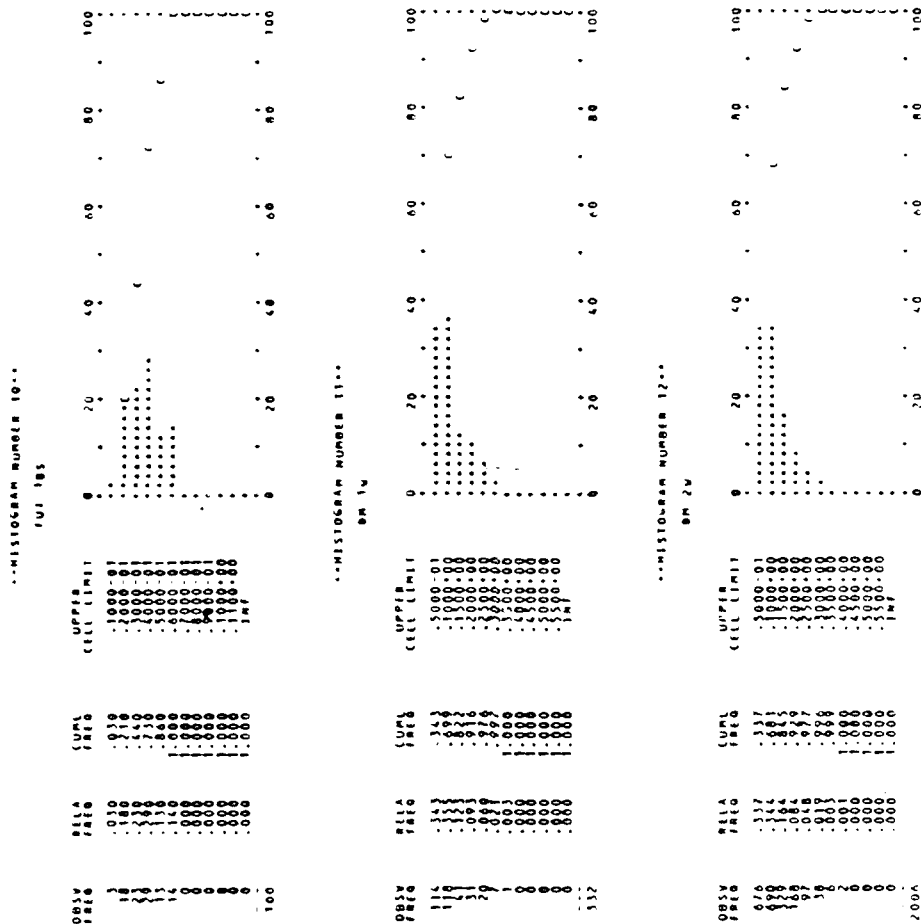


Figure 3-10 (Continued).


```

--HISTOGRAM NUMBER 16--
BM 6W
OBSV  DATA  CUML  UPPER
FREQ  FREQ  FREQ  CELL LIMIT
      0      20      40      60      80      100
NO VALUES RECORDED.

--HISTOGRAM NUMBER 17--
BM 7W
OBSV  DATA  CUML  UPPER
FREQ  FREQ  FREQ  CELL LIMIT
      0      20      40      60      80      100
NO VALUES RECORDED.

--HISTOGRAM NUMBER 18--
BM 8W
OBSV  DATA  CUML  UPPER
FREQ  FREQ  FREQ  CELL LIMIT
      0      20      40      60      80      100
NO VALUES RECORDED.

--HISTOGRAM NUMBER 19--
BM 9W
OBSV  DATA  CUML  UPPER
FREQ  FREQ  FREQ  CELL LIMIT
      0      20      40      60      80      100
NO VALUES RECORDED.

--HISTOGRAM NUMBER 20--
BM 10W
OBSV  DATA  CUML  UPPER
FREQ  FREQ  FREQ  CELL LIMIT
      0      20      40      60      80      100

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Figure 3-10 (Continued).

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Figure 3-10 (Continued).

.8700+01	.2000+01	.2688+00	.7312+00
.8800+01	.2000+01	.4022+00	.5978+00
.8900+01	.4000+01	.2088+00	.7912+00
.9000+01	.2000+01	.9400+00	.6001+01
.9100+01	.0000	.9250+00	.7500+01
.9200+01	.0000	.1000+01	.3974+05
.9300+01	.1000+01	.8000+00	.2000+00
.9400+01	.2000+01	.9000+00	.1000+00
.9500+01	.7000+01	.6526+00	.3474+00
.9600+01	.3000+01	.3404+00	.6596+00
.9700+01	.4000+01	.3226+00	.6774+00
.9800+01	.3000+01	.2935+00	.7065+00
.9900+01	.4000+01	.3846+00	.6154+00
.1000+02	.2000+01	.8200+00	.1800+00
.1010+02	.1000+01	.8750+00	.1250+00
.1020+02	.1000+01	.9000+00	.1000+00
.1030+02	.1000+01	.1000+01	.5960+05
.1040+02	.2000+01	.9000+00	.1000+00
.1050+02	.6000+01	.4526+00	.5474+00
.1060+02	.2000+01	.2660+00	.7340+00
.1070+02	.3000+01	.4086+00	.5914+00
.1080+02	.6000+01	.2717+00	.7283+00
.1090+02	.1000+01	.4505+00	.5495+00
.1100+02	.4000+01	.7400+00	.2600+00
MINIMUM	.0000	.0000	.1397+06
MAXIMUM	.9000+01	.1000+01	.1000+01

Figure 3-10 (Continued).

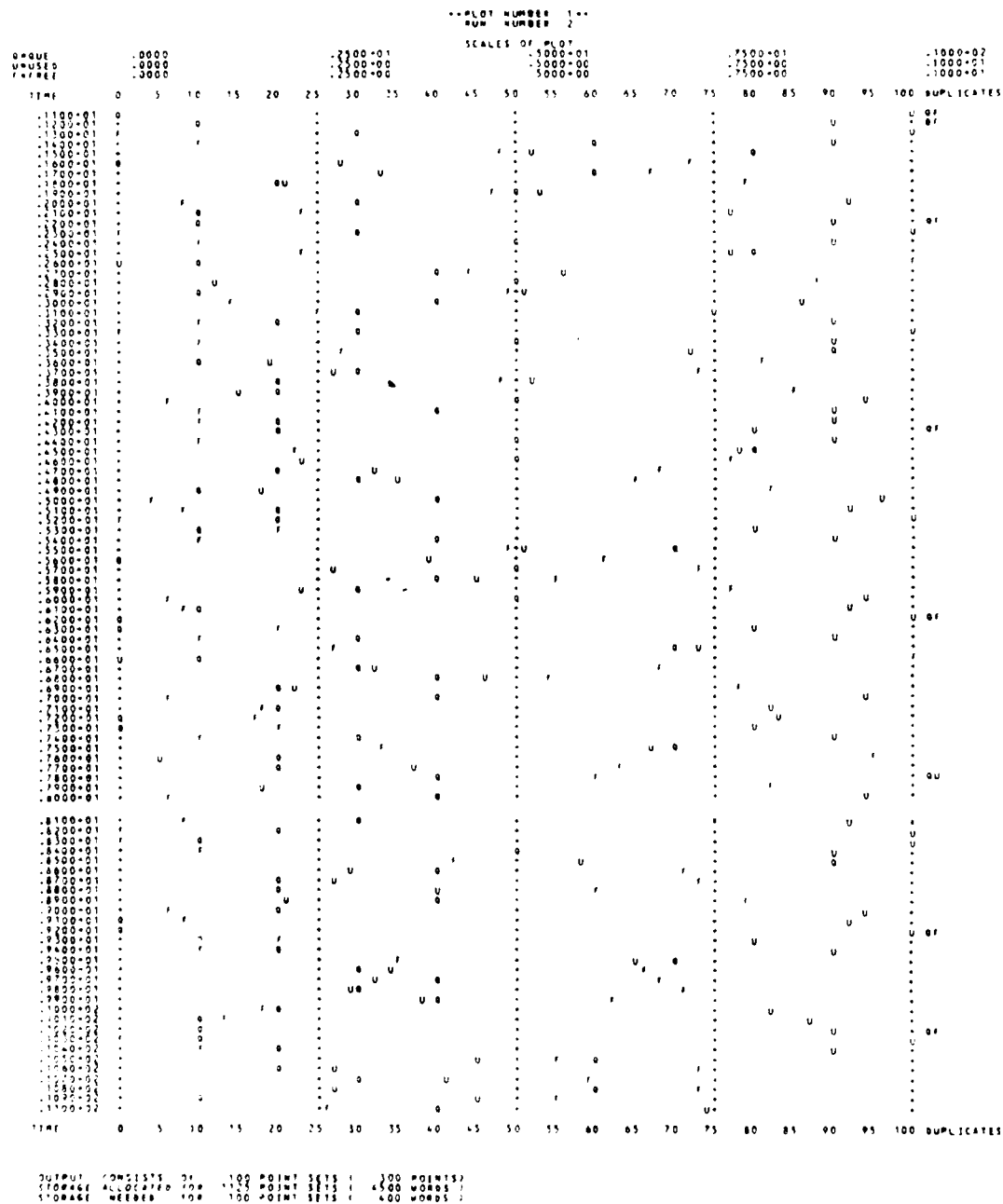


Figure 3-11 Plot Output for MUXDA in Second Run.

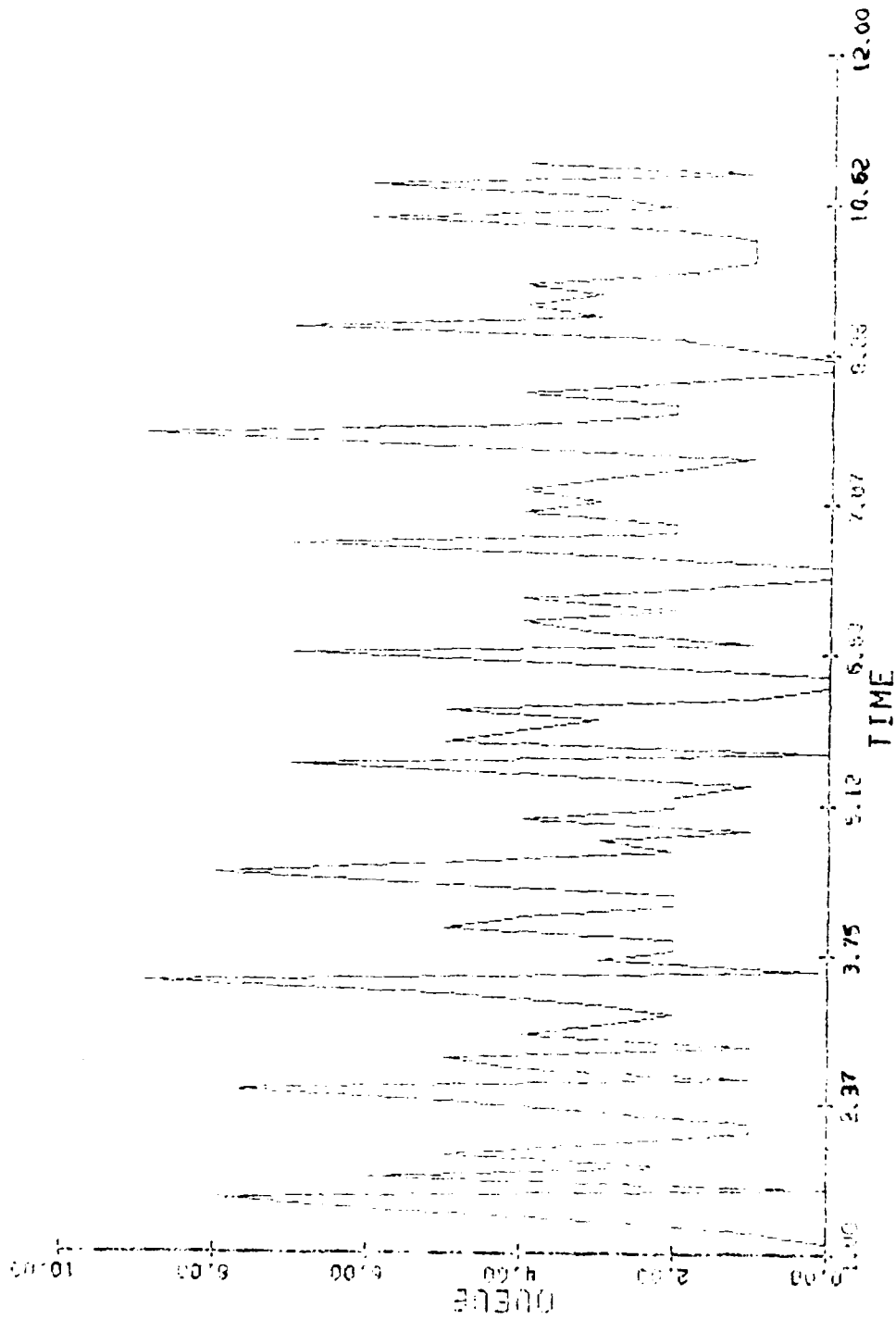


Figure 3-12 Variation of Queue Length with Time in MUXDA (Second Run).

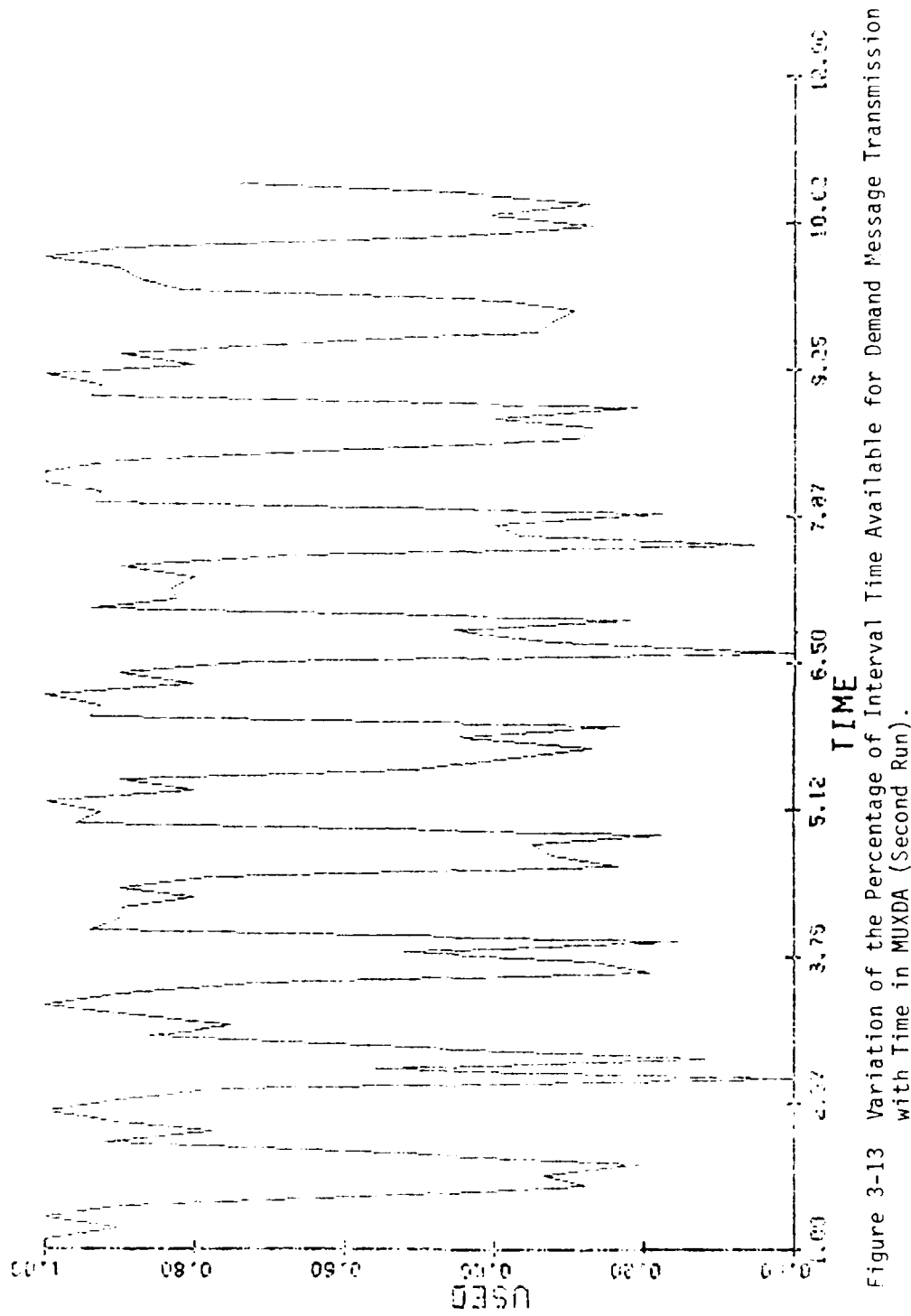


Figure 3-13 Variation of the Percentage of Interval Time Available for Demand Message Transmission with Time in MUXDA (Second Run).

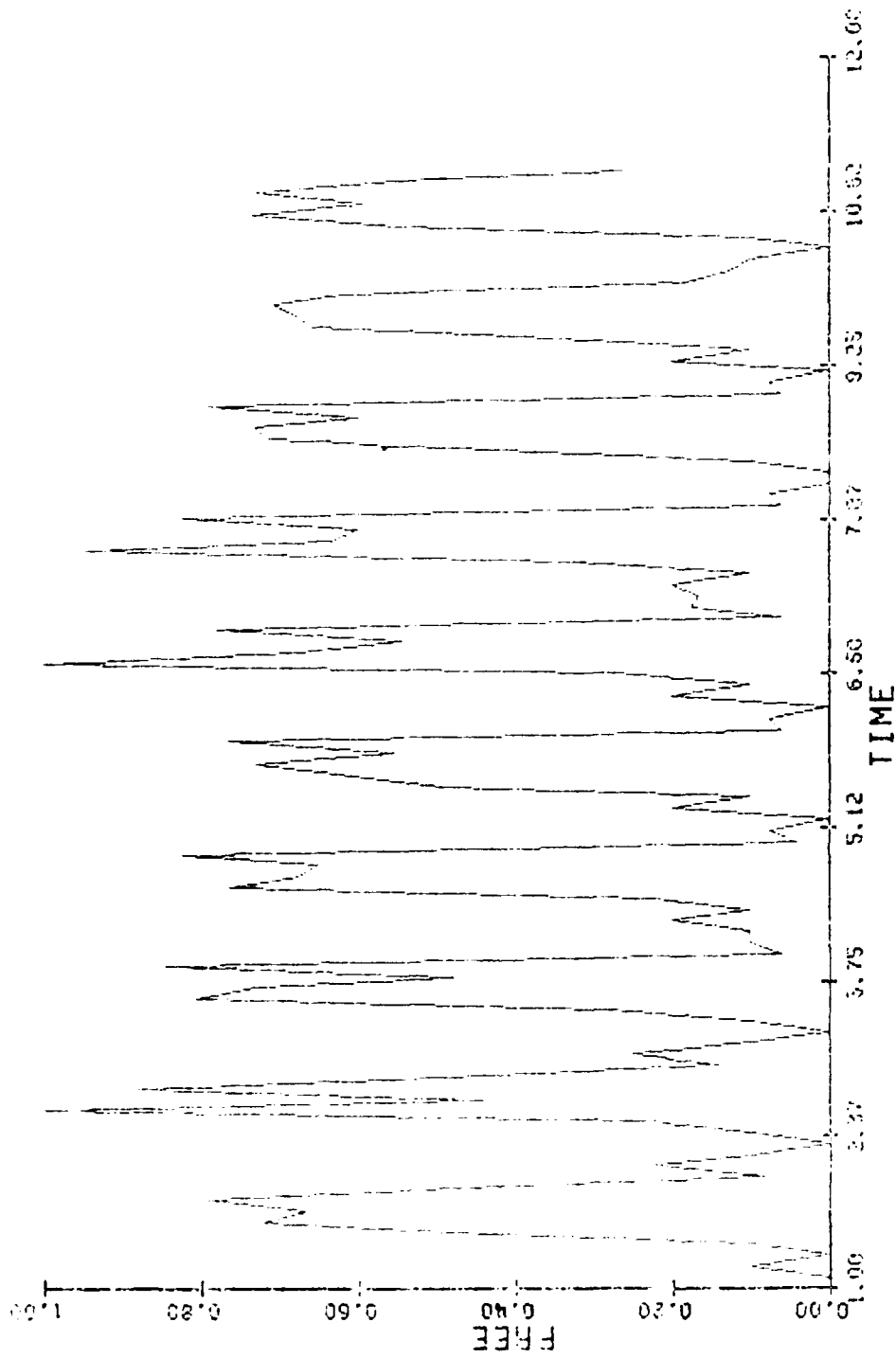


Figure 3-14 Variation of Bus Idle Time with Time in MUXDA (Second Run).

A DESCRIPTION OF THE MUXDB PROGRAM

The MUXDB model refers to redundancy management and fault-handling phases of the multiplex system. Regarding the means by which faults will be dealt with and system redundancy controlled, this is an area of great complexity in the design of multiplex systems. Redundancy is designed into multiplex systems to reduce malfunctions.

MUXDA and MUXDB basically have the same key features, but both models are important because it takes longer to cycle through an equivalent simulated time for MUXDB than it does for MUXDA. MUXDB is a more complex form of model DA; the differences include the following:

- (1) extreme noise impact on the data bus
- (2) terminal malfunction and impact of failure recovery
- (3) the command and response dealt with on an individual message basis
- (4) introduction of message transmission time uncertainties

Statement of the Problem

Model DB represents a system consisting of demand access background message queueing and foreground fixed format message transmission. After completing the fixed message requirement, the demand access messages are transmitted on a first-in, first-out basis.

Model DB takes into account the impact of noise on the dual redundant data bus. In order for a failure to result, both data buses must be impacted by a noise event during transmission of the same message. In this model, bus failures are generated by using a noise event of

ATTRIBUTES	FILE 1	FILE 2	FILE 3
File Definition	Events	Arrived Demand Messages	Temporary Storage File
ATRIB (1)	Event Time	Time of Arrival	Event Time
(2)	Event Type where Event Type = $I*100 + J$ and I is event type and J is sub-type	1000. + Demand Message Number	Same as File 1
(3)	Message number (for event type 100) Message number plus number of hits on buses (for event types 200 and 300) Noise generator number (for event types 400 or 500) Don't care (for other event types)	Time of Arrival in Waiting Queue	Same as File 1

I = Event Type

J = Subtype

100 - Watchdog Timer
 200 - Call to a Terminal
 300 - Terminal Response to a Call
 400 - Noise Start
 500 - Noise Stop
 600 - Terminal Recovery from Failure
 700 - Terminal Failure
 800 - Start a FUI
 1000 - Demand Message Arrival

I	J
100	Dummy Argument
200	Terminal Number 1,NTP
300	Terminal Number 1,NTR
400	Bus/Noise Designation 1,2,3
500	Bus/Noise Designation 1,2,3
600	Terminal Number 1,NTR
700	Terminal Number 1,NTR
800	FUI Number 1,NFUIS
1000	Demand Message Number i,NDM

Table 3-3 Definition of GASP Files.

Variable	Definition
DM (I,J)	<p>Demand Message Parameter Definition.</p> <p>J = Demand Message Number I = Demand Message Parameter</p> <p>where:</p> <p>1 = Mean time between Demand Message Occurrences</p> <p>2 = Maximum Δ^* of uniform distribution about Mean</p> <p>3 = Demand Message length</p> <p>4 = Terminal to call for this Message</p>
DME	Time of the end of the response of the last demand message sent
FIX (I,J)	<p>Fixed message lengths per FUI</p> <p>J = FUI number I = (I,NFIX(J)) for particular Fixed Message within FUI</p>
FME	Time of the end of the response of the last fixed message sent
FUI	Fundamental Update Interval (FUI) for data transmission on bus
FUIIT	The time of occurrence of the last FUI numbered 1
FUIPRS	Time of start of actual message or process for FUI
FUISTA	The actual time of FUI start
IBUSY	Bus Controller Busy Transmitting or Awaiting Response (0 = Not Busy, 1 = Busy)
ICURF	The FUI number currently being processed (1,NFUIS)
ILBUS	The current number of noise events disrupting transmission on the left bus (0,NNOISE)

Table 3-4 Definition of Non-GASP Variables.

* Time increment between two successive points.

Variable	Definition
IØK (I)	Terminal Up/Down Status I = Terminal Number (1,NTR) IØK(I) = (0=Up and Working, 1=Busted)
IRBUS	The current number of noise events disrupting transmission on the right bus (0,NNOISE)
IRESE	The number of valid readable responses lost to timeout
JIT	The switch to detect occurrence of the first scheduled message
MSGNØN	The current fixed message number, in FUI, ICURF, being processed at this time if MSGTYP=1 (Don't care if MSGTYP≠1)
MSGTYP	The current message type being processed by the bus controller. Where MSGTYP equals: 1 for fixed messages 2 for demand messages
NB	Number of noise hits on both buses
NØM	Maximum Quantity of Demand Messages which the System must process
NFIX (I)	The number of fixed messages to be processed by an individual FUI I = Particular FUI Number (1,NFUIS)
NFUIS	Maximum number of FUI intervals. This is the number of minor frame cycles per major frame.
NL	Number of noise hits on left bus
NMSG	Total number of messages sent during simulation
NMSGH	Total number of messages hit on at least one bus
NNOISE	Number of different noise generators impacting the system. This is the number of user input noise generator cards (Max=15).

Table 3-4 Definition of Non-GASP Variables (Continued).

Variable	Definition
NSBUS (I)	Noise generation parameter for generator I which denotes bus(es) impacted. (I=1, NNOISE) and NSBUS(I)=: 1 for left bus affected 2 for right bus affected 3 for both buses affected.
NR	Number of noise hits on right bus
NTM	User input of quantity of terminal down events affecting system. (Note: a terminal down event can affect any terminal in system).
NTO	Number of timeouts
NTP	User input of quantity of terminals in system
NUMV (I)	(Unused variable)
SLNG (I)	Mean length for occurrence of noise event generated by noise generator I. Where I = (1, NNOISE)
SLVAR	Maximum Δ of uniform distribution about length SLNG(I) for occurrence noise generator I where I = (1, NNOISE)
SMEAN (I)	Mean time between occurrences of noise events generated by noise generator I (I = (1, NNOISE)).
SMVAR (I)	Maximum Δ of uniform distribution about SMEAN(I). I is noise generator number (1, NNOISE).
TLEN (I)	The length of a terminal down time for terminal down event generator I. (I = (1, NTM)).
TLVAR (I)	The maximum Δ of uniform distribution about time of terminal down TLEN(I) generated by terminal down generator I. (I=(1, NTM))
TMEAN (I)	Mean time for occurrence of next terminal down by terminal down generator I where I = (1, NTM).
TMSENT (I)	Total message lengths sent per FUI number I where I = (1, NFUIS).

Figure 3-4 Definition of Non-GASP Variables (Continued).

Variable	Definition
TMVAR (I)	Maximum Δ of uniform distribution about TMEAN(I), the time of occurrence of next terminal down by terminal down generator I where I = (1,NTM).
TRES	The mean time of terminal I response where I = (1,NTR).
TRVAR (I)	Maximum Δ of uniform distribution about TRES(I), the response time of terminal I where I = (1,NTR).
XFUI	FUI in subroutine FUI to avoid labeling problem.

Table 3-4 Definition of Non-GASP Variables (Continued).

endless duration. The foreground transmission of a message is sent on a message-by-message basis, instead of a fixed non-varying sequence group. This scheme evaluates the impact of noise on the message. For separate evaluation, the message is separated into the command segment and the response segment. Failure can be recognized by either a non-responding terminal or a failure of the controller to acknowledge the response. A failure can also be determined by a "watch-dog" timer event that occurs before a given message response.

The occurrence of a failure event causes each terminal on the bus to fail. There are two failure modes: (1) permanent disable or (2) intermittent disable (that is, a terminal which recovers from a failure after a period of time). There is a response time associated with each message, which is uniformly distributed. Therefore, under this situation a controller cannot predict the length of time for transmitting a message. If the length of time for an average message transmission is less than the time to the start of the next FUI time, the controller will schedule its occurrence; however, this program has a built in feature which allows a delay of the next FUI fixed format message transmission until the transmission in progress is completed.

Simulation Objectives

The objectives of this simulation are to determine bus resource utilization for this approach of data handling, in addition to obtaining a measure of the impact of bus uncertainties on the data transportation timing. The bus uncertainties include variable response delay, bus noise and corresponding watch dog requirements,

AD-A097 375 MISSISSIPPI STATE UNIV MISSISSIPPI STATE ENGINEERING--ETC F/O 9/2
A STUDY OF AVIONICS TIME DIVISION MULTIPLEX BUS SIMULATION.(U)
DEC 80 M D CALHOUN, B KHATIRZAD AFOSR-80-0126
UNCLASSIFIED MSSU-EIRS-EE-81-1 AFOSR-TR-81-0311 NL

2 1/2 2
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and terminal failure and corresponding watch-dog requirements.

GASP IV Simulation Structure and Program Variables for MUXDB

In this program, there are three files used. Table 3-3 gives the definitions of the files and their associated characteristics for this simulation. File 1 is the event file as per GASP IV, File 2 stores the demand message arrival, and File 3 is the temporary storage file. Table 3-4 defines the non-GASP variables.

Main Program, Subroutine INTLC, and Subroutine EVNTS Description

Main Program

The main program sets the card reader number (NCRDR) and the card printer number (NPRNT) and subroutine GASP is called. The MUXSIM executive system is not used, therefore it is not necessary to use subroutines CHAIN, RESTOR, and GETCOM.

Subroutine INTLC

This subroutine is called via subroutine DATIN, in order to read in the simulation data cards and to set up the initial conditions from the input data cards or algebraic statements. The non-GASP user input data are printed out to make checking easier.

Subroutine EVNTS

Subroutine EVNTS sends control to one of the nine user written subroutines: WATCH, CTERM, TERMR, NOISES, NOISET, TRMUP, TRMDN, FUI, and DMARIV. The events of the simulation, in the order of their event code are:

100-Watch-Dog Timer (WATCH)
200-Call to Terminal (CTERM)
300-Terminal Response to a Call (TERMR)
400-Noise Start (NOISES)
500-Noise Stop (NOISET)
600-Terminal Recovery from Failure (TRMUP)
700-Terminal Failure (TRMDN)
800-Start a Fundamental Update Interval (FUI)
1000-Demand Message Arrival (DMARIV)

Subroutine WATCH (IDUM)

The "watch-dog" timer event is established in subroutine WATCH, which performs the following functions:

- (1) The program increases the number of timeouts (NT0) by one.
- (2) To set the requirement for testing a next message, it calls subroutine NXTMSG (2).

Subroutine CTERM (ITRM)

The call to terminal events is accomplished in subroutine CTERM, which performs the following functions:

- (1) This routine tests for noise hits on the data bus.
- (2) CTERM handles message arrival and processing at a terminal and produces terminal response.
- (3) CTERM prevents response if noise hits on both buses or if the terminal is down.
- (4) If there is no response inhibit, CTERM schedules a response.
- (5) CTERM increases the number of messages by one in order to record

the total number of messages sent during the simulation.

Subroutine TERM (ITRM)

Terminal response is accomplished in subroutine TERM, which performs the following functions:

- (1) This routine checks to see if the terminal response is valid; if it is not, the "watch-dog" timer is left alone.
- (2) It illuminates the "watch-dog" timer and calls the next message (NXTMSG (3)) subroutine to program the following message if the terminal response is valid.
- (3) If the terminal response is valid, but the "watch-dog" timer has expired, IRESE is increased by one.

Subroutine NOISES (IN)

The noise event process is accomplished in subroutine NOISES, which performs the following functions:

- (1) NOISES processes noise events and schedules the next noise event arrival and duration.
- (2) It establishes which buses are impacted.
- (3) This routine marks the message on the bus hit according to noise.
- (4) It increases the count of number of noise events on the proper buses by one.
- (5) NOISES establishes the end-of-the-noise event.
- (6) It calls the STAT subroutine to record the bus noise data.

Subroutine NOISET (IN)

Noise event termination is established in subroutine NOISET, which

performs the following functions:

- (1) This routine reduces the number of noise events on the proper buses by one to record the number of noise events left.
- (2) To record the bus noise statistics, it calls subroutine STAT.

Subroutine TRMUP (ITN)

Terminal recovery from failure is established in subroutine TRMUP, which performs only one function: it decreases the terminal up/down status IOK(IN) by one. The terminal is operational if the indicator is zero.

Subroutine TRMDN (ITN)

Terminal failure is established in subroutine TRMDN, which performs the following functions:

- (1) To indicate that the terminal is down, it sets the up/down status IOK(ITN) up one.
- (2) TRMDN schedules the next down event for this terminal.

Subroutine FUI (IFUI)

The start of the fundamental update interval is established in subroutine FUI, which performs the following functions:

- (1) If FUI = 1, it proceeds to compute the time of the next FUI (1) start to prevent the round-off error from accumulating and invalidating the results. It then produces the entire schedule for all FUI starts for the remainder of this frame and schedules the arrival of the FUI (1) for the next major frame. If FUI \neq 1, it omits the above and starts at this point.

(2) It sets the value for current FUI (ICURF) and sets the value of the fixed message number to be transmitted to 1, the message type to 1 to indicate a fixed message, and the JTT switch to I to enable the detection of the first message to be transmitted. It then calls subroutine NXTMSG (1) to schedule the next possible call to a terminal.

Subroutine DMARIV (IDM)

The arrival of a demand message is established in subroutine DMARIV, which performs the following functions:

- (1) DMARIV establishes the length, message number, and arrival time.
- (2) It files this information in File (2) or the arrived demand message file.
- (3) It schedules the next arrival of this demand message.

Subroutine OTPUT

Subroutine OTPUT is used to gain output in addition to the standard GASP IV summary report. OTPUT is called prior to subroutine SUMRY and is used to print out the following:

- (1) The number of timeouts or intervals of time between bus failure and bus recovery.
- (2) The number of valid readable responses lost to timeouts.
- (3) The number of bits on the left bus, right bus, and on both buses.
- (4) The total number of messages sent.
- (5) The total number of messages to hit on one bus or more.

Subroutine NXTMSG (IAM)

The subsequent call to a terminal scheduling is established in

subroutine NXTMSG, which performs the following functions:

- (1) If it is the start of FUI and the bus is busy either waiting on transmission or a transmission is in progress, it returns to the subroutines that have been called.
- (2) NXTMSG branches on message type to 3 or 5.
- (3) It collects a histogram and statistics information for the first fixed message in FUI.
- (4) If possible, it schedules a fixed message transmission and a companion "watch-dog" timer event. It then updates the message number by one, sets the IBUSY flag to busy (one) and increases the message count by one, and returns.
- (5) For a demand message, NXTMSG tests to see if there is time to send a demand message; if there is, it schedules a call to a terminal and schedules a companion "watch-dog" terminal event, sets the busy flag, and increases the message count by one.
- (6) If a demand message cannot be scheduled due to lack of time to achieve the transmission, this routine sets the busy flag to free and establishes the end of demand message transmission for this FUI. It then returns to the subroutines that have been called.

Subroutine STAT (ILBUS, IRBUS)

Statistics of time-persistent variables for noise on the left bus, right bus, and/or both are collected for noise events on the bus; this is the only function that subroutine STAT performs.

Function RNXT (RMEN, RVAR, ISTRM)

This routine computes the delta time for the next event arrival

for a given event generation, which is based on a uniform distribution about the mean, using the random number stream designated by the user. RNXT performs the following functions:

- (1) For calling the next arrival of the event in question, RNXT establishes the random number stream.
- (2) For the event in question, it establishes the uniform upper and lower bound.
- (3) By using the uniform distribution, RNXT computes the arrival time.

Simulation Report

The MUXDB outputs are given in the following section, with particular emphasis on some of the more common data outputs:

Figure 3-15 shows the input data echo check, provided by subroutine DATIN. Figure 3-16 presents the user input cards; Figure 3-17 is similar to Figure 3-16, but is given in more detail. The printout of the files that are obtained at the end of subroutine DATIN (Time 0) is shown in Figure 3-18, and a partial printout of the event tracing which is obtained from subroutine MONTR is shown in Figure 3-19.

Figure 3-20 is the GASP IV summary report. The statistics that are collected using subroutine COLCT are presented; these show that the interval time between the start of an actual message and the response of the last demand message is, on the average, .016 of the time unit with the standard deviation of .0026 of the time unit. These values are based on 1,000 observations. The minimum and maximum values observed for the time interval between the start of an

actual message and the end of the response of the fixed message are .011 and .022 of the time unit, respectively. The average interval time between the start of an actual message and the end of the last demand message is .088 of the time unit, based on 1,000 observations.

The next set of statistics on the summary report is for the data collected in subroutine TIMST; this shows that the utilization of noises on the right bus is .018 of the time unit over the total simulation time of 1,000 of the time unit.

Statistics regarding the use of files are shown in Figure 3-21. For example, on the average, there are 23.3 events in file 1. A maximum of 32 events are stored in the event file.

In Figure 3-22, statistical information for the fixed message in FUI is given. The figure shows that 91.4% of the first fixed messages, based on 10,001 observations, has the starting time less than or equal to .014 of the time unit.

```

SIMULATION PROJECT NUMBER 5 HY BEMR002
DATE 4/21/80 RUN NUMBER 1 OF 1
LLSUP=0000000000000000 GASP IV VERSION 18MAY74

NNCL= 2 NNSTA= 3 NNHIS= 5000 NNPRM= 0 NNPLT= 0 NNSTR= 5 NNTRY= 100
NNAT= 3 NNFIL= 3 NNSET= 0 NNEOS= 0 NFLAG= 0

COLCT NO. 1 LLABC=IFFL
COLCT NO. 2 LLABC=ITFL

TIMST NO. 1 LLABT=NRIRUS I.C.= .0000
TIMST NO. 2 LLABT=NLIRUS I.C.= .0000
TIMST NO. 3 LLABT=NRIRUS I.C.= .0000
TIMST NO. 4 LLABT=NLIRUS I.C.= .0000

MISTO NO. 1 LLABH=JIT MNCEL= 10 MHLOW= .0000 MHMID= .2000-02

PKRKE= ( 0)
TIMN= ( 3)
MSTOPE= 1 JJBEG= 1 JICRD= 0 TTBEQ= .0000 TTFIN= .1000-04
JJCLR= 1 JJCL= 43163 19240 45212 15893
JJELL= 1
JJSED= 65397

```

Figure 3-15 GASP IV Input Data Echo Check for MUXDB Simulation.

[illegible]

Figure 3-16 User Input Data for GASP IV in MUXDB Simulation.

INTERMEDIATE RESULTS

```

CURRENT EVENT.....TNOW=.5000-02
NEXT EVENT.....TTNEX=.2017+03 .1000+01
CURRENT EVENT.....TNOW=.2100-01
NEXT EVENT.....TTNEX=.2100-01 .1000+01
CURRENT EVENT.....TNOW=.1644-01
NEXT EVENT.....TTNEX=.3010+03 .1000+01
CURRENT EVENT.....TNOW=.2100-01
NEXT EVENT.....TTNEX=.1000+03 .1000+01
CURRENT EVENT.....TNOW=.9842-01
NEXT EVENT.....TTNEX=.1001+04 .0000
CURRENT EVENT.....TNOW=.1000+00
NEXT EVENT.....TTNEX=.3020+03 .7000+01
CURRENT EVENT.....TNOW=.1000+00
NEXT EVENT.....TTNEX=.3020+03 .7000+01
CURRENT EVENT.....TNOW=.1024+00
NEXT EVENT.....TTNEX=.1005+04 .0000
CURRENT EVENT.....TNOW=.1024+00
NEXT EVENT.....TTNEX=.1026+00 .0000
CURRENT EVENT.....TNOW=.1026+00
NEXT EVENT.....TTNEX=.1003+04 .0000
CURRENT EVENT.....TNOW=.1026+00
NEXT EVENT.....TTNEX=.1050+00 .0000
CURRENT EVENT.....TNOW=.1050+00
NEXT EVENT.....TTNEX=.2016+03 .1000+01
CURRENT EVENT.....TNOW=.1050+00
NEXT EVENT.....TTNEX=.1210+00 .1000+01
CURRENT EVENT.....TNOW=.1109+00
NEXT EVENT.....TTNEX=.3010+03 .1000+01
CURRENT EVENT.....TNOW=.1109+00
NEXT EVENT.....TTNEX=.1210+00 .1000+01
CURRENT EVENT.....TNOW=.1169+00
NEXT EVENT.....TTNEX=.2010+03 .2010+03
CURRENT EVENT.....TNOW=.1169+00
NEXT EVENT.....TTNEX=.1330+00 .2010+03
CURRENT EVENT.....TNOW=.1223+00
NEXT EVENT.....TTNEX=.3010+03 .2010+03
CURRENT EVENT.....TNOW=.1223+00
NEXT EVENT.....TTNEX=.1330+00 .2010+03
CURRENT EVENT.....TNOW=.1283+00
NEXT EVENT.....TTNEX=.2020+03 .2050+03
CURRENT EVENT.....TNOW=.1283+00
NEXT EVENT.....TTNEX=.1423+00 .2050+03
CURRENT EVENT.....TNOW=.1371+00
NEXT EVENT.....TTNEX=.3020+03 .2050+03
CURRENT EVENT.....TNOW=.1371+00
NEXT EVENT.....TTNEX=.1423+00 .2050+03
CURRENT EVENT.....TNOW=.1421+00
NEXT EVENT.....TTNEX=.2010+03 .2030+03
CURRENT EVENT.....TNOW=.1421+00
NEXT EVENT.....TTNEX=.1581+00 .2030+03
CURRENT EVENT.....TNOW=.1553+00
NEXT EVENT.....TTNEX=.3010+03 .2030+03
CURRENT EVENT.....TNOW=.1553+00
NEXT EVENT.....TTNEX=.1581+00 .2030+03
CURRENT EVENT.....TNOW=.1974+00
NEXT EVENT.....TTNEX=.1004+04 .0000
CURRENT EVENT.....TNOW=.2000+00
NEXT EVENT.....TTNEX=.8030+03 .7000+01
CURRENT EVENT.....TNOW=.2000+00

```

Figure 3-19 Output from Subroutine MONTR, showing Event Tracing for MUXDB.

NUMBER OF VALID READABLE RESPONSES LOST TO TIMEOUT = 0
 NUMBER OF TIMEOUTS = 0
 NUMBER OF HITS ON LEFT BUS = 248 RIGHT BUS = 166 BOTH BUSES = 211
 TOTAL NUMBER OF MESSAGES SENT = 126834
 TOTAL NUMBER OF MESSAGES HIT ON AT LEAST ONE BUS = 1147

GASP SUMMARY REPORT

SIMULATION PROJECT NUMBER 5 HY HEM000Z

DATE 4/ 21/ 80 RUN NUMBER 1 OF 1

CURRENT TIME = .1000+04

STATISTICS FOR VARIABLES BASED ON OBSERVATION		CV		MINIMUM		MAXIMUM		CUR. VALUE	
MEAN	STD DEV	SD OF MEAN							
FILE	.1620-01	.2558-02	.8089-04	.1579+00	.1190-01	.2295-01	.1000		
FILE	.8836-01	.2553-01	.8072-03	.2889+00	.1131-01	.1782+00	.1000		
STATISTICS FOR TIME-PERSISTENT VARIABLES									
MEAN	STD DEV	MINIMUM	MAXIMUM	TIME	INTERVAL				
RTBUS	.1449+00	.0000	.4000+01		.1000+04	.0000			
RTBUS	.1238+00	.0000	.3000+01		.1000+04	.1000+01			
RTBUS	.8833-01	.0000	.3000+01		.1000+04	.0000			

Figure 3-20 GASP Summary Report for MUXDB.


```

**CASP FILE STORAGE AREA DUMP AT TIME .1000+0000
MAXIMUM NUMBER OF ENTRIES IN FILE STORAGE AREA .30

PRINTOUT OF FILE NUMBER 1
INOM = .100+00
QTIME = .10 0.00
TIME PERIOD FOR STATISTICS .1000+00
AVERAGE NUMBER IN FILE 2.4228
STANDARD DEVIATION 1.6210
MAXIMUM NUMBER IN FILE 10

FILE CONTENTS
ENTRY 1 1000+00
ENTRY 2 1000+00
ENTRY 3 1000+00
ENTRY 4 1000+00
ENTRY 5 1000+00
ENTRY 6 1000+00
ENTRY 7 1000+00
ENTRY 8 1000+00
ENTRY 9 1000+00
ENTRY 10 1000+00
ENTRY 11 1000+00
ENTRY 12 1000+00
ENTRY 13 1000+00
ENTRY 14 1000+00
ENTRY 15 1000+00
ENTRY 16 1000+00
ENTRY 17 1000+00
ENTRY 18 1000+00
ENTRY 19 1000+00
ENTRY 20 1000+00
ENTRY 21 1000+00
ENTRY 22 1000+00
ENTRY 23 1000+00
ENTRY 24 1000+00
ENTRY 25 1000+00
ENTRY 26 1000+00
ENTRY 27 1000+00
ENTRY 28 1000+00
ENTRY 29 1000+00
ENTRY 30 1000+00

PRINTOUT OF FILE NUMBER 2
INOM = .1000+00
QTIME = .1000+00
TIME PERIOD FOR STATISTICS .1000+00
AVERAGE NUMBER IN FILE 2.4228
STANDARD DEVIATION 1.6210
MAXIMUM NUMBER IN FILE 10

FILE CONTENTS
ENTRY 1 1000+01
ENTRY 2 1000+01
ENTRY 3 1000+01
ENTRY 4 1000+01
ENTRY 5 1000+01
ENTRY 6 1000+01
ENTRY 7 1000+01
ENTRY 8 1000+01
ENTRY 9 1000+01
ENTRY 10 1000+01
ENTRY 11 1000+01
ENTRY 12 1000+01
ENTRY 13 1000+01
ENTRY 14 1000+01
ENTRY 15 1000+01
ENTRY 16 1000+01
ENTRY 17 1000+01
ENTRY 18 1000+01
ENTRY 19 1000+01
ENTRY 20 1000+01
ENTRY 21 1000+01
ENTRY 22 1000+01
ENTRY 23 1000+01
ENTRY 24 1000+01
ENTRY 25 1000+01
ENTRY 26 1000+01
ENTRY 27 1000+01
ENTRY 28 1000+01
ENTRY 29 1000+01
ENTRY 30 1000+01

PRINTOUT OF FILE NUMBER 3
INOM = .1000+00
QTIME = .9999+03
TIME PERIOD FOR STATISTICS .1000+00
AVERAGE NUMBER IN FILE 2.4228
STANDARD DEVIATION 1.6210
MAXIMUM NUMBER IN FILE 10

FILE CONTENTS
ENTRY 1 1000+02
ENTRY 2 1000+02
ENTRY 3 1000+02
ENTRY 4 1000+02
ENTRY 5 1000+02
ENTRY 6 1000+02
ENTRY 7 1000+02
ENTRY 8 1000+02
ENTRY 9 1000+02
ENTRY 10 1000+02
ENTRY 11 1000+02
ENTRY 12 1000+02
ENTRY 13 1000+02
ENTRY 14 1000+02
ENTRY 15 1000+02
ENTRY 16 1000+02
ENTRY 17 1000+02
ENTRY 18 1000+02
ENTRY 19 1000+02
ENTRY 20 1000+02
ENTRY 21 1000+02
ENTRY 22 1000+02
ENTRY 23 1000+02
ENTRY 24 1000+02
ENTRY 25 1000+02
ENTRY 26 1000+02
ENTRY 27 1000+02
ENTRY 28 1000+02
ENTRY 29 1000+02
ENTRY 30 1000+02

```

Figure 3-21 Statistics Regarding
the Use of Files for MUXDB.

CHAPTER IV

A SIMULATION EXAMPLE IN VARIOUS LANGUAGES

In this chapter, a single queue, single server simulation example is discussed in four languages; they are: FORTRAN, GASP IV, GPSS II, and SIMSCRIPT II.

The primary goal of this program is to simulate a single queue, single server system. In this thesis, the server is analogous to the terminal or bus controller and the queue is the message queue stored in the controller. The service unit is the data bus itself. The arrival of a message on a bus is exponentially distributed with mean time of five minutes and the service time is also exponentially distributed with mean time of four minutes. This program is simulated for eight hours (simulation time). The second goal is to use FORTRAN to implement the model to realize impropriety of the language for simulation. Figure 4-1 shows the general structure of this problem in the FORTRAN language.

A Description of the FORTRAN Simulation Program

The FORTRAN Simulation Program performs the following functions:

- (1) FORTRAN initializes all variables and parameters and sets the total time of simulation.
- (2) This program checks to see whether the simulation time is over; if it is over, it calls the proper event to be executed.
- (3) FORTRAN calculates the average queue length and the average service time for all runs.

The flow chart of subroutines ARRIVAL, SERVICE, and DEPARTURE is given in Figures 4-2, 4-3, and 4-4, respectively. The printout of this program is given in Figure 4-5.

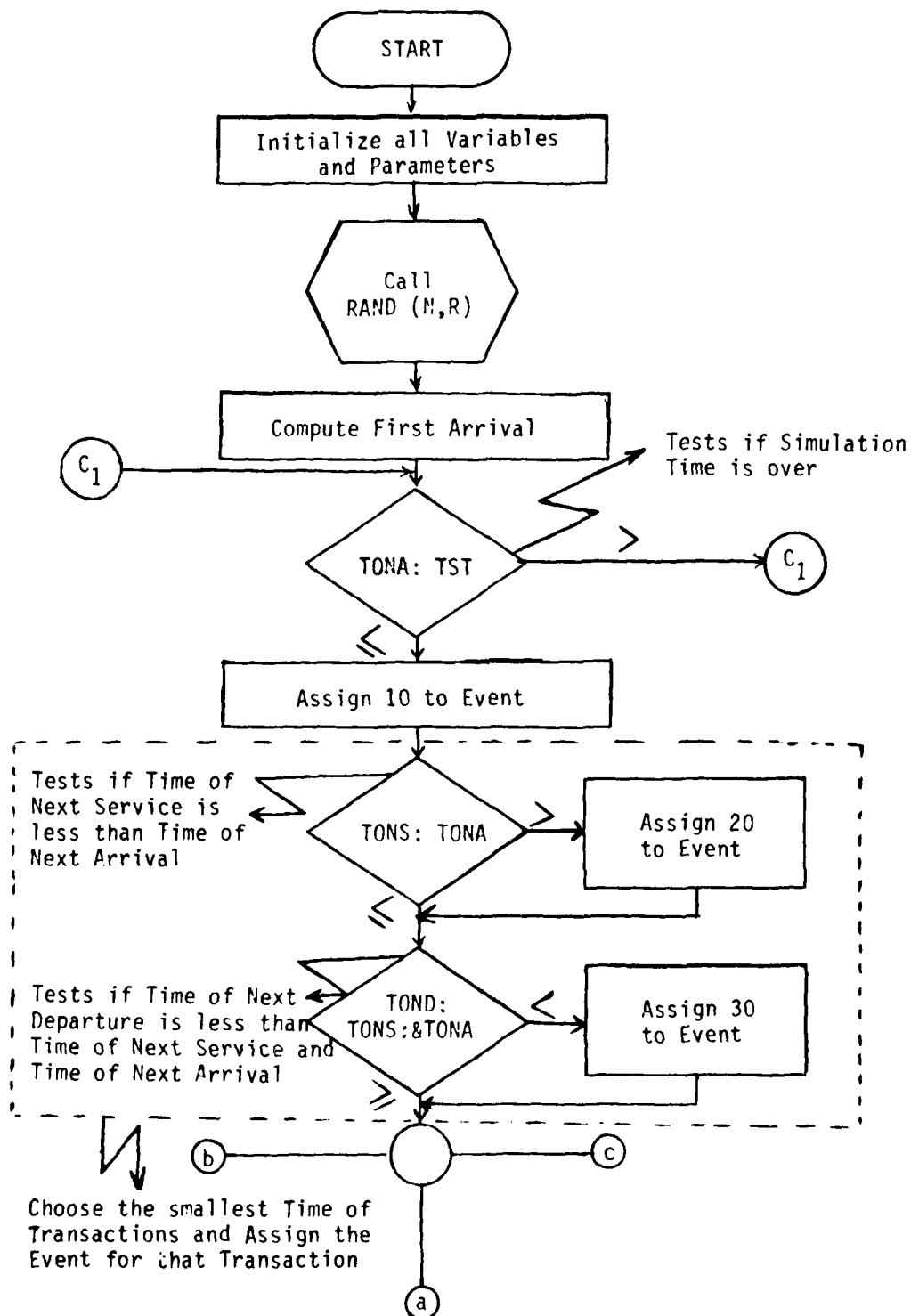


Figure 4-1 Flow Chart of Single Queue, Single Server in the FORTRAN Program.

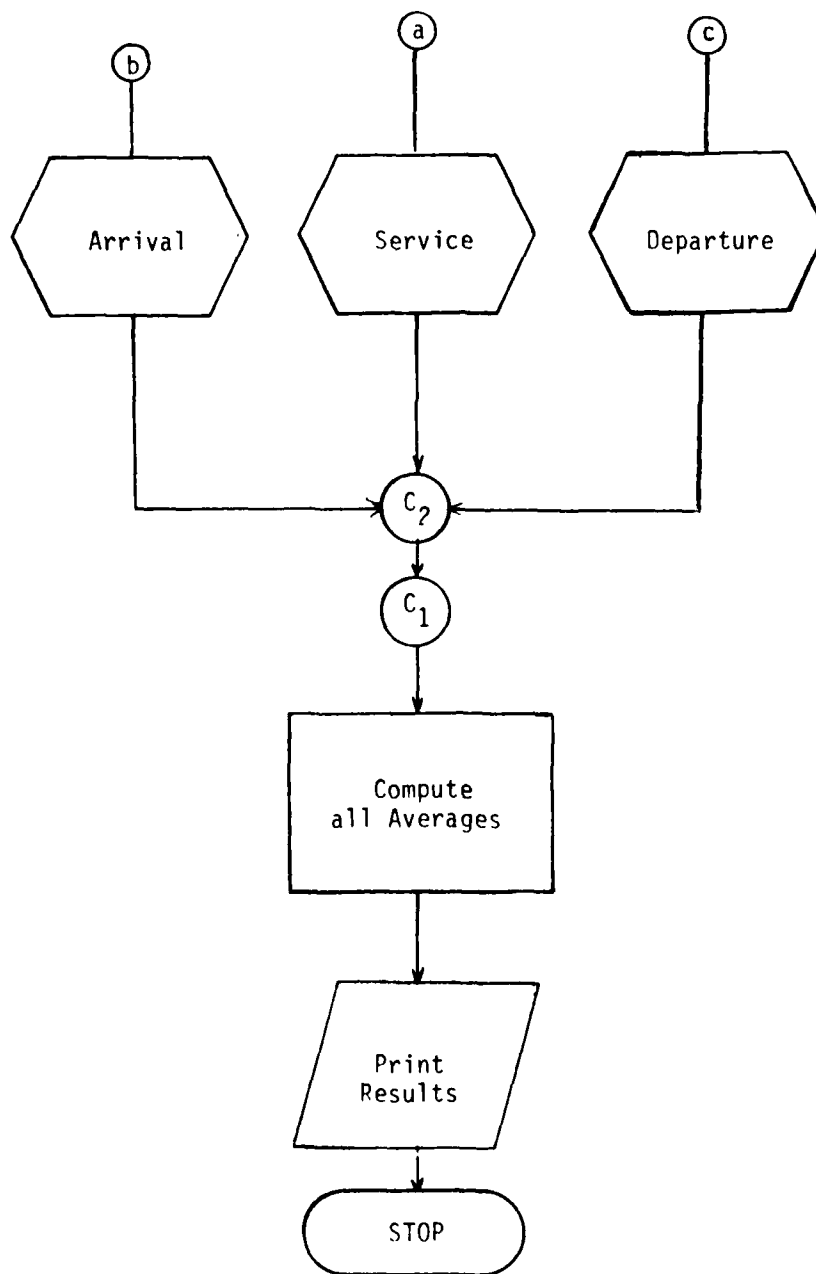


Figure 4-1 Flow Chart of Single Queue, Single Server in the FORTRAN Program (Continued).

Subroutine ARRIVAL

The parameters received by this subroutine are: Time of Next Arrival (TONA), Time of Next Service (TONS), Clock, Time of Last Queue Change (TOLQC), Queue Length (IQ), Total Queue Length (TIQ), Facility Status (IFS), Sum of Queue Length (SQQL), Expected Arrival Time (EXPA), and Seed for Random Number Generator (N).

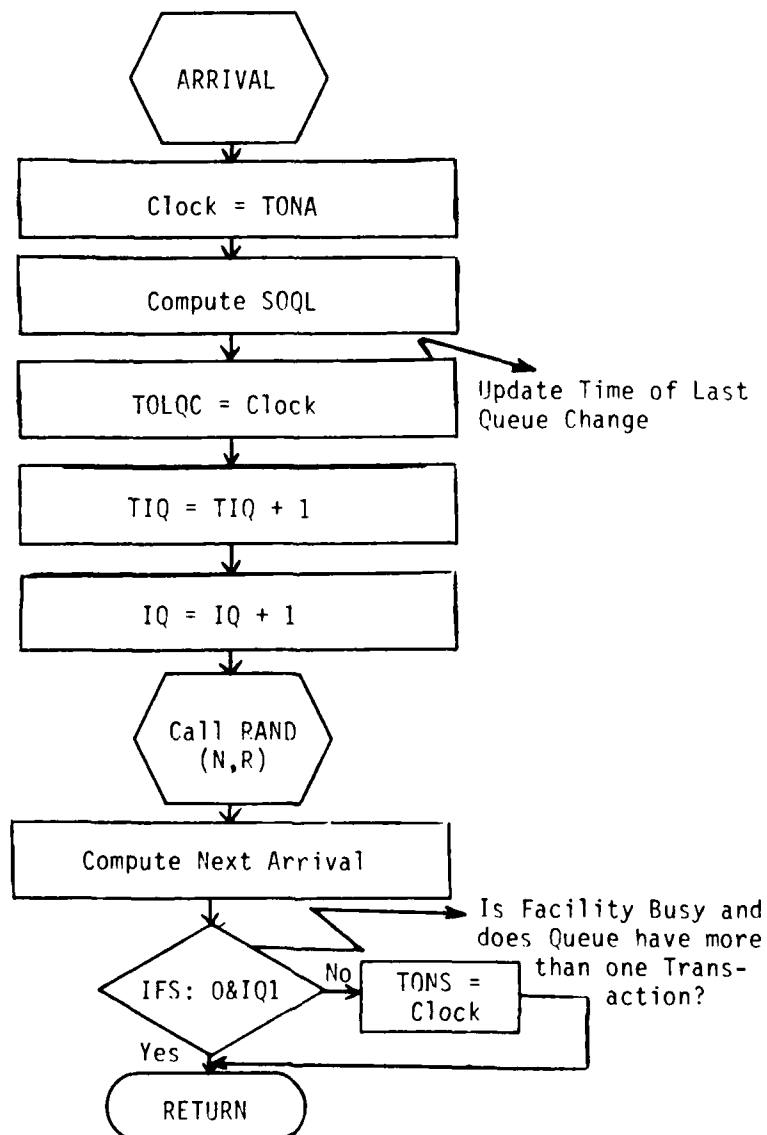


Figure 4-2 Flow Chart of Subroutine ARRIVAL.

Subroutine SERVICE

The parameters received by this subroutine are: Time of Next Service (TONS), Time of Next Departure (TOND), Clock, Time of Last Queue Change (TOLQC), Queue Length (IQ), Sum of Queue Length (SOQL), Sum of Service Time (SOST), Expected Service Time (EXPS), and Seed for Random Number Generator (N).

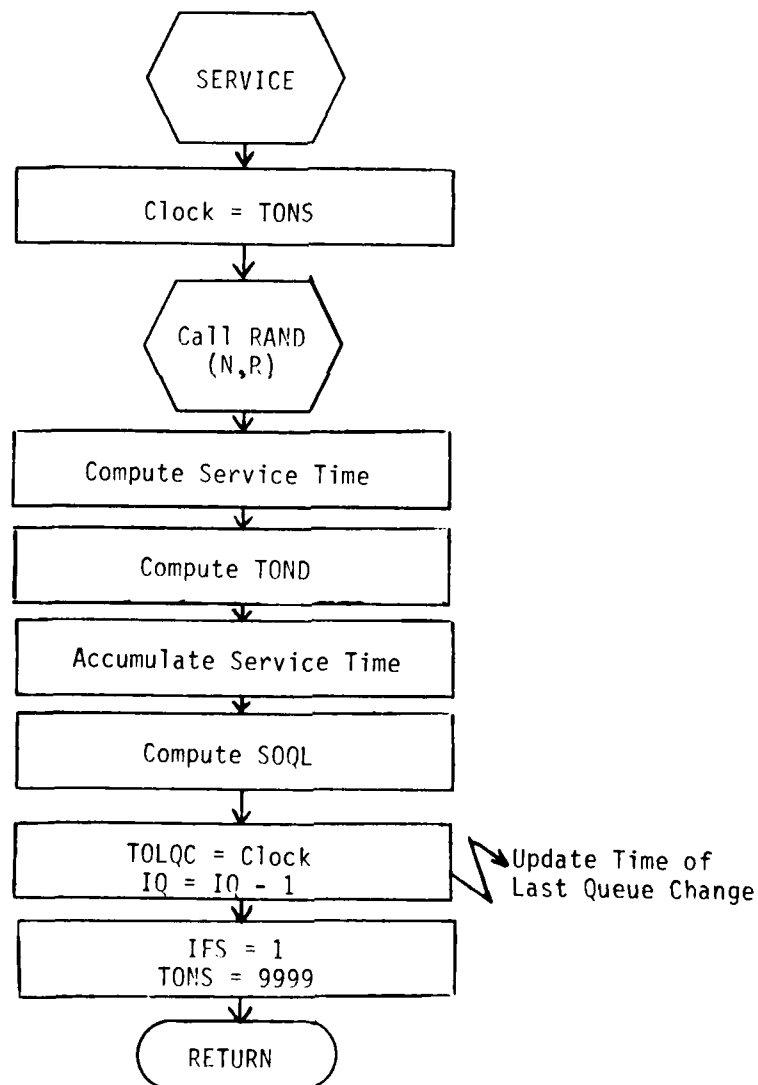


Figure 4-3 Flow Chart of Subroutine SERVICE.

Subroutine DEPARTURE

The parameters received by this subroutine are: Time of Next Departure (TOND), Time of Next Service (TONS), Clock, Queue Length (IQ), and Facility Status (IFS).

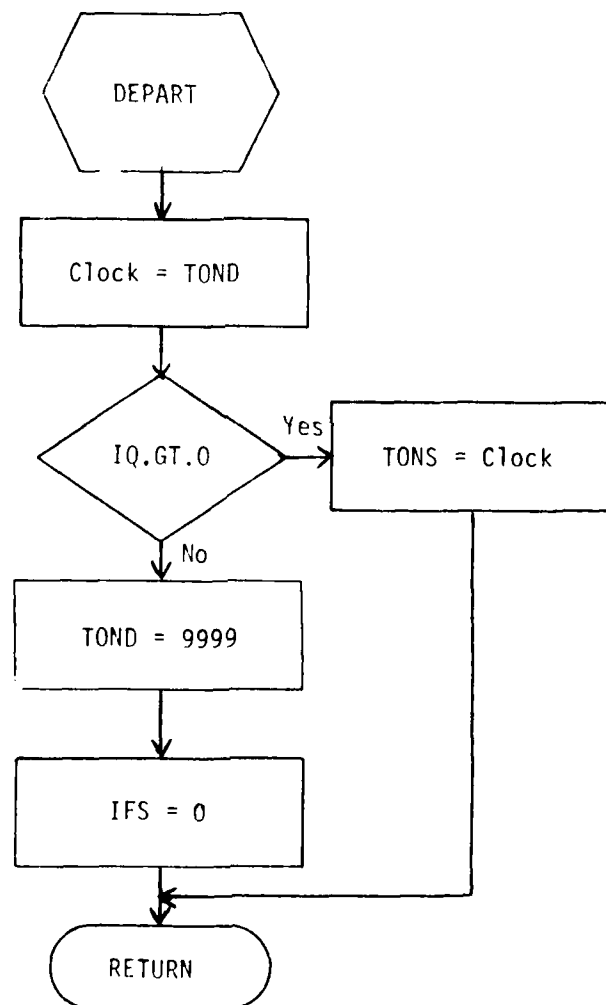


Figure 4-4 Flow Chart of Subroutine DEPARTURE.

S I M U L A T I O N S T A T I S T I C S	
AVE QUEUE LENGHT	AVE UTILIZATION
.9970	.7062
4.2776	.9702
1.4635	.7174
2.0633	.7982
3.7672	.7320
2.9433	.6660
.7757	.5398
1.3136	.6600
.7144	.5906
1.0702	.6919
4.4136	.8949
2.3680	.8013
5.0661	.8017
1.7005	.7697
2.3255	.8646
1.8739	.7695
2.8511	.8537
.5753	.6330
1.8114	.7047
.9342	.6452
1.9664	.7915
3.4616	.8869
3.2761	.8369
4.9629	.9315
2.2642	.7723
.9359	.6947
2.8954	.9164
1.5390	.7317
2.6189	.8787
3.4771	.9187
1.1896	.7540
2.0946	.7690
.8668	.6132
.7945	.7569
6.4977	.6525
1.1461	.7956

Figure 4-5 Printout of the FORTRAN Simulation Program.

1.3156	.6212
.7018	.6884
17.2642	.9922
1.5735	.7029
3.5791	.6353
2.7486	.6363
1.0270	.6779
2.3770	.6172
1.3752	.6719
.3362	.6226
10.1216	.9340
3.2814	.9179
1.5017	.7428
5.0549	.9389
2.1151	.7273
3.6910	.6481
1.1218	.6756
1.6242	.7386
3.6657	.8750
10.3328	.6785
.7712	.7332
1.1313	.6622
2.8800	.6844
1.6529	.7562
1.2291	.8015
1.5557	.7025
3.6046	.6579
2.3624	.6465
.5565	.5564
3.4269	.9500
1.3291	.7119
1.6151	.7523
.5944	.6256
1.5605	.7602
1.1294	.7944
1.0742	.6635
1.1469	.7552
.5041	.6212
1.0667	.7234
1.5027	.6525

Figure 4-5 (Continued).

.7096	.7530
1.3979	.7234
1.9040	.7235
4.5719	.7952
1.0405	.7503
.6499	.6771
2.9232	.9330
2.1061	.6452
1.1514	.7253
3.5295	.6784
.7528	.6782
2.0771	.7967
.4917	.5779
1.1886	.7049
.7551	.5948
.6132	.6291
.5109	.6616
2.8871	.7849
1.1541	.6342
1.5171	.7629
5.5250	.6621
2.0046	.7952
1.6616	.7940
2.9341	.6749
AVE QUEUE LENGHT FOR ALL RUNS =	2.4085
AVE UTILIZATION FOR ALL RUNS =	.7644

W.F.S.

Figure 4-5 (Continued).

GASP IV Simulation Program

The objective of this program is to simulate a Single Queue, Single Server system by using the GASP IV simulation language. The arrival of a message is exponentially distributed with mean time five minutes and the service time is exponentially distributed with mean time four minutes.

A Description of the GASP IV Simulation Program

The GASP IV Simulation Program is divided into the Main Program and four subroutines; they are: EVNTS, APR, BEGS, and FINS.

There are three files used for this program. File 1 is the event file, File 2 is for queueing the message, and File 3 is for service facility. The flow chart of this program is shown in Figure 4-6.

Main Program

The Main Program sets the card reader number (NCRDR) and the card printer number (NPRNT) and subroutine GASP is called.

Subroutine EVNTS

Subroutine EVNTS sends control to one of the three user written subroutines: APR, BEGS, and FINS. The events of the simulation, in the order of their event code are:

20 - Arrival (ARR)

30 - Begin Service (BEGS)

40 - Finish Service (FINS)

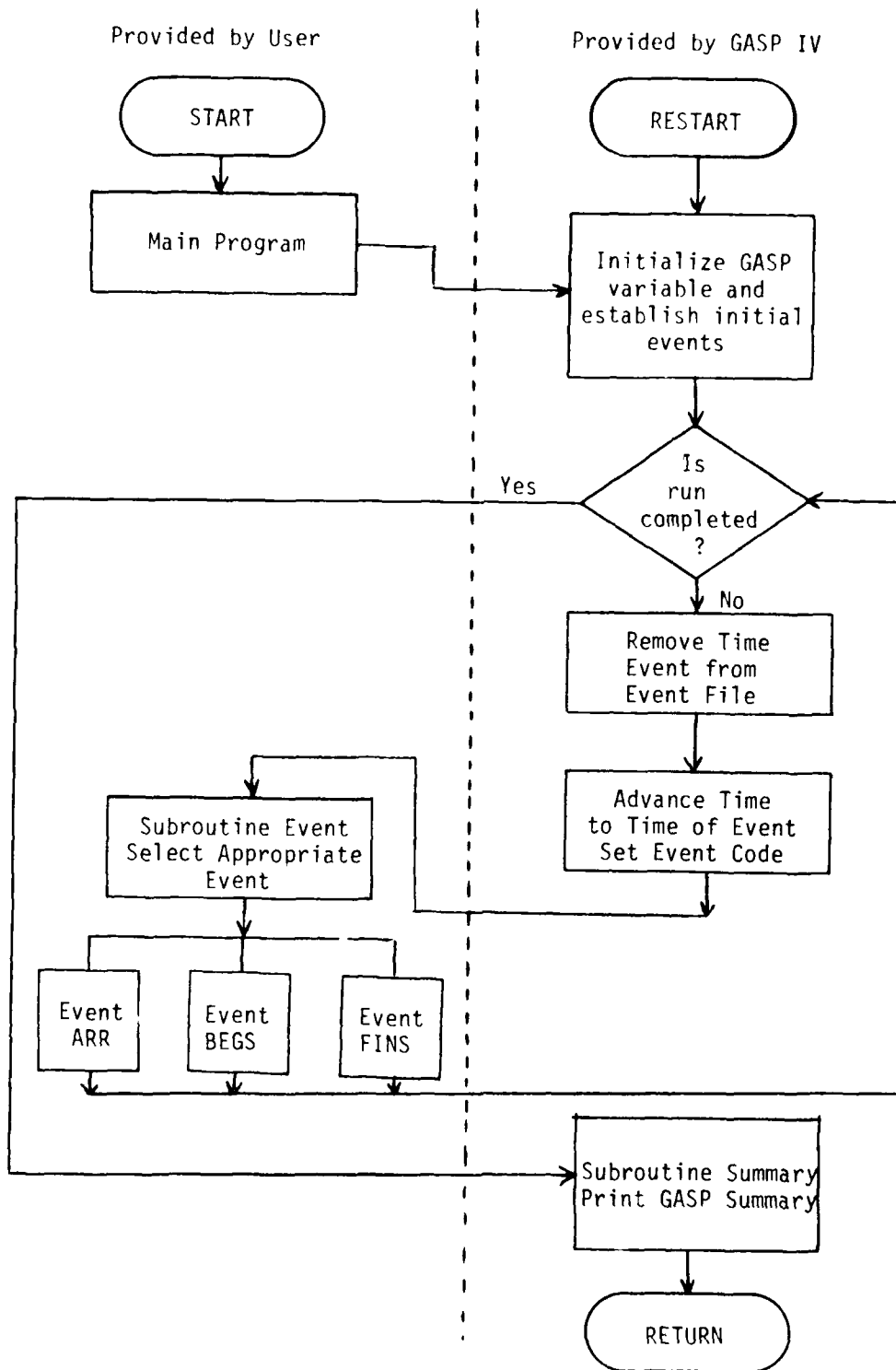


Figure 4-6 Flow Chart for GASP Single Queue, Single Server.

Subroutine ARR

The event arrival process of a message is accomplished in subroutine ARR. This subroutine records the arrival of a message and schedules the next arrival of a message. ARR also tests to see whether there are any messages in the Queue and if the Service Facility is free. If there are no messages in the Queue and the Service Facility is free, it schedules another arrival of a message; otherwise, ARR returns to subroutine BEGS.

Subroutine BEGS

The begin event is established in subroutine BEGS. This subroutine removes a message from the Queue, puts the message in the Service Facility, and schedules the finishing service.

Subroutine FINS

The finish event process is accomplished in subroutine FINS. This subroutine removes a message from the Service Facility and schedules begin service if there are any messages in the Queue.

Simulation Report

Figure 4-7 presents the input data echo check, provided by subroutine DATIN and a printout of the files that are obtained at the end of subroutine DATIN.

Figure 4-8 is the GASP IV summary report. On the average, there are 1.83 events in file 1, with the standard deviation of .38 minutes. File 2 shows the average Queue length is 2.85 minutes, with the standard deviation of 2.95 minutes. The max-

imum number of messages in the Queue is 12. File 3 shows that the average utilization time is .83 minutes, with the standard deviation time of one minute. The maximum number of messages in the Service Facility is one.

SIMULATION PROJECT NUMBER 0 PY BEHROOZ
 DATE 5/22/1980 RUN NUMBER 1 OF 1
 LLSUP=0000000000000000 GASP IV VERSION 18MAY72

ANCLT=	0	NNSTZ=	0	NNPRM=	0	NNPLT=	0	NNSTR=	1	NNTRY=	15
NNATR=	(1)	NNFIL=	1	NNSED=	0	NNES=	0	NNFLAG=	0		
KKRKR=	(1)										
IINN=	(1)										
PSTOF=	1	JJCLK=	1	JJBTG=	1	JTBEG=	0.000	JTFIN=			
JJFIL=	4976										
IISSE=											0.4800+03

**GASP FILE STORAGE AREA DUMP AT TIME 0.0000 **

MAXIMUM NUMBER OF ENTRIES IN FILE STORAGE AREA = 1

PRINTOUT OF FILE NUMBER 1
 INOW = 0.0000
 OCTIME = 0.0000

FILE CONTENTS

ENTRY 1 = 0.2000+01 0.1000+01

PRINTOUT OF FILE NUMBER 2
 INOW = 0.0000
 OCTIME = 0.0000

THE FILE IS EMPTY

PRINTOUT OF FILE NUMBER 3
 INOW = 0.0000
 OCTIME = 0.0000

THE FILE IS EMPTY

Figure 4-7 Input Data Echo Check and Printout of Files at Time 0 for Single Bus Example.

```

**GASP SUMMARY REPORT**
SIMULATION PROJECT NUMBER 0 BY BEHROOZ
DATE 5/ 22/ 1980 RUN NUMBER 1 OF 1
CURRENT TIME = .4800+03

**GASP FILE STORAGE AREA DUMP AT TIME .4800+03**
MAXIMUM NUMBER OF ENTRIES IN FILE STORAGE AREA = 15

PRINTOUT OF FILE NUMBER 1
TNOW = .4800+03
QOTIM = .4747+03
TIME PERIOD FOR STATISTICS .4800+03
AVERAGE NUMBER IN FILE 1.8300
STANDARD DEVIATION .3757
MAXIMUM NUMBER IN FILE 2
FILE CONTENTS
ENTRY 1 = .4934+03 .1000+01

PRINTOUT OF FILE NUMBER 2
TNOW = .4800+03
QOTIM = .4726+03
TIME PERIOD FOR STATISTICS .4800+03
AVERAGE NUMBER IN FILE 2.8523
STANDARD DEVIATION 2.9598
MAXIMUM NUMBER IN FILE 12
THE FILE IS EMPTY

PRINTOUT OF FILE NUMBER 3
TNOW = .4800+03
QOTIM = .4747+03
TIME PERIOD FOR STATISTICS .4800+03
AVERAGE NUMBER IN FILE .8300
STANDARD DEVIATION .3757
MAXIMUM NUMBER IN FILE 1
THE FILE IS EMPTY

```

Figure 4-8 GASP IV Summary Report for Single Bus Example.

GPSS II Simulation Program

The objective of this program is to simulate a single queue, single server system by using the GPSS II simulation language. The arrival of a message is exponentially distributed with mean time five minutes and the service time is exponentially distributed with mean time four minutes.

A Description of the GPSS II Simulation Program

The GPSS II Simulation Program performs the following functions:

- (1) This program creates the arrival of a message by using the GENERATE block.
- (2) GPSS II records the entries of messages in the QUEUE block.
- (3) It begins service on the facility in the SEIZE block.
- (4) The message uses the service facility in the ADVANCE block.
- (5) The message frees the service facility in the RELEASE block.
- (6) The simulation terminates when simulation time is over.

The block diagram for this program is given in Figure 4-9.

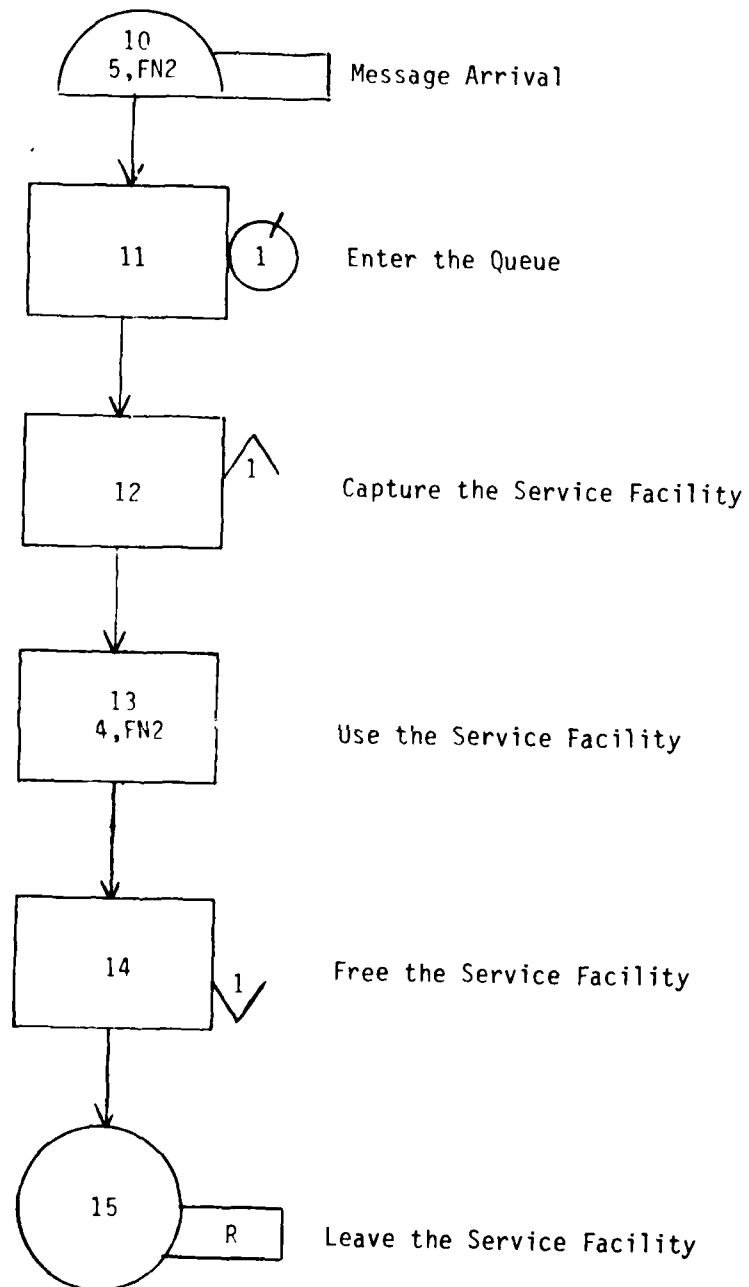


Figure 4-9 The Block Diagram for GPSS II Simulation Program.

Simulation Report

Figure 4-10 presents the GPSS II printout. The second and third lines of this printout are the transaction counts for all blocks. For example, at Block 2, 5 indicates the number of transactions currently at the block and 53 is the total number of transactions that entered the block.

Line six gives the following information: the facility number (1), the average utilization time (.76 minutes), the number of times the facility was used (48), and the average time for each transaction (3.37 minutes).

Line nine gives statistics for the Queue, measured by the block diagram. This includes the following:

- (1) the number of the Queue used in the model (1)
- (2) the largest number of messages in the Queue (6)
- (3) the average number of messages in the Queue (1.45)
- (4) the total number of messages entering in the Queue (53)
- (5) the number of messages that have no waiting time (12)
- (6) the percentage of messages that have no waiting time (22.64%)
- (7) the average length of time that messages spent in the Queue (5.79 minutes)
- (8) the average waiting time in the Queue (7.49 minutes), excluding the messages that do not have waiting time.
- (9) there is no table (0)
- (10) the current value of the Queue content (5)

SIMSCRIPT II Simulation Program

The objective of this program is to simulate a Single Queue, Single Server system by using the SIMSCRIPT II simulation language. The arrival of a message is exponentially distributed with mean time five minutes and the service time is exponentially distributed with mean time four minutes.

A Description of the SIMSCRIPT II Simulation Program

The SIMSCRIPT II Simulation Program is divided into five parts; they are: Preamble, Main Program, Event Arrival, Event Departure, and Event Stop Simulation.

The Preamble defines every event, including Service Time, Queue Change, and Sum of Queue, as variables. It also defines the status of the model and all integer variables.

The Main Program schedules the arrival of a message, the desired number of hours for the simulation run, and the start of the simulation.

The Event Arrival schedules the arrival of a message and creates a message. It files the message in the Queue and records the total number of entries. The Event Arrival computes the sum of the Queue length and schedules the departure of the message. Figure 4-11 shows the flow chart for Event Arrival.

The Event Departure lets the status be idle if the Queue is empty; otherwise, it removes the first message from the Queue and updates the last Queue change. The Event Departure destroys the message and determines the service time. It also schedules the

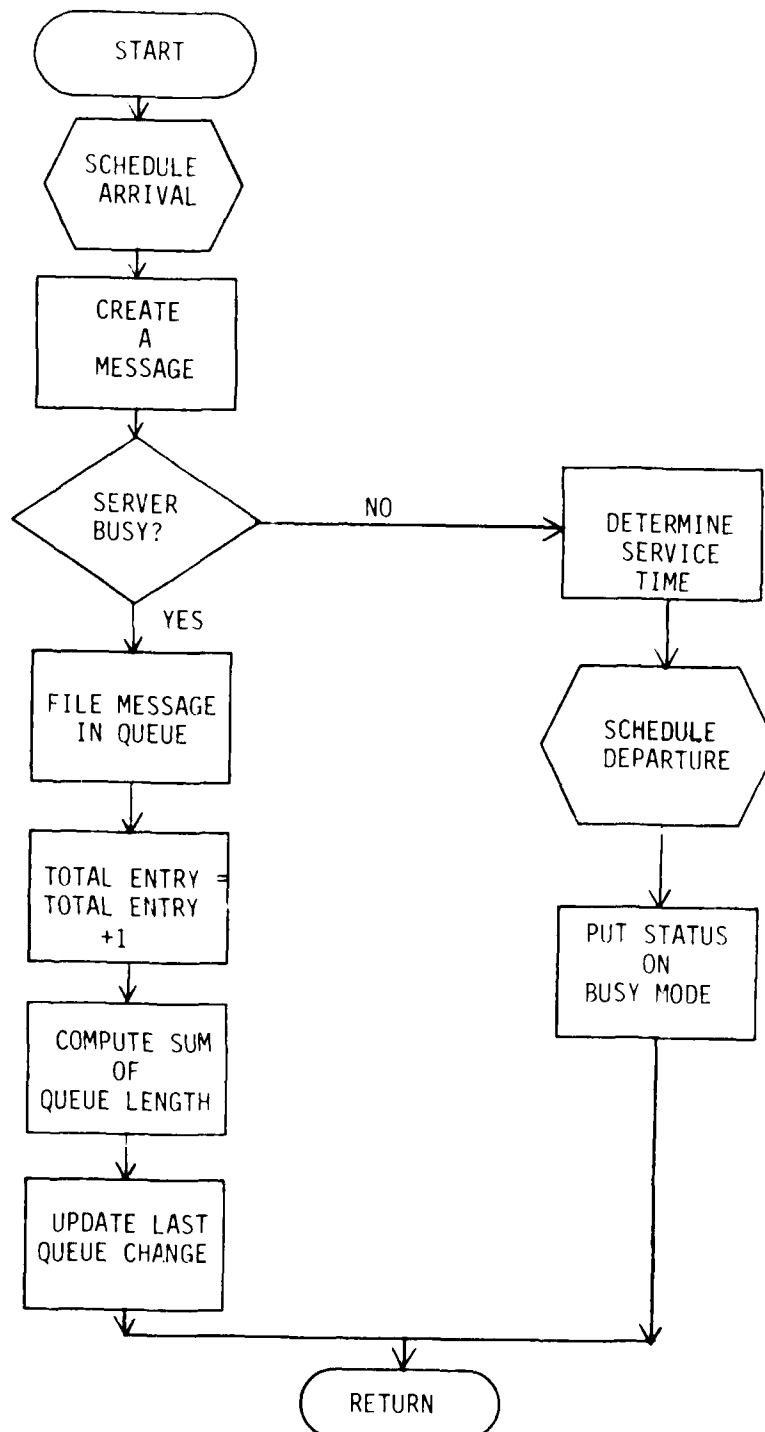


Figure 4-11 Flow Chart for Event Arrival for Single Bus Example.

departure of the message. Figure 4-12 shows the flow chart of Event Departure.

The Event Stop Simulation gives the simulation statistics, such as, the average Queue length, utilization time, the maximum number of messages in the Queue, and the total entries.

Simulation Report

The average Queue length for this simulation program is 3.69 minutes and the average utilization time is 0.94 minutes. The total number of messages entered is 99 and the maximum number in the Queue is 9.

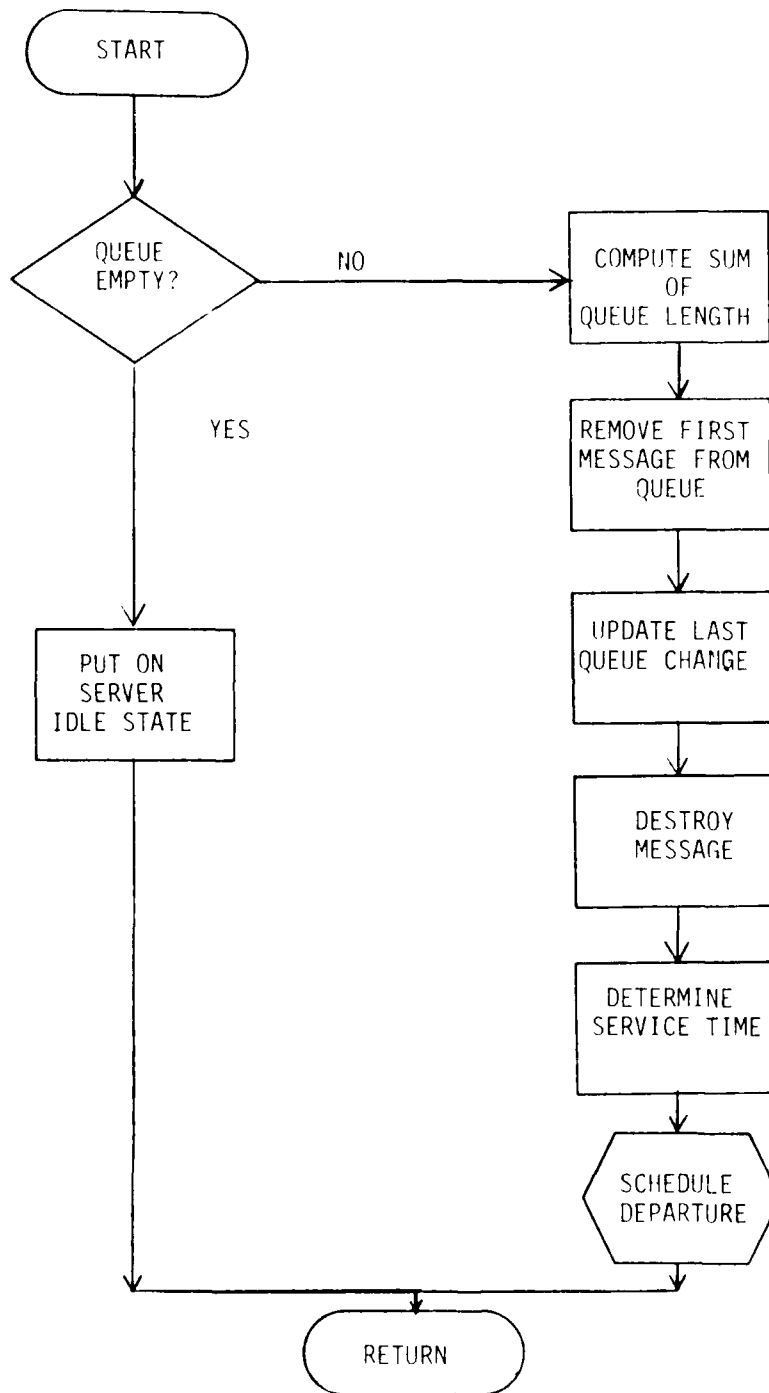


Figure 4-12 Flow Chart for Event Departure for Single Server Example.

CHAPTER V

SUMMARY AND CONCLUSION

In the preceding chapters of this report five simulation languages are presented: GASP IV, GPSS II, SIMSCRIPT II, ADA, and ECSS II. Additionally, a simulation of a simple bus, single queue system is shown utilizing FORTRAN IV, GASP IV, GPSS II, and SIMSCRIPT II. The objective of this simulation is to obtain information on queue length and bus utilization and compare the various programming languages. The ADA and ECSS II languages are not available on the Mississippi State University Univac 1108 System, thus there are no simulation runs in these languages.

The primary thrust in this research effort has been the utilization of AFAL's MUXSIM simulation program. MUXSIM was copied from the AFAL DEC System 10 onto magnetic tape and transported to Mississippi State University. Considerable time and effort was expended in adapting MUXSIM to the UNIVAC 1108 system. Due to the non-availability of interactive terminals at Mississippi State University, MUXSIM runs were made in batch mode using card decks.

The following results were achieved with MUXSIM operating on the UNIVAC 1108 system:

1. The dynamic portions of MUXSIM, MUXDA and MUXDB, were software modified for use with the UNIVAC 1108 based GASP IV. Simulation runs of MUXDA and MUXDB are listed in Chapter III of this report.

2. GASP IV user subroutines are written in FORTRAN language. Additional FORTRAN subroutines for expanded plots of MUXDA bus statistics collected by GASP IV are listed (p. 154). See the Appendix for all program listings.
3. Data files for MUXDA and MUXDB were linked to GASP IV.

Finally, the ADA and ECSS II languages were considered as possible simulation tools for future avionics multiplex data bus studies. Both ADA and ECSS II are general purpose languages with attributes which make them candidates for consideration. ADA has programming features similar to COBOL and PASCAL. The ECSS II language relies on a computer system with a SIMSCRIPT compiler. From a practical point of view, it appears ECSS II offers little advantage over SIMSCRIPT. As mentioned previously, no simulation runs were made with ADA and ECSS II; the discussion of these languages is based on information obtained from references [8] [9].

The foregoing statements summarize the work accomplished under this grant and cover the work statements outlined in the proposal. An additional study was made for comparative purposes utilizing GASP IV, GPSS II, FORTRAN, and SIMSCRIPT. The results of this comparison are shown in Chapter IV.

APPENDIX

LIST OF PROGRAMS AND SUBROUTINES

MUXDA

```

17      PROC
        DIMENSION NDET(11)
        COMMON /GCOM1/ ISET(1000), JSET(1000)
        EQUIVALENCE (ISET(1), JSET(1))
        COMMON /GCOM2/ ITRIB(25), JEVNT, MFA, MFE(100), MLE(100), MSTOP, ACORP,
        & NNAPO, NNAPT, NNAIR, NNAFL, NND(100), NNTFY, NNPRNT, PPARM(50,4), TNCA,
        & TTREG, TTCLR, TTFIN, TTRIB(25), TTSET
        COMMON /GCOM3/ DD(100), DDOL(100), DTFUL, DTNO, ISEES, LFLAG(50), NFLAG,
        & NNEGS, NNEG, SS(100), SSL(100), TTNEV
        COMMON /GCOM4/ AAEP, DTMAX, DTMIN, DTSAV, IITES, LLEFP, LLSAV, LLSEV, APE
        & SPE, TTLAS, TTSV
        COMMON /GCOM5/ IPLT(10), NMLW(25), NMLD(25), IICPD, ITTAP(10), JJCEL
        & IISCD, LLABC(25,2), LLABP(25,2), LLABP(11,2), LLAPT(25,2), LLPMS(10), LL
        & PLO(10), LLPLT, LLSUP(10), LLSYM(10), MMPTS, NNCEL(25), NNCLT, NNHIS, NNPL
        & ET, NNPTS(10), NASTA, NNVAR(10), PPMT(10), PPLO(10)
        COMMON /GCOM6/ IIEVT, IISCD(5), JJREG, JJCLR, MMNIT, MMON, NNAME(3), VNCF
        & I, NNDAY, NNPT, NASET, NNPRJ, NNPRM, NNRRS, NNPRN, NNSTG, NNTR, SSEED(6)
        COMMON /GCOM7/ EENG(100), IINN(100), YKPNK(100), MYAXQ(100), QGT(100)
        & S, SSC=V(25,5), SSTPV(25,5), VVNG(100)
      END

```

```

PROGRAM MUXDA
INCLUDE IT

```

```

-----INPUT CARD DEFINITION-----
CARD TYPE APE DEFINED BY RELATIVE POSITION WITHIN THE DICTIONARY
DECK. THESE CARDS ARE LOCATED AFTER THE GASP IV CONTROL CARDS FOR
SIMULATION RUN 1.

```

```

-----CARD TYPE I DEFINES THE FUI TIME LENGTH AND DEMAND MESSAGE
TRANSFER MODE (1,2). (F10,C,RY,I2) (ONE CARD)
IF MODE 1 IS SELECTED TWO RUNS WILL ENSUE. (ONE MODE 1, THE SECOND
MODE 2) IF MODE 2 IS SELECTED ONE RUN WILL ENSUE. (MODE 2)
MODE 1 = FIRST-IN-FIRST-OUT.
MODE 2 = LONGEST MESSAGE THAT CAN BE TRANSMITTED IN THE
IN THE REMAINING TIME GOES FIRST.

```

```

-----CARD TYPE II DEFINES THE DURATION OF THE FIXED MESSAGE SEQUENCE
FOR EACH FUI. (THIS REQUIRES A CARD FOR EACH FUI AND THE CARDS
MUST BE SEQUENCED BY ASCENDING FUI NUMBER.) (F10,C)
0.0 - ENTRY INDICATES THE END OF CARD TYPE II SEQUENCE.

```

```

-----CARD TYPE III DEFINES THE DEMAND MESSAGES. (4F10,C) (EACH CARD
DEFINES A DEMAND MESSAGE.)
THE ENTRY IS IN EACH CARD ARE DEFINED AS:
FIELD 1 = MEAN ARRIVAL TIME. (UNIFORMLY DISTRIBUTED)
FIELD 2 = MAXIMUM DEVIATION FROM MEAN ARRIVAL (+,-).
FIELD 3 = DEMAND MESSAGE LENGTH.
FIELD 4 = UNDEFINED FOR THIS MODEL.

```

```

0.0 - ENTRY IN FIELD 1 INDICATES THE END OF CARD TYPE
III SEQUENCE.

```

```

ACORP=5
APRNT=0
CALL GASP
CALL EXIT
END

```

```

SUBROUTINE EVATS (IX)
  J=IX/400
  J=J-1+100
  IF (J.EQ.C) CALL EPROR(1)
  GO TO (100,200,300,400),J
100 CALL FUIF(J)
200 CALL FUIFRE(J)
300 CALL ENDDM(J)
400 CALL DPARIV(J)
RETURN
END

```

```

SUBROUTINE ENDDM(NM)
C-----A 300 TYPE EVENT (END A DEMAND MESSAGE)
C PERFORMS THE END OF DEMAND MESSAGE ARRIVAL PROCESSING.

```

```

  INCLUDE IT
  COMMON /MUX1/FUI,IT,NOM,FUI,NFUIS,FUINXT,NFUI,MODE
  COMMON /MUX2/DM(5,20),FUIFX(25)
  DELAY=NOW-ATRI(1)
  LEN=0
  CALL WISTC(DELAY,1)
  FREE TIME STARTS AFTER FINISH OF A DEMAND MESSAGE
  ATRI(1)=NOW
  ATRI(2)=200.-FLOAT(NFUI)
  CALL FILEM(1)
  RETURN
END

```

```

SUBROUTINE FUIFRE(NF)
C-----A 200 TYPE EVENT (START OF FREE TIME IN THIS FUI)
C PROCESSES THE END OF A MESSAGE TRANSMISSION AND SCHEDULES THE
C NEXT DEMAND MESSAGE TRANSMISSION.

```

```

  INCLUDE IT
  COMMON /MUX1/FUI,IT,NOM,FUI,NFUIS,FUINXT,NFUI,MODE
  COMMON /MUX2/DM(5,20),FUIFX(25)
  COMMON /MUX3/ DMSENT(20),FUI,AT(20)
C-----X IS THE REMAINING FREE FUI TIME
  X=FUINXT-TNOW
C-----EXIT IF NOTHING QUEUED OR NO TIME LEFT
  IF (X.EQ.0) GO TO 2
  IF (X.LE.0) GO TO 2
  SELECT ENTRY FROM CUE
  GO TO (11,12),MODE
11 CONTINUE

```

```

SUBROUTINE INTC
  READS IN SIMULATION DATA CARDS AND SETS UP INITIAL CONDITIONS FOR
  SIMULATION EITHER FROM THE INPUT DATA CARDS OR BY ALGEBRAIC
  STATEMENTS.

  INCLUDE IT
  COMMON /FUX1/ FUI1T,NDM,FUI,NFUIS,FUI1NT,NFUI,MODE
  COMMON /FUX2/ DM(5,20),FUIFX(25)
  COMMON /FUX3/ DMSENT(20),FUIWAT(20)
  IF(NCRDR)
    IF(NNRUN.NE.1) GO TO 20
    NFUIS=0

  READS IN CARD TYPE I WHICH DEFINES THE FUI DURATION AND RUN MODE.

  READ(IRD,403) FUI,MODE
  FORMAT(F10.5,2A,10)
  IF(MODE.EQ.0) MODE=1
  WRITE(NPRT,300) FUI,MODE
  FORMAT('FUI=',F10.5,' MODE OF ',I3,/)
  X=0 FUI=NO. FREE FUI START

  READS IN CARD TYPE II WHICH DEFINES FUI FIXED MESSAGE SEQUENCE
  DURATION AND QUANTITY OF FUIS.

  READ(IRD,100) X
  FORMAT(F10.5)
  IF(X.LE.0.0) GO TO 2
  NFUIS=NFUIS+1
  WRITE(NPRT,301) NFUIS,X
  FORMAT('FUIS',F10.5)
  FUIFX(NFUIS)=X
  IF(X.GT.FUI) CALL ERROR(2)
  GO TO 1
  CONTINUE
  FUI1T=TNOW
  DO 3 I=1,NFUIS
    X=FUI1T-FUI*FLOAT(I-1)
    CALL NXTFUI(I,X)
  NDM=1

  READS IN CARD TYPE III WHICH DEFINES THE DEMAND MESSAGES.

  READ(IRD,200) DM(J,NDM),J=1,4
  FORMAT(4F10.5)
  IF(DM(1,NDM).LE.0.0) GO TO 10
  NDM=NDM+1
  GO TO 5
  CONTINUE
  NDM=NDM-1
  WRITE(NPRT,302) NDM
  FORMAT('NDM=',I3,/,10X,/, ' PARAMETERS OF A DM' - NDM=I,14)
  DO 11 I=1,NDM
    WRITE(NPRT,303) DM(J,I),J=1,4
    FORMAT('S,4(F10.5,X,F10.5))
  CALL NXTDM(I)
  CONTINUE
  DO 15 I=1,20
    DMSENT(I)=0.
  FUIWAT(I)=0.
  RETURN

  CONTINUE
  NNPTS(1)=NNPTS(1) - 1
  MODE=MODE+1
  FUI1T=TNOW
  DO 21 I=1,NFUIS
    X=FUI1T-FUI*FLOAT(I-1)
    CALL NXTFUI(I,X)
  DO 23 I=1,NDM
    CALL NXTDM(I)
  GO TO 30
END

```



```

12      IF (X(2)
      GO TO 20
      CONTINUE
      IF (X(3,2,1,0,0))
      CONTINUE
      COPY SELECTION INTO ATTRIBUTES AREA
      IF (X(2,0,0)) GO TO 2
      CALL COPY(1)
      TEST IF WILL FIT
      IF (ATTRIB(1).GE.X) GO TO 2
      CALL RMVCE(1,2)
      DML IS DEMAND MESSAGE LENGTH
      DML=ATTRIB(1)
      ATTRIB(1)=TNOW+DML
      ATTRIB(2)=100+ATTRIB(2)
      CALL FILEW(1)
      DMSENT(NF)=DMSENT(NF)+DML
      RETURN
      CONTINUE
      FUIWAT(NF)=FUIWAT(NF)+X
      RETURN
      END

      SUBROUTINE FUIT(NF)
      C-----A 100 TYPE EVENT (START OF THIS FUI)
      C-----PERFORMS THE PROCESSING INVOLVED WITH FUI STARTUP.
      C
      REAL XX(4)
      INCLUDE IT
      COMMON /MUX1/FUIT,NDM,FUI,NFUIS,FUINXT,NFUI,MODE
      COMMON /MUX2/DM(5,20),FUIFX(25)
      COMMON /MUX3/DMSENT(20),FUIWAT(20)
      X=FUI+FLOAT(NFUIS)
      C-----FOLLOWING STATEMENT IS SAVING FUI 1 TIME TO PREVENT DRIFT OF
      C-----FUI TIMES WITH RESPECT TO EACH OTHER DUE TO ROUND OFF
      IF (NF.EQ.1) FUIT=TNOW+X
      C-----TEST FOR FIRST CYCLE THROUGH MAJOR CYCLE
      C-----SKIP PLOT CALL IF FIRST MAJOR CYCLE
      IF (FUIT.LE.(TTBEG+X)) GO TO 1
      C-----COLLECT ONLY 100 SETS OF POINTS
      IF (NNPTS(1).GE.100) GO TO 1
      C-----X IS THE FREE FUI TIME AVAILABLE FOR SCHEDULE OF DEMAND MESSAGES
      X=FUI-FUIFX(NF)
      C-----PLOT ARGUMENTS
      C-----1 IS QUEUE NUMBER AT FUI TIME
      C-----2 IS THE DEMAND MESSAGE LENGTHS SENT PERCENTAGE OF AVAILABLE
      C-----3 IS UNUSED TIME AS PERCENTAGE OF NON FIXED TIME
      XX(1)=FLOAT(NNG(2))
      XX(2)=DMSENT(NF)/X
      XX(3)=FUIWAT(NF)/X
      CALL GPLOT(XX,TNOW,1)
      CONTINUE
      CALL HISTO(DMSENT(NF),NF)
      C-----ZERO TOTAL ACCUMULATORS
      DMSENT(NF)=0.0
      FUIWAT(NF)=0.0
      C-----X IS NOW TIME OF NEXT FUI FOR THIS FUI NUMBER
      X=FUIT+FUI+FLOAT(NF-1)
      CALL NATFUI(NF,X)
      C-----SCHEDULE THE FREE FUI TIME START FOR THIS FUI
      ATTRIB(1)=TNOW+FUIFX(NF)
      ATTRIB(2)=200+FLOAT(NF)
      ATTRIB(3)=FUI-FUIFX(NF)
      CALL FILEW(1)
      C-----FUIWAT IS WHEN NEXT FUI STARTS
      FUIWAT=TNOW+FUI
      C-----NFUI IS CURRENT FUI INTERVAL NUMBER
      NFUI=NF
      RETURN
      END

```

```

SUBROUTINE DMARIV(ND)
C-----A LOGIC TYPE EVENT (ARRIVAL OF A DEMAND MESSAGE)
C-----PROCESSES THE ARRIVAL OF DEMAND MESSAGES AND CALLS FOR SCHEDULING
C-----OF THE NEXT DEMAND MESSAGE ARRIVAL.
C-----
C-----DM IS THE DEMAND MESSAGE DEFINITION
C-----DM(1,N) IS DEFINED AS:
C-----FROM
C-----A1=ARRIVAL TIME MEAN
C-----A2=DISTRIBUTION CODE VALUE ABOUT MEAN
C-----A3=MESSAGE LENGTH
C-----N=N
C-----
C-----INCLUDE IT
C-----COMMON /MUX1/FUI1T,NDM,FUI,NFUIS,FUINXT,NFUI,MODE
C-----COMMON /MUX2/DM(5,10),FUIFX(25)
C-----SCHEDULE THE NEXT DEMAND MESSAGE ARRIVAL
C-----CALL NXTDM(ND)
C-----PUT CURRENT D.M. ON WAITING QUE
C-----ATRIB(1)=DM(3,ND)
C-----ATRIB(2)=FLOAT(ND)
C-----ATRIB(3)=TNOW
C-----CALL FILEM(2)
C-----RETURN
C-----END

SUBROUTINE NXTFUI(I,WHEN)
C-----
C-----SCHEDULES THE START OF THE NEXT FUI.
C-----
C-----COMMON /MUX1/FUI1T,NDM,FUI,NFUIS,FUINXT,NFUI,MODE
C-----COMMON /MUX2/DM(5,20),FUIFX(25)
C-----INCLUDE IT
C-----ATRIB(1)=WHEN
C-----ATRIB(2)=100.*FLOAT(I)
C-----CALL FILEM(1)
C-----RETURN
C-----END

SUBROUTINE NXTDM(I)
C-----
C-----SCHEDULES ARRIVAL OF THE NEXT DEMAND MESSAGE.
C-----
C-----COMMON /MUX1/FUI1T,NDM,FUI,NFUIS,FUINXT,NFUI,MODE
C-----COMMON /MUX2/DM(5,10),FUIFX(25)
C-----INCLUDE IT
C-----PHI=DM(2,I)
C-----PLOW=PHI
C-----J=MOD(I,5)+1
C-----ATRIB(1)=TNOW+DM(1,J)+UNIFR(PLOW,PHI,J)
C-----ATRIB(2)=100.*FLOAT(I)
C-----CALL FILEM(1)
C-----RETURN
C-----END

```

MUXDB

[illegible]

```

PROGRAM MUKDB
INCLUDE IT
COMMON /MUK1/NDV,CM(4,25),TMSFNT(25)
COMMON /MUK2/FU1IT,FU1,NF1IS,NF1X(25),F1A(25,25),TCUMF
COMMON /MUK3/ANOISE,NGBUS(15),SMEAN(15),SMMAN(15),SLNG(15),SLVAR
(15)
COMMON /MUK4/NT,MEAN(15),TMVAR(15),TLEN(15),TLVAR(15)
COMMON /MUK5/ILBUS,IRBUS
COMMON /MUK6/NTRES(15),TPAR(15),NUMV(15),IOM(15)
COMMON /MUK7/IDUSY,MSTYP,MSGNCW
DATA ISW/1/

```

```
-----INPUT CARD DEFINITION-----
INPUT CARD TYPE IS DEFINED BY THE LETTER ENTERED IN COLUMN 1
DEFINED AS FOLLOWS:
```

```

A = EXIT, FINISHED WITH INPUT.
D = DEMAND MESSAGE      F(11,4F10.0) FOR MEAN, VARIANCE, LENGTH, TERM. NO.
F = FIXED MESSAGE       F(16,15,14F5.0) FOR FUI NUMBER AND 14 MESSAGE
                        LENGTHS.
T = TERMINAL DOWN      F(16,15,4F10.0) FOR TERMINAL NUMBER, MEAN AND
                        VARIANCE OF OCCURANCE, AND
                        LENGTH AND VARIANCE OF DOWN.
% = NOISE              F(16,15,4F10.0) FOR BUS INDICATOR(1,2,3=LEFT,
                        RIGHT, BOTH), MEAN AND
                        VARIANCE OF OCCURANCE, AND
                        LENGTH AND VARIANCE OF
                        DURATION.
U = NUMBER OF FUIS     F(16,15,F10.0) FOR NUMBER OF FUIS, FUI
                        INTERVAL (FUNDIMENTAL UPDATE
                        INTERVALS).
R = RESPONSE TIME      F(16,15,2F10.0) FOR TERMINAL NUMBER, MEAN
                        RESPONSE TIME, VARIANCE OF
                        RESPONSE TIME.
C = COMMENT CARD IN DECK - NO ACTION

```

-----EVENT DEFINITIONS-----
EVENT TYPES ARE DEFINED BY HUNDREDS (100) AND EVENT SUB-TYPES
A-E ARE DEFINED BY UNITS (1), AS FOLLOWS:

```

100 - WATCH DOG TIMER
1.TIME
2.EVENT NUMBER
3.MESSAGE NUMBER

200 - CALL TERMINAL
1.TIME
2.EVENT NUMBER + TERMINAL DESTINATION
3.MESSAGE NUMBER + 10000'S OF HITS LEFT + 10000'S
OF HITS RIGHT

300 - TERMINAL RESPONSE
1.TIME
2.EVENT NUMBER + TERMINAL RESPONDING
3.MESSAGE NUMBER + 10000'S OF HITS LEFT + 10000'S
OF HITS RIGHT

```

```

400 - NOISE START
      1.TIME
      2.EVENT NUMBER + BUS DESIGNATION (1-3)
      3.NOISE NUMBER

500 - NOISE END
      1.TIME
      2.EVENT NUMBER + BUS DESIGNATION (1-3)
      3.NOISE NUMBER

600 - TERMINAL DOWN
      1.TIME

700 - TERMINAL UP
      1.TIME
      2.EVENT NUMBER + TERMINAL NUMBER

800 - FUI TIME START
      1.TIME
      2.EVENT NUMBER + FUI NUMBER

1000 - DEMAND MESSAGE ARRIVAL
      1.TIME
      2.EVENT + DEMAND MESSAGE NUMBER

MESSAGE NUMBERS- 100'S FOR FIXED TYPE
                  200'S FOR DEMAND TYPE

```

```

NCRD=5
NPRINT=6
CALL GASP
CALL EXIT
END

```

SUBROUTINE INTLC

READS IN THE SIMULATION DATA CARDS AND SETS UP THE INITIAL CONDITIONS FOR THE SIMULATION EITHER FROM THE SIMULATION INPUT DATA CARDS OR BY ALGEBRAIC STATEMENTS

```

INTEGER CARD(40),SCRATCH(80)
INCLUDE IT
COMMON /MUX1/NDM,DM(4,15),TMSENT(25)
COMMON /MUX2/FUI17,FUI,VFUI5,NFIX(25),FIX(,25),ICURF
COMMON /MUX7/NNCISE,NSEUS(15),SMEAN(15),SMVAR(15),SLNG(15),SLVAR
1(15)
COMMON /MUX4/NTM,TMEAN(15),TMVAR(15),TLEN(15),TLVAR(15)
COMMON /MUX5/NTR,TRES(15),TRVAR(15),NUMV(15),IOK(15)
COMMON /MUX4/ILBUS,IRBUS
COMMON /MUX7/IBUSY,MSGOTYP,MSGNOW
COMMON /MUXUSE/FUIPRS,FME,DME
COMMON /MUXRES/IRESE
COMMON /STAT1/NMSGH,NNL,NNR,NNP,NTD,NMSG
DATA NC/1HC/
DATA NX,ND,NT,NF,NR,AN,NU/1HX,1HD,1HT,1HF,1HR,1HN,1HU/
NMM=0
NNL=0
NNR=0
NNP=0
NTD=0
FUI17=TYCW
NNOISE=0
NFUI5=0
NMM=0

```

```

      NTR=0
      ITCUS=0
      IFBUS=0
      IFUSY=0
      MSGTYPE=1
      FUIPRS=TNQ
      IPRES=0
      NMSG=0
      NLE=0
      NNR=0
      NND=0
      NTU=0
      NMSG=0
      DO 1 I=1,25
        FIA(I,1)=0
        NFIA(I)=0
        DO 2 J=1,15
          ICA(J)=0
        1 CONTINUE
        WRITE(NPRT,100)
        500 FORMAT('10,72','INPUT CARDS')
        IPAGE=0
        1 CONTINUE
        READ(INCRDR,100,END=99)CARD
        100 FORMAT('CA1')
        ENCODE(PC,100,SCRCH)CARD
        ICA=CARD(1)
        501 WRITE(NPRT,501)CARD
        FORMAT('1X,11,0CA1')
        IPAGE=IPAGE+1
        IF(IPAGE.LE.52)GO TO 502
        WRITE(NPRT,500)
        502 IPAGE=0
        CONTINUE
        IF(ICA.EQ.VX)GO TO 99
        IF(ICA.EQ.NC)GO TO 1
        IF(ICA.EQ.ND)GO TO 10
        IF(ICA.EQ.NT)GO TO 10
        IF(ICA.EQ.NF)GO TO 20
        IF(ICA.EQ.NR)GO TO 40
        IF(ICA.EQ.VN)GO TO 50
        IF(ICA.EQ.VU)GO TO 50
        CALL ERROR(10)
        GO TO 1
      99
      10 = DEMAND MESSAGE CARD
      10 CONTINUE
      NDM=NDM+1
      DECODE(PC,101,SCRCH)(DM(I,NDM),I=1,4)
      101 FORMAT('11,4F10.0')
      GO TO 1
      20 = FIXED MESSAGE CARD
      20 CONTINUE
      DECODE(PC,102,SCRCH)I
      102 FORMAT('10,15')
      J=FIX(I)+1
      K=J+1
      DECODE(PC,103,SCRCH)(FIX(L,I),L=J,K)
      103 FORMAT('11,14F5.0')
      NFIX(I)=K
      GO TO 1
      30 = TERMINAL DOWN CARD
      30 CONTINUE
      NNTM=1
      DECODE(PC,104,SCRCH): ,TMEAN(NTM),TMVAR(NTM),TLEN(NTM),
      104 TTVAR(NTM)
      FORMAT('10,15,4F10.0')
      GO TO 1
      40 = TERMINAL RESPONSE TIME
      40 CONTINUE
      NTR=1
      DECODE(PC,105,SCRCH): ,TRRES(NTR),TRVAR(NTR)
      105 FORMAT('10,15,2F10.0')
      GO TO 1

```

1

```

250 CONTINUE
   IF(NNOISE.LE.0) GO TO 240
   WRITE(NPRNT,110)
   FORMAT(11,'110: NOISE PARAMETERS: /,,' BUS CODE',T20,'MEAN',
1  T40,'VARIANCE',T40,'LENGTH',T80,'VARIANCE OF LENGTH')
   DO 351 I=1,NNOISE
   112 WRITE(NPRNT,117)NBUS(I),SMEAN(I),SMVAR(I),SLNG(I),SLVAR(I)
   117 FORMAT(1A,13,T40,F10.4,T40,F10.4,T50,F10.4,T50,F10.4)
   351 CONTINUE

      NUMBER OF FUIS

260 CONTINUE
   WRITE(NPRNT,118)NFUIS,FUI
   118 FORMAT(10,NFUIS=' ',15,' FUI=',F10.5)

      SETUP ALL EVENTS
      DEMAND MESSAGES

   IF(NDM.LE.0) GO TO 330
   DO 311 I=1,NDM
   311 ATRIB(1)=TINC*RNXT(DM(1,I),DM(2,I),1)
      CALL FILEM(1)
      TERMINAL DOWN

320 CONTINUE
   IF(NTM.LE.0) GO TO 350
   DO 321 I=1,NTM
   321 ATRIB(1)=TINC*RNXT(TMEAN(I),TMVAR(I),1)
      CALL FILEM(1)
      NOISE

330 CONTINUE
   IF(NBUS.LE.0) GO TO 360
   DO 331 I=1,NBUS
   331 ATRIB(1)=TINC*RNXT(SMEAN(I),SMVAR(I),1)
      ATRIB(2)=TINC*RNXT(NSBUS(I))
      ATRIB(3)=1
      CALL FILEM(1)
      FUI 1

340 CONTINUE
   IF(NFUI.LE.0) CALL ERROR(13)
   ATRIB(1)=TINC
   ATRIB(2)=0.1
   CALL FILEM(1)

      INITIALIZATION DONE

   TRACE START TIME
   ATRIB(1)=0.
   ATRIB(2)=0.
   CALL FILEM(1)
   TRACE END AND TIME
   ATRIB(1)=1.
   ATRIB(2)=0.
   CALL FILEM(1)
   RETURN
END

```



```

SUBROUTINE STAT(ILFLO,IRFUS)
C
C COLLECTS TIME PERSISTENT STATISTICS ON DATA AND NOISE.
C
C INCLUDE IT
C IFILFUS
C CALL TIMST(X,TNOW,1)
C IFIRFUS
C CALL TIMST(X,TNOW,2)
C X=INT((ILFUS,IRFUS))
C CALL TIMST(X,TNOW,3)
C RETURN
C END

SUBROUTINE NATMSG(IAM)
C
C SCHEDULES THE NEXT POSSIBLE CALL TO A TERMINAL EVENT.
C
C INCLUDE IT
C COMMON /MUA1/NOV,OM(4,15),TMSEVT(25)
C COMMON /MUA2/FU1IT,FU1,AFU1S,NF1X(25),FIX(25,25),ICURF
C COMMON /MUA3/NTR,TRIS(15),TRVAR(15),NUMV(15),IOK(15)
C COMMON /MUA4/IBUS,IRFUS
C COMMON /MUA5/IBUSY,MSGTYP,MSGNO
C COMMON /MUA6/JIT,FU1STA
C COMMON /MUA7/USE/FUIPRS,FME,DME
C COMMON /STAT/NMSGH,NL,NP,NB,NTD,NMSG
C
C ARGUMENT IAM HAS FOLLOWING POSSIBLE VALUES AND MEANINGS
C 1 - FU1 TIME IS OCCURRING NOW
C 2 - WATCHDOG TIMEOUT EVENT IS OCCURRING NOW
C 3 - A NORMAL RESPONSE IS OCCURRING NOW
C
C TEST IF FU1 AND BUSY WITH A MESSAGE
C IF((IAM.EQ.1).AND.(IBUSY.NE.0))-RETURN
C
C
C NEED TO SEND A MESSAGE - DETERMINE TYPE
C GO TO (10,20),MSGTYP
C
C CONTINUE
C CONNECT JITTER HISTO
C CONNECT (X,NTD),JIT
C JITE=
C IFINQ=FU1STA
C CALL HISTO(X,1)
C IF((IAM.NE.1).AND.(IBUSY.NE.1))DME=TNOW
C IF(ICURF.NE.1)JITE=JITE+1
C IF(TNOW-TRIS(JITE).GT.1)JITE=JITE+1
C
C COLLECT STATISTICS
C IFME=FU1DME
C CALL COLT(X,1)
C IFME=FU1DME
C CALL COLT(X,2)
C IFIPRST=
C CONTINUE
C
C PRINT MESSAGE IF POSSIBLE

```

```

      IF (FIX(MSGNO,ICURF).LE.0.)GO TO 12
      IF MSG(VMSGNO,5)+1
      IF LGAT(NTR)+.5
      ATTRIB(1)=TNOW+FIX(MSGNO,ICURF)
      ATTRIB(2)=20000+UNER*(1,1,1)
      ATTRIB(3)=MSGNO+ILBUS*1000+IRBUS*100000.
      CALL FILEM(1)

      WATCH DOG FOR MESSAGE

      IF ATTRIB(2)=000.
      X=1.05*(FIX(MSGNO,ICURF)+TRES(1)+TRVAR(1))
      ATTRIB(1)=TNOW+X
      ATTRIB(2)=1000.
      ATTRIB(3)=MSGNO
      CALL FILEM(1)
      MMSG=MMSG+1
      IMSG=1
      NMMSG=NMSG+1
      RETURN

12 CONTINUE
MSGTYP=1
FUE=TNOW
GO TO 1

CONTINUE
DEMAND MESSAGE LOOK

TRY TO SEND SOME DEMAND MESSAGES
X=TIME REMAINING TILL NEXT FUI START
X=(FUIT+(ICURF+FUI))-TNOW

SELECT ENTRY FROM QUE

IF ME(1)
IF (1.LE.0)GO TO 90
CALL COPY(1)
DML=ATTRIB(1)

IF (DML.GT.X)GO TO 90
CALL REMOVE(1,2)
ATTRIB(1)=TNOW+DML
IF ATTRIB(2)
ATTRIB(2)=2000.+DM(4,1)
ATTRIB(3)=ILBUS*1000.+IRBUS*100000.+1+200.
CALL FILEM(1)

TMSENT(ICURF)=TMSENT(ICURF)+DML

J=DM(4,1)
X=1.05*(DML+TRES(J)+TRVAR(J))
ATTRIB(1)=TNOW+X
ATTRIB(2)=1000.
ATTRIB(3)=2000.+1
CALL FILEM(1)
IMSG=1
NMMSG=NMSG+1
RETURN

CONTINUE
IMSGTYP=1
IMUE=TNOW
RETURN
END

```

```

SUBROUTINE CTERM(ITRM)
C
C HANDLES MESSAGE ARRIVAL AND SUBSEQUENT PROCESSING AT A TERMINAL
C AND GENERATES TERMINAL RESPONSE.
C
C INCLUDE IT
COMMON /MUX/NTD,TRES(15),TRVAR(15),NUMV(15),IOK(15)
COMMON /MUX/ILBUS,IRBUS
COMMON /STAT/NMSGH,NL,NR,NE,NTD,NMSG
C
C MODULE FOR TERMINAL RECEIVING A CALL AND:
C A. GENERATING A RESPONSE
C B. NO ACTION
C DEPENDING ON:
C A. TERMINAL IS OPERATIONAL
C B. MESSAGE RECEIVE READABLE FROM AT LEAST
C ONE BUS
C
C STATISTICS COLLECTION IF ANY
C TEST FOR NOISE HITS
C
C IHTD=ATTRIB(7)/100000.+5
C IHTL=(ATTRIB(3)-(IHTD*100000.))/1000.+5
C MSG=ATTRIB(3)-(IHTD*100000.)-(IHTL*1000.)+5
C
C NO RESPONSE IF HIT ON BOTH SIDES OR TERMINAL DOWN
C
C IF((IHTD.GT.0).OR.(IHTL.GT.0))NMSGH=NMSGH+1
C IF((IHTD.GT.0).AND.(IHTL.GT.0))RETURN
C IF(IOK(ITRM).GT.0)RETURN
C
C OK - GENERATE RESPONSE
C
C ATTRIB(1)=TNO+RNAT(TRES(ITRM),TRVAR(ITRM),ITRM)
C ATTRIB(2)=300.+ITRM
C ATTRIB(3)=MSG+ILEUS*1000.+IRBUS*100000.
C CALL FILEM(1)
C NMSG=NMSG+1
C RETURN
C END

```

```

SUBROUTINE TERM(IIRM)
C
C PROCESSES TERMINAL RESPONSE.
C
C INCLUDE IT
COMMON /MJK2/FU11T,FU11,FU15,NFIX(25),FIX(25,25),ICURF
COMMON /MUK4/INTR,TRES(15),TRVAR(15),NUMV(15),IOK(15)
COMMON /MUKRES/IRESE
COMMON /STAT/NMSGH,NL,NR,NB,NTG,NMSG
C
C     TERMINAL HAS RESPONDED
C
C     INTR=ATR:R(7)/100000.*.5
C     INTR=ATR:5(3)-(INTR*100000.)/10.*.5
C     INTR=ATR:5(3)-(INTR*100000.)/1000.*.5
C     INTR=ATR:5(3)-(INTR*100000.)-(INTR*1000.)*.5
C
C     COLLECT STATISTICS
C
C     IF((INTR.GT.0).OR.(JHTL.GT.0))NMSG=NMSG+1
C
C     TEST IF RESPONSE READABLE
C
C     IF((INTR.GT.0).AND.(JHTL.GT.0))GO TO 90
C
C     KILL WATCH DOG ON THIS MESSAGE
C
C     J=0
C     XMSG
C     CONTINUE
1   INFIN(4,5,1,3,.5)
C     IF(I.EQ.0)GO TO 20
C     CALL REMOVE(1,1)
C     IF(ATRIB(2).EQ.100.)GO TO 10
C     REMOVE TEMPORALLY ANY MESSAGE NO. EVENT NOT WATCH DOG TIMER
C     EVENT.
C     CALL FILEM(3)
C     J=J+1
C     GO TO 1
10  CONTINUE
C     IF(J.EQ.0) GO TO 20
C     DO 11 1=1,J
C     CALL REMOVE(MFE(3),3)
11  CALL FILEM(1)
20  CONTINUE
C     CALL NXTMSG(3)
C     CONTINUE
90  RETURN
C0  IRESE=IRESE+1
C     IF(J.NE.0)GO TO 10
C
C     RETURN
C     END
C
C SUBROUTINE WATCH(IDUM)
C
C WATCH DOG EVENT OCCURENCE IS ESTABLISHED.
C
C IF((INTR.GT.0).OR.(JHTL.GT.0))NMSG=NMSG+1
C
C COLLECT STATISTICS ON NO RESPONSE FROM TERMINAL
C
C NTO=NTG+1
C CALL NATMSG(2)
C RETURN
C END

```

```

C      SUBROUTINE NOISES(IN)
C
C      PROCESSES NOISE EVENTS AND SCHEDULES NEXT NOISE EVENT AND
C      DURATION.
C
C      INCLUDE IT
C      COMMON /MUX1/NOISE,NSEUS(15),SMEAN(15),SMVAR(15),SLNG(15),SLVAR
1(15)
C      COMMON /MUX4/ILBUS,IRBUS
C      COMMON /STAT/NMSGH,NL,NR,NB,NTD,NMSG
C
C      NOISE EVENT START
C
C      NNO=ATTRIB(3)
C      N=ATTRIB(2)-400
C      X=ATTRIB(2)
C      IF((X.LE.400.).OR.(X.GT.407.))CALL ERROR(8)
C      IF(X.EQ.401.)Y=1000.
C      IF(X.EQ.402.)Y=10000.
C      IF(X.EQ.403.)Y=101000.
C
C      MARK EVERY MESSAGE ON BUS (FILE 1) AS HIT
C
C      CONTINUE
C      I=NFIND(225,5,1,2,26.)
C      IF(I.EQ.0)I=NFIND(325,5,1,2,26.)
C      IF(I.EQ.0)GO TO 10
C      CALL REMOVE(I,1)
C      CALL FILEM(1)
C      GO TO 1
C
10  CONTINUE
C
C      MARK AND RETURN TO FILE 1
C
C      I=MFE(3)
C      IF(I.EQ.0)GO TO 20
C      CALL REMOVE(I,1)
C      ATTRIB(3)=ATTRIB(3)+Y
C      CALL FILEM(1)
C      GO TO 10
C
20  CONTINUE
C      GO TO (21,22,23),IN
C
21  ILBUS=ILBUS+1
C      NL=NL+1
C      GO TO 30
C
22  IRBUS=IRBUS+1
C      NR=NR+1
C      GO TO 30
C
C
C
23  ILBUS=ILBUS+1
C      IRBUS=IRBUS+1
C
30  CONTINUE
C      IF((ILBUS.GT.0).AND.(IRBUS.GT.0))NB=NB+1
C      CALL STAT(ILBUS,IRBUS)
C
C      NOW FOR NOISE TERMINATION EVENT CREATION
C
C      ATTRIB(1)=TNO+RNXT(SLNG(NNO),SLVAR(NNO),NNO)
C      ATTRIB(2)=500.+IN
C      ATTRIB(3)=NNO
C      CALL FILEM(1)
C
C      NEXT NOISE EVENT (THIS NUMBER)
C
C      ATTRIB(1)=TNO+RNXT(SMEAN(NNO),SMVAR(NNO),NNO)
C      ATTRIB(2)=400.+IN
C      ATTRIB(3)=NNO
C      CALL FILEM(1)
C
C      ALL DONE
C
C      RETURN
C      END

```

```

C      SUBROUTINE NOISET(IN)
C      PROCESSES NOISE TERMINATION EVENT. REMOVES NOISE EVENT(S) FROM
C      BUS(ES).
C      INCLUDE IT
C      COMMON /MUX7/NNNOISE,NSBUS(15),SMEAN(15),SMVAR(15),SLNG(15),SLVAR
1(15)
C      COMMON /MUX8/ILBUS,IRBUS,
C      END NOISE EVENT
C
C      GO TO(1,2,3),IN
1      ILBUS=ILBUS-1
C      GO TO 10
2      IRBUS=IRBUS-1
C      GO TO 10
3      IPBUS=IPBUS-1
C      ILBUS=ILBUS-1
10      CONTINUE
      CALL STAT(ILBUS,IRBUS)
      RETURN
      END

C      FUNCTION RNXT(XMEN,PVAR,ISTRM)
C      USING UNIFORM DERIVE A NUMBER TO ADD TO INOW GIVING NEXT
C      EVENT TIME. ISTRM IS ASSUMED ANY POSITIVE INTEGER.
C      I=MOD(ISTRM,5)+1
C      XHI=PVAR
C      XLO=XHI
C      RNAT=XMEN+UNIFORM(XLO,XHI,1)
C      RETURN
C      END

C      SUBROUTINE TRMUP(ITN)
C      ESTABLISHES TERMINAL RECOVERY FROM FAILED MODE.
C      COMMON /MUX5/NTR,TRES(15),TRVAR(15),NUMV(15),IOK(15)
C      IOK(ITN)=IOK(ITN)+1
C      RETURN
C      END

C      SUBROUTINE TRMDN(ITN)
C      ESTABLISHES TERMINAL FAILURE.
C      INCLUDE IT
C      COMMON /MUX4/NTM,TMEAN(15),TMVAR(15),TLEN(15),TLVAR(15)
C      COMMON /MUX5/NTR,TRES(15),TRVAR(15),NUMV(15),IOK(15)
C      IOK(ITN)=IOK(ITN)+1
C      NEXT DOWN EVENT
C      ATR1(1)=TNOW+RNXT(TMEAN(ITN),TMVAR(ITN),ITN)
C      ATR1(2)=AOC+ITN
C      CALL FILEW(1)
C      TERMINAL UP EVENT SCHEDULED NEXT
C      ATR1(1)=TNOW+RNXT(TLEN(ITN),TLVAR(ITN),ITN)
C      ATR1(2)=AOC+ITN
C      CALL FILEW(1)
C      RETURN
C      END

```

```

      SUBROUTINE DMARIV(IDM)
C
C      PROCESSES DEMAND MESSAGE ARRIVAL AND SCHEDULES NEXT DEMAND MESSAGE
C      ARRIVAL.
C
      INCLUDE IT
      COMMON /MUJ1/NDM,DM(4,25),TMSENT(25)
C
      DEMAND MESSAGE IDM HAS ARRIVED. PUT ON QUE
C
      ATTRIB(1)=DM(3,IDM)
      ATTRIB(2)=IDM
      ATTRIB(3)=TNO
C
      SAVE LENGTH,MESSAGE NUMBER,ARRIVAL TIME ON QUE
      CALL FILEM(2)
C
      NEXT D.M. NO. IDM
C
      ATTRIB(1)=TNO+RNXT(DM(1,IDM),DM(2,IDM),IDM)
      ATTRIB(2)=1000.+IDM
      CALL FILEM(1)
      RETURN
      END

      SUBROUTINE DTPLT
C
C      OUTPUTS NON-GASP INFORMATION ABOUT THE EFFECT OF BUS NOISE.
C
      INCLUDE IT
      COMMON /MUXPEC/IRESE
      COMMON /STAT1/NMSGH,NL,NP,NB,NTO,NMSG
      WRITE(NPRINT,100)IRESE
100  FORMAT('NUMBER OF VALID READABLE RESPONSES LOST TO TIMEOUT =',I9)
      WRITE(NPRINT,101)NTO
101  FORMAT('NUMBER OF TIMEOUTS =',I9)
      WRITE(NPRINT,102)NL,NR,NP
102  FORMAT('NUMBER OF HITS ON LEFT BUS =',I9,
1* RIGHT BUS =',I9,
2* BOTH BUSES =',I9)
      WRITE(NPRINT,103)NMSG
103  FORMAT('TOTAL NUMBER OF MESSAGES SENT =',I9)
      WRITE(NPRINT,104)NMSGH
104  FORMAT('TOTAL NUMBER OF MESSAGES HIT ON AT LEAST ONE BUS =',I9)
      RETURN
      END

```

FORTRAN IV Simulation Example

```

.....
      INTEGER EVENT
.....
      INITIALIZATION OF ALL VARIABLE AND PARAMETER
.....
      RANDOM NUMBER GENERATOR SEED
      RND=1951171
.....
      SUM OF SERVICE TIME FOR ALL RUNS
      SSOST=0.0
.....
      SUM OF QUEUE LENGTH FOR ALL RUNS
      SSOQT=0.0
.....
      MEAN INTER ARRIVAL TIME OF MESSAGE
      EXPA=5.0
.....
      MEAN SERVICE TIME OF MESSAGE
      EXPS=4.0
.....
      TOTAL SIMULATION TIME
      TST=480.0
.....
      WRITE(0,1)
      WRITE(0,2)
      DO 100 I=1, 100
.....
      NUMBER OF MESSAGE ENTRIES
      TIC=0.0
.....
      FACILITY STATUS
      IFS=0
.....
      QUEUE LENGTH
      IQ=0
.....
      TIME OF LAST QUEUE CHANGE
      TOLQC=0.0
.....
      SOST=0.0
.....
      SUM OF QUEUE LENGTH

```



```

C
C      SQCL= 0.0
C.....
C      TIME OF NEXT SERVICE
C      TONS= 9999.
C.....
C      TIME OF NEXT DEPARTURE
C      TOND= 9999.
C.....
C      TIME OF NEXT ARRIVAL
C      TONA= 0.0
C.....
C      SYTEM CLOCK
C      CLOCK= 0.0
C.....
C      CALL RAND(N,R)
C      TONA= -EXPA*ALOG(R)
200  CONTINUE
      IF (TONA .GT. TST) GOTO 40
      ASSIGN 10 TO EVENT
      IF (TONS .LT. TONA) ASSIGN 20 TO EVENT
      IF (TOND .LT. TONS .AND. TOND .LT. TONA) ASSIGN 30 TO EVENT
      GOTO EVENT,(10,20,30)
10   CONTINUE
      CALL ARIVAL(TONA,TONS,CLOCK,TOLQC,IG,TIG,IFS,SQCL,EXPA,N)
      GOTO 200
20   CONTINUE
      CALL SERV(TONS,TOND,CLOCK,TOLQC,IG,IFS,SQCL,SOST,EXPS,N)
      GOTO 200
30   CONTINUE
      CALL DEPART(TOND,TONS,CLOCK,IG,IFS)
      GOTO 200
40   CONTINUE
C.....
C      CALCULATION OF AVERAGE QUEUE LENGTH(AVQL), AVERAGE
C      SERVICE TIME(AVST)
C.....
      AVQL= SQCL/CLOCK
      AVST= SOST/CLOCK
      SSOST= SSOST+AVQL
      SSOST= SSOST+AVST
      WRITE(6,3) AVQL,AVST
100  CONTINUE
C.....
C      CALCULATION OF AVERAGE QUEUE FOR ALL RUN, AVERAGE
C      UTILIZATION FOR ALL RUN AND AVERAGE TIME OF MESSAGE ENTRY FOR
C      ALL RUN
C.....
      AVQL= SSOST/100.
      AVST= SSOST/100.
      WRITE(6,4) AVQL,AVST
      FORMAT(11,7,7,7,30X,'S I M U L A T I O N S T A T I S T I C S')
      FORMAT(11,15X,'AVE QUEUE LENGHT',20X,'AVE UTILIZATION')
      FORMAT(11,17X,F5.4,25X,F5.4)
      FORMAT(11,20X,'AVE QUEUE LENGHT FOR ALL RUNS = ',F5.4,
      *'/100',20X,'AVE UTILIZATION FOR ALL RUNS = ',F5.4)
      STOP
      END

```

```

SUBROUTINE ARRIVAL(TONA,TONS,CLOCK,TOLCC,IQ,TIG,IFS,SOQL,EXPA,N)
  CLOCK=TONA
  SOQL=SOQL-(CLOCK-TOLCC)*IQ
  TOLCC=CLOCK
  TIG=TIG-1.
  IQ=IQ+1
  CALL RAND(N,R)
  TONA=CLOCK+(-EXPA*ALOG(R))
  IF (IFS.NE.C.OF.IQ.GT.1) RETURN
  TONS=CLOCK
RETURN
END

```

```

SUBROUTINE SERV(TONS,TOND,CLOCK,TOLCC,IQ,IFS,SOQL,SOST,EXPS,N)
  CLOCK=TONS
  CALL RAND(N,R)
  SERV=-EXPS*ALOG(R)
  TOND=CLOCK+SERV
  SOST=SOST+SERV
  SOQL=SOQL+(CLOCK-TOLCC)*IQ
  TOLCC=CLOCK
  IQ=IQ-1
  IFS=1
  TONS=9999.
RETURN
END

```

```

SUBROUTINE DEPART(TOND,TONS,CLOCK,IQ,IFS)
  CLOCK=TOND
  IF (IQ.GE.0) TONS=CLOCK
  TOND=9999.
  IFS=0
RETURN
END

```

```

SUBROUTINE RAND(N,R)
  A=315227
  N=N+K
  R=R-N
  P=EN/34359738337.
  R=ABS(R)
RETURN
END

```

SIMSCRIPT II Simulation Example

```

EVENTS INCLUDE ARRIVAL, DEPARTURE AND STOP.SIMULATION
    EVERY MESSAGE MAY BELONG TO THE QUEUE
DEFINE SERVICE.TIME, QUEUE.CHANGE, SUM.QUEUE AS VARIABLE
DEFINE STATUS AS AN INTEGER VARIABLE
DEFINE N.QUEUE TO MEAN
DEFINE BUSY TO MEAN
DEFINE TOTAL.ENTRY AS AN INTEGER VARIABLE
THE SYSTEM OWNS THE QUEUE
TOTAL MAX.QUEUE AS THE MAXIMUM OF N.QUEUE
ACCUMULATE UTILIZATION AS THE AVERAGE OF STATUS
END

MAIN
SCHEDULE A ARRIVAL IN EXPONENTIAL.F(5.0,1) MINUTES
SCHEDULE A STOP.SIMULATION IN 8 HOURS
START SIMULATION
END

EVENT ARRIVAL
SCHEDULE A ARRIVAL IN EXPONENTIAL.F(5.0,1) MINUTES
CREATE A MESSAGE
IF STATUS = BUSY OR N.QUEUE > 1
LET SUM.QUEUE= SUM.QUEUE+(TIME.V+1440.-QUEUE.CHANGE)*N.QUEUE
FILE MESSAGE IN QUEUE
LET TOTAL.ENTRY=TOTAL.ENTRY+1
LET QUEUE.CHANGE= TIME.V+1440.
RETURN
ELSE
LET SERVICE.TIME= EXPONENTIAL.F(4.0,?)
SCHEDULE A DEPARTURE IN SERVICE.TIME MINUTES
NEXT STATUS= BUSY
RETURN
END
```

```

1  EVENT DEPARTURE
2  IF QUEUE IS EMPTY
3  LET STATUS = IDLE
4  RETURN
5  ELSE
6  LET SUM.QUEUE = SUM.QUEUE + (TIME.V - 1440. - QUEUE.CHANGE) * N.QUEUE
7  REMOVE FIRST MESSAGE FROM QUEUE
8  LET QUEUE.CHANGE = TIME.V - 1440.
9  DESTROY MESSAGE
10 LET SERVICE.TIME = EXPONENTIAL.F(4.0, 1)
11 SCHEDULE A DEPARTURE IN SERVICE.TIME MINUTES
12 RETURN
13 END

```

```

1  EVENT STOP-SIMULATION
2  LET AVE.QUEUE.LENGTH = SUM.QUEUE / (TIME.V - 1440.)
3  START NEW PAGE
4  SKIP 5 LINES
5  PRINT 7 LINE WITH AVE.QUEUE.LENGTH, UTILIZATION, MAX.QUEUE
6  AND TOTAL.ENTRY THUS
7  S : * U L A T I O N S T A T I S T I C S
8  AVERAGE QUEUE LENGTH ***
9  UTILIZATION *** MINUTES
10 MAX.QUEUE ***
11 TOTAL.ENTRY *** MESSAGE ENTRY
12 STOP
13 END

```

GASP IV Simulation Example

```

SC 10:44:47 (->0)      RI
17  PAOC
    DIMENSION NSET(1)
    COMMON CSET(5000)
    EQUIVALENCE (NSET(1),CSET(1))
    COMMON/GCOM1/ATEP(25),JEVNT,MFA,MFE(100),MLE(100),MSTOP,NCECF,
    ENNAPC,NNAPT,NNATR,NNFIL,NAL(100),NNTAY,NPRNT,FRARM(50,4),TNCW,
    TTBEQ,TTCLF,TTFIN,TTTIE(25),TTSET
    COMMON /GCOM2/ DC(100),DDL(100),DTFUL,DTNOW,ISEES,LLFLAG(50),NFLAG,
    ENNEGC,NNEGS,NNEGT,SS(100),SSL(100),TTNEY
    COMMON/GCOM3/ AAERR,DTMAX,DTMIN,DTSAV,IITES,LLERR,LLSAV,LLSEV,PRE
    KPR,TTLAS,TTSAV
    COMMON/GCOM4/ DTFLT(10),HMLW(25),HMLD(25),IICRD,ITAF(10),JJCEL
    S(500),LLAPC(25,2),LLAEH(25,2),LLAEP(11,2),LLAET(25,2),LLPHI(10),LL
    EPLO(10),LLPLT,LLSUP(15),LLSYM(10),MMPTS,NNCEL(25),NNCLT,NNHIS,NNFL
    ET,NNPTS(10),NNSTA,NNVAR(10),PPHI(10),PPLO(10)
    COMMON/GCOM5/ IIEVT,IISED(6),JJBEQ,JJCLP,MMNIT,MMON,NNAME(3),NNCF
    S,NNDAY,NNPT,NNSET,NNPRJ,NNPRM,NNPNS,NNRUN,NNSTR,NNYR,SSEED(6)
    COMMON/GCOM6/FEENG(100),IINN(100),KKPNK(100),MMAXG(100),GGTIM(100)
    S,SSDEV(25,5),SSFPV(25,6),VVNQ(100)
END

```

```

C .....
C
C   MAIN PROGRAM
C .....
C   INCLUDE IT
C .....
C   INITIALIZE CARD READER VALUE,NCRDR AND PRINTER VALUE,NPRNT .
C .....
C   NCRDR=5
C   NPRNT=6
C   CALL GASP
C   STOP
C   END

SUBROUTINE EVNTS(IX)
  INCLUDE IT
C .....
C   IF IX IS 20 EVENT ARRIVAL WILL OCCUR.
C   IF IX IS 30 EVENT BEGIN SERVICE WILL OCCUR.
C   IF IX IS 40 EVENT FINISH SERVICE WILL OCCUR.
C .....
C   GO TO (20,30,40),IX
20  CALL ARR
    RETLN
30  CALL BECC
    RETLN
40  CALL FINS
    RETLN
END

```

```

      EXECUTIVE ARR
      INCLUDE IT
.....
      FILE 2 = QUEUE
      ATTRIBUTE 1 = TIME OF ARRIVAL
.....

      ATIME(1)=TNCW
.....
      SCHEDULE NEXT EVENT
.....
      CALL FILEM(2)
.....
      FILE 1 SERVICE FACILITY
      SCHEDULE NEXT ARRIVAL MESSAGE
.....
      X=DRAND(1)
      ATIME(1)=TNCW + ((-5.) *ALOG(X))
.....
      CODE FOR SERVICE ARRIVAL=1
.....
      ATIME(2)=1
      CALL FILEM(1)
.....
      TEST WHETHER THERE IS ANY MESSAGE IN THE QUEUE AND SERVICE FACILITY
      IF FREE
      NNG(2) NUMBER OF MESSAGE ENTRY IN FILE 2
.....
      IF(NNG(2).EQ.1.AND. NNG(3).EQ.0) GO TO 10
      RETURN
.....
      SCHEDULE NEXT EVENT
.....
      10 ATIME(1)=TNCW
.....
      CODE FOR BEGINNING OF SERVICE=2
.....
      ATIME(1)=1
      CALL FILEM(1)
      RETURN
      END

```

```

SUBROUTINE FINS
  INCLUDE 'F'
  .....
  REMOVE MESSAGE FROM QUEUE
  MESSAGE IS RELATIVE ADDRESS OF FIRST MESSAGE ENTRY IN FILE 7
  .....
  CALL REMOVEMESSAGE
  .....
  PUT MESSAGE INTO SERVICE FACILITY
  LEFT AVAILABLE TO TIME OF BEGIN SERVICE
  .....
  ATIME(0)=NOW
  CALL FILEM(7)
  .....
  SCHEDULE FINISH SERVICE
  .....
  RETURN(0)
  ATIME(0)=NOW+(1-4)*ALICE(0)
  .....
  CODE FOR FINISH SERVICE=2
  .....
  ATIME(0)=7
  .....
  SCHEDULE NEXT EVENT
  .....
  CALL FILEM(7)
  RETURN
  END
SUBROUTINE FINS
  INCLUDE 'F'
  .....
  REMOVE MESSAGE FROM SERVICE FACILITY
  MESSAGE IS RELATIVE ADDRESS OF LAST MESSAGE ENTRY IN FILE 7
  FILE 7 IS SERVICE FACILITY
  .....
  CALL REMOVEMESSAGE(7)
  MESSAGE=MESSAGE(0)
  .....
  SCHEDULE BEGIN SERVICE IF THERE IS NO MESSAGE IN THE QUEUE
  MESSAGE IS RELATIVE ADDRESS OF MESSAGE ENTRY IN FILE 7 (QUEUE)
  .....
  MESSAGE(0)=MESSAGE RETURN
  ATIME(0)=NOW
  ATIME(0)=0
  .....
  SCHEDULE NEXT EVENT
  .....
  CALL FILEM(7)
  RETURN
  END

```

GPSS Simulation Example

LOC	NAME	X	Y	Z	SEL	NBA	NBB	MEAN	MOD	REMARKS
1	START									
2	GENERATE									
3	QUEUE									
4	SEIZE									
5	ADVANCE									
6	RELEASE									
7	TERMINATE									
8	END									

 **SIMULATION PROGRAM FOR SINGLE QUEUE SINGLE SERVER TIME OF MESSAGE
 **ARRIVAL EXPONENTIALLY DISTRIBUTED WITH MEAN 5 AND SERVICE TIME IS
 **EXPONENTIALLY DISTRIBUTED WITH MEAN 4

LOC	NAME	X	Y	Z	SEL	NBA	NBB	MEAN	MOD	REMARKS
1	START									
2	GENERATE									
3	QUEUE									
4	SEIZE									
5	ADVANCE									
6	RELEASE									
7	TERMINATE									
8	END									

 **SIMULATION PROGRAM FOR SINGLE QUEUE SINGLE SERVER TIME OF MESSAGE
 **ARRIVAL EXPONENTIALLY DISTRIBUTED WITH MEAN 5 AND SERVICE TIME IS
 **EXPONENTIALLY DISTRIBUTED WITH MEAN 4

Plotting Routines

```

      DIMENSION QUE(102), USED(102), FREE(102), TIME(102)
      N=100
      XMAX=-1.E+35
      DO 10 I=1,100
      I1=I-1
      TIME(I)=1.0+.1*I1
      XMAX=AMAX1(XMAX,TIME(I))
10    CONTINUE
      DO 20 I=1,100
      READ(5,25) QUE(I),USED(I),FREE(I)
25    FORMAT(1X,3E8.4)
      CONTINUE
      CALL PFRD(TIME,FREE,N,XMAX)
      DO 40 I=1,100
      WRITE(6,40) I,TIME(I),QUE(I),USED(I),FREE(I)
40    FORMAT(2X,I3,4(5X,E8.4))
      CONTINUE
      STOP
      END

```

```

      SUBROUTINE PFRD (XX,YY,N,XMAX)
      DIMENSION XX(102),YY(102)
      XCRG=1.0
      YCRG=1.75
      XSZ=11.0
      YSZ=6.5
      CALL PLOTS(XSZ,YSZ,0,1)
      CALL LINEWT(-1)
      CALL PLOT(1.,1.,-3)
      CALL PLOT(XSZ,0.0, )
      CALL PLOT(0.0,YSZ,2)
      CALL PLOT(0.0,0.0,2)
      CALL PLOT(XCRG,YCRG,-3)
      XCOR=XCRG
      YCOR=YCRG
      K=1
      CALL SCALE (XX(K),XCOR,N,1)
      CALL SCALE (YY(K),YCOR,N,1)
      N1=N+1
      N2=N+2
      XX(N2)=XMAX/XCOR
      CALL AXIS(0.0,0.0,5HFREE ,+5,YCOR,90.,YY(N1),YY(N2))
      CALL AXIS(0.0,0.0,4HTIME,-4,XCOR,0.0,XX(N1),XX(N2))
      CALL LINEWT(0)
      CALL LINE(XX(K),YY(K),N,1,0,12,.075)
      CALL PLOT(0.0,0.0,909)
      RETURN
      END

```

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